Games with payoff

Wiesław Zielonka

LIAFA, Université Paris 7 Denis Diderot and CNRS

Games

```
Players: 1 and 2.
```

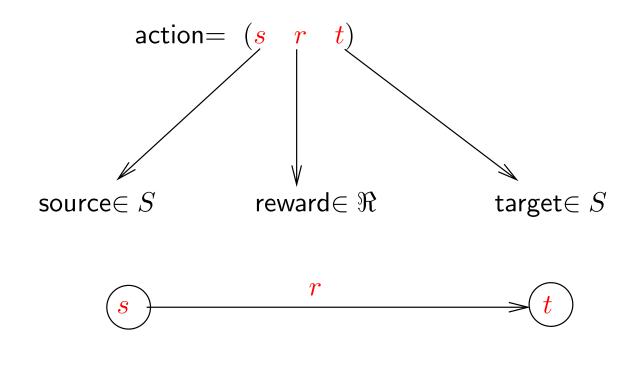
```
Arenas:

S_1, S_2 — states controlled by players 1 and 2,

A – actions,

\Re – rewards.
```

 $S = S_1 \cup S_2 - \text{all states,} \\ A \subset S \times \Re \times S.$



$$A(s) = \{a \in A \mid \text{source}(a) = s\}$$

actions *available* at $s \in S$.

Arena

$$\mathcal{A} = (S_1, S_2, A)$$

 $S, A(s), \forall s \in S - finite, nonempty.$

A history $h = a_1 a_2 \ldots \in A^{\infty}$,

$$\forall i, \text{target}(a_i) = \text{source}(a_{i+1}).$$

A *play* $p = a_1 a_2 \dots$ — an infinite sequence of actions executed by the players (play=infinite history).

Preference relation

For a play $p = a_1 a_2 \dots$

 $\operatorname{reward}(p) = \operatorname{reward}(a_1) \operatorname{reward}(a_2) \ldots \in \Re^{\omega}$

an infinite finitely generated sequence of rewards.

A preference relation \sqsubseteq complete, transitive and reflexive relation over \Re^{ω} , $r, r' \in \Re^{\omega}$,

$$r \sqsubseteq r'$$

means that for player p the sequence r' is at least as valuable as the sequence r.

Payoff mapping

Payoff mapping

$$u: \mathfrak{R}^{\omega} \longrightarrow \mathbb{R} \cup \{-\infty, \infty\}$$

induces a preference relation \sqsubseteq_u :

$$r \sqsubseteq_u r'$$
 iff $u(r) \le u(r')$.

Game

Game : arena \mathcal{A} and preference relations $\sqsubseteq_1, \sqsubseteq_2$ of each player.

An antagonistic game: (zero-sum game) $\sqsubseteq_2 = (\sqsubseteq_1)^{-1}$.

$$\mathbf{G} = (\mathcal{A}, \sqsubseteq) \ ,$$

 \mathcal{A} — an arena,

 \sqsubseteq — a preference relation for player 1.

Examples

Parity games

 $\Re = \mathbb{N}$, rewards = priorities.

For $n = n_1 n_2 \ldots \in \mathbb{N}^{\omega}$ let

 $priority(n) = \limsup_{i \to \infty} n_i$

maximal priority occurring infinitely often in n.

 $m,n\in\mathbb{N}^{\omega}$,

 $n \sqsubseteq m$ if priority $(n) \mod 2 \le \operatorname{priority}(m) \mod 2$

Mean-payoff games

 $\Re = \mathbb{R}$, for $r = r_1 r_2 \ldots \in \mathbb{R}^{\omega}$,

$$\overline{\mathrm{mean}}(r) = \limsup_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} r_i .$$

Exercise

In this exercise we assume that in mean-payoff games both players have optimal positional strategies. (We shall prove it later.)

Show that parity games can be reduced to mean-payoff games.

In other words, suppose that you have an algorithm solving mean-payoff games, i.e calculating the value of the mean-payoff game for each initial state and optimal positional strategies for both players. Then show how such an algorithm can be used to solve parity games.

Is your reduction parity mean-payoff polynomial?

Discounted games

$$\Re = \mathbb{R}$$
, for $r = r_0 r_1 \ldots \in \mathbb{R}^{\omega}$,

$$\operatorname{disc}_{\beta}(r) = (1 - \beta) \sum_{i=0}^{\infty} \beta^{i} r_{i} ,$$

 $\beta \in (0,1)$ is a discount factor.

Strategies

A *strategy* for player 1

 $\sigma: \{h \mid h \text{ a finite history with } \operatorname{target}(h) \in S_1\} \longrightarrow A$

where $\sigma(h) \in A(\operatorname{target}(h))$.

 $\forall s \in S, \lambda_s \text{ empty history source}(\lambda_s) = \text{target}(\lambda_s) = s.$

Histories consistent with a strategy

A history $h = a_1 a_2 \dots$ is *consistent* with a strategy σ of player 1 if for each i < |h|, if $h_i < h$ is the prefix of h of length i such that $target(h_i) \in S_1$ then

$$a_{i+1} = \sigma(h_i) \quad .$$

Notation:

 σ and τ — strategies for players 1 and 2 respectively.

$p_{\mathcal{A}}(s,\sigma,\tau)$

unique play consistent with σ and τ with source s.

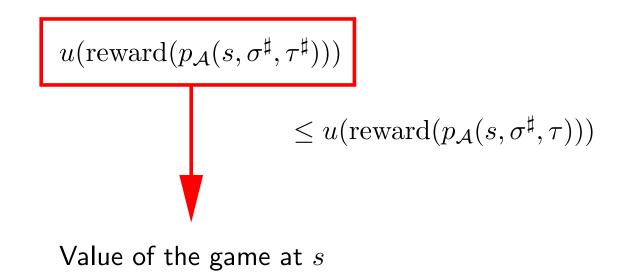
Optimal strategies

 $\sigma^{\sharp} \in \text{Strategy}_1, \ \tau^{\sharp} \in \text{Strategy}_2 \text{ are optimal if}$ $\forall s \in S, \ \forall \sigma \in \text{Strategy}_1, \ \tau \in \text{Strategy}_2,$

reward $(p_{\mathcal{A}}(s,\sigma,\tau^{\sharp})) \sqsubseteq \operatorname{reward}(p_{\mathcal{A}}(s,\sigma^{\sharp},\tau^{\sharp})) \sqsubseteq \operatorname{reward}(p_{\mathcal{A}}(s,\sigma^{\sharp},\tau))$.

 $\forall s \in S, \forall \sigma \in \text{Strategy}_1, \tau \in \text{Strategy}_2,$

```
u(\operatorname{reward}(p_{\mathcal{A}}(s,\sigma,\tau^{\sharp}))) \leq
```



General value definition

lower value =
$$\underline{\operatorname{val}}(s)$$
 =

$$\sup_{\sigma} \inf_{\tau} u(\operatorname{reward}(p_{\mathcal{A}}(s, \sigma^{\sharp}, \tau^{\sharp}))) \leq \inf_{\tau} \sup_{\sigma} u(\operatorname{reward}(p_{\mathcal{A}}(s, \sigma^{\sharp}, \tau^{\sharp})))$$

$$= \overline{\operatorname{val}}(s) = \operatorname{upper value}(s)$$

 $\quad \text{and} \quad$

$$value(s) := \underline{val}(s) = \overline{val}(s)$$
.

A *positional* or *memoryless* strategy for player 1

$$\sigma: S_1 \to A$$

where $\sigma(s) \in A(s)$, $\forall s \in S_1$.

Basic questions of game theory

- Does there exist a value for a given game G?
- The existence of optimal strategies for both players.
- The existence of "simple" optimal strategies.

Have the players optimal positional strategies?

More examples

Simple Priority Games

 $\alpha:\mathbb{N}\to\mathbb{R},$ a priority valuation.

Let $n = n_1 n_2 \ldots \in \mathbb{N}^{\omega}$. Then the payoff of *simple priority games*:

 $u_{\alpha}(n) = \alpha(\operatorname{priority}(n)),$

Exercise

Suppose that an arena \mathcal{A} is colored with k different priorities. Show that the simple priority game on \mathcal{A} can be solved by solving several (at most k-1) parity games and that both players have optimal positional strategies in simple priority games.

(This reduction will be valid also for infinite arenas.)

Mean-payoff Priority Games.

 $\Re = \mathbb{N} \times \mathbb{R}$, $(n, r) \in \Re$, n — priority, r — reward.

 $x = (n_1, r_1), (n_2, r_2), \ldots \in \Re^{\omega}$ $n = \text{priority}(n_1 n_2 \ldots) \text{ priority of } x,$

$$x(n) = (n_{i_1}, r_{i_1}), (n_{i_2}, r_{i_2}), \dots$$

where $n = n_{i_1} = n_{i_2} = \cdots$.

$$\overline{\mathrm{mean}}(x) = \limsup_{k \to \infty} \frac{r_{i_1} + \dots + r_{i_k}}{k} .$$

Gambling Games.

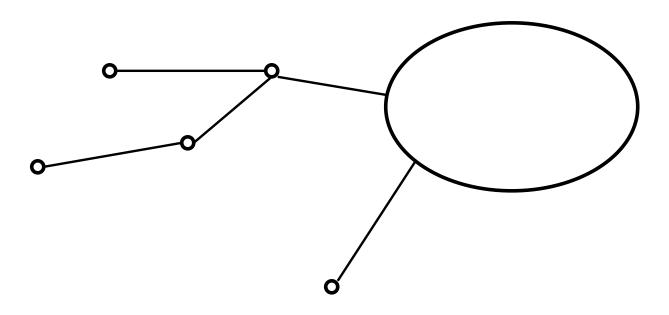
 $\Re = \mathbb{R}, r_1 r_2 \dots$

$$g_{\lambda}(r_1r_2\ldots) = (1-\lambda)\liminf_{i\to\infty} r_i + \lambda \limsup_{i\to\infty} r_i$$
.

Exercise

Show that parity games can be reduced to gabling gambling games with $\lambda=\frac{1}{2}.$

For all previous examples if all states are controlled by one player then this player has an optimal positional strategy.



Suppose that player 1 (maximizer) controls all states. For all games (except discounted) his optimal strategy for one-player game is the following:

• find the simple cycle in the arena ${\cal A}$ with the maximal payoff,

• go to this cycle and next go forever along this cycle.

Exercise

Show that the strategy described above is really optimal for one-player mean-payoff games.

Show the same for mean-payoff priority games and for gambling games.

From One-Player Games to Two-Player Games.

 $\mathcal{A} = (S_1, S_2, A)$ is controlled by player *i* if $\forall s \in S_j$, $j \neq i$, |A(s)| = 1.

Theorem. *Fix*

- \Re a set of rewards,
- \sqsubseteq a preference relation over \Re^{ω} .

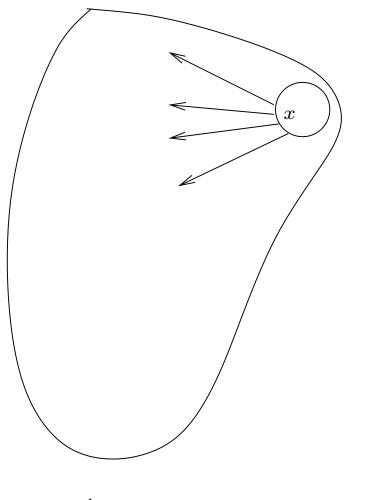
Suppose that for each finite one-player arena \mathcal{A} the player controlling \mathcal{A} has an optimal positional strategy in the game $(\mathcal{A}, \sqsubseteq)$. Then for all twoperson games $(\mathcal{A}, \sqsubseteq)$ on finite arenas \mathcal{A} both players have optimal positional strategies. **Proof** |A| - |S| the *rank* of A.

Proof: induction over the rank value.

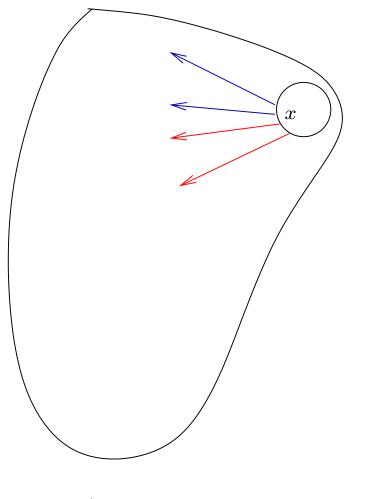
The pivot — a fixed state $x \in S_1$ such that |A(x)| > 1.

$$A(x) = A_L(x) \cup A_R(x)$$

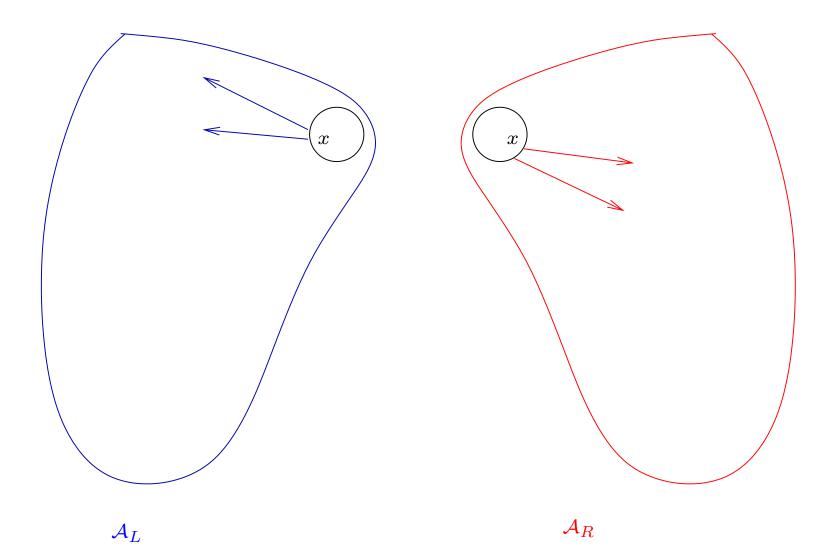
a non-trivial partition of A(x) onto Left (bLue) actions and Right (Red) actions.

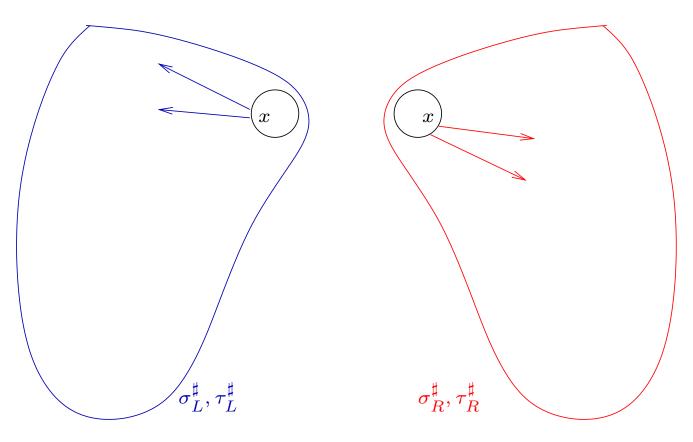


 \mathcal{A}



 \mathcal{A}

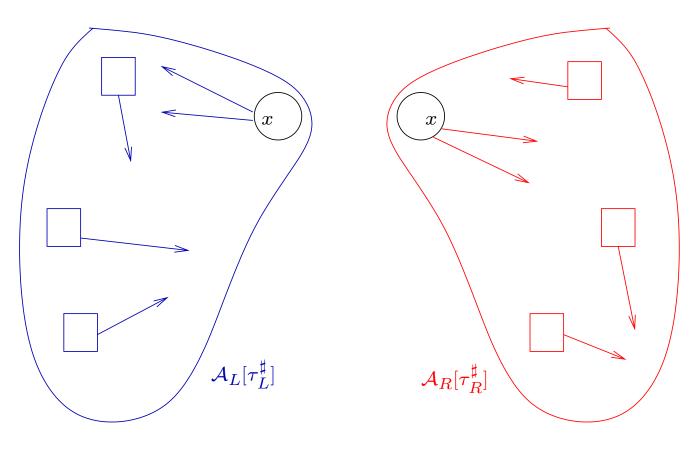




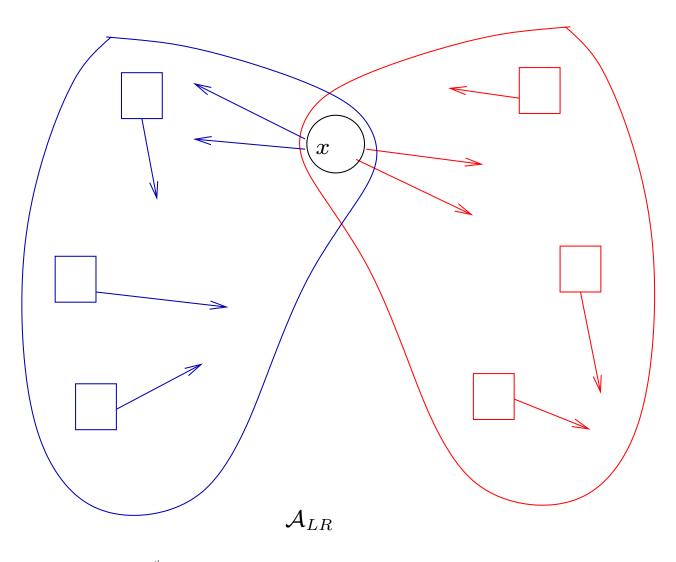
By induction there exist optimal positional strategies on \mathcal{A}_L and \mathcal{A}_R

We show that one of the strategies σ_L^{\sharp} , σ_R^{\sharp} is optimal for player 1 in the initial game on \mathcal{A} .

Usually neither τ_L^{\sharp} nor τ_R^{\sharp} is optimal on \mathcal{A} but we show how to construct an optimal strategy for player 2 on \mathcal{A} using these two strategies. The strategy for player 2 that we will construct will use one bit of memory to choose between τ_L^{\sharp} nor τ_R^{\sharp} depending on the last movement of player 1 at the pivot state.



Restrict the movements of player 2 by allowing only actions imposed by strategies τ_L^\sharp and τ_R^\sharp



 σ^{\sharp}_{LR} optimal positional strategy of player 1 on \mathcal{A}_{LR}

Optimal strategy of player 1 in ${\cal A}$

$$\sigma^{\sharp} = \begin{cases} \sigma_{L}^{\sharp} & \text{if } \sigma_{LR}^{\sharp}(x) \text{ is a blue action} \\ \\ \\ \sigma_{R}^{\sharp} & \text{if } \sigma_{LR}^{\sharp}(x) \text{ is a red action} \end{cases}$$

Our choice of the optimal strategy of player 1 in ${\cal A}$

We assume that:

$$\sigma_{LR}^{\sharp}(x) \in A_L(x)$$

 $\sigma^{\sharp} := \sigma_L^{\sharp} .$

 $\quad \text{and} \quad$

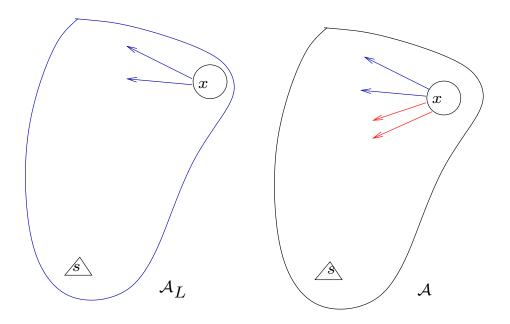
Optimal strategy for player 2 **on** \mathcal{A}

h be a finite history in \mathcal{A} with $target(h) \in S_2$.

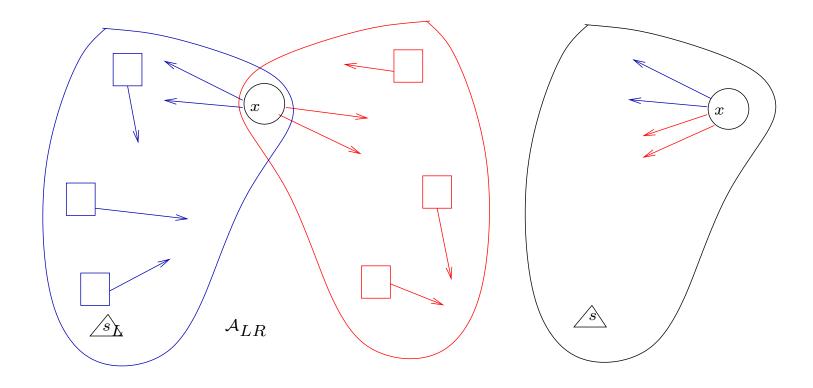
 $\tau^{\sharp}(h) = \begin{cases} \tau_{L}^{\sharp}(\operatorname{target}(h)) & \text{if either } h \text{ does not contain any action with source } x \\ & \text{or the last such action belongs to } A_{L}(x), \\ \tau_{R}^{\sharp}(\operatorname{target}(h)) & \text{if } h \text{ contains at least one action with source } x \\ & \text{and the last such action belongs to } A_{R}(x). \end{cases}$

We should prove

reward $(p_{\mathcal{A}}(s,\sigma,\tau^{\sharp})) \sqsubseteq \operatorname{reward}(p_{\mathcal{A}}(s,\sigma^{\sharp},\tau^{\sharp})) \sqsubseteq \operatorname{reward}(p_{\mathcal{A}}(s,\sigma^{\sharp},\tau))$.



$$p_{\mathcal{A}}(s,\sigma^{\sharp},\tau^{\sharp}) = p_{\mathcal{A}}(s,\sigma_{L}^{\sharp},\tau_{L}^{\sharp}) = p_{\mathcal{A}_{L}}(s,\sigma_{L}^{\sharp},\tau_{L}^{\sharp}) \sqsubseteq p_{\mathcal{A}_{L}}(s,\sigma_{L}^{\sharp},\tau) = p_{\mathcal{A}}(s,\sigma_{L}^{\sharp},\tau) = p_{\mathcal{A}}(s,\sigma_{L}^{\sharp},\tau) = p_{\mathcal{A}}(s,\sigma_{L}^{\sharp},\tau)$$



$$p_{\mathcal{A}}(s,\sigma,\tau^{\sharp}) = p_{\mathcal{A}_{LR}}(s_L,\sigma,\cdot) \sqsubseteq p_{\mathcal{A}_{LR}}(s_L,\sigma_{LR}^{\sharp},\cdot) = p_{\mathcal{A}_L}(s,\sigma_{LR}^{\sharp},\tau_L^{\sharp}) \sqsubseteq p_{\mathcal{A}_L}(s,\sigma_L^{\sharp},\tau_L^{\sharp}) = p_{\mathcal{A}}(s,\sigma^{\sharp},\tau^{\sharp})$$

Exchangeability property for optimal strategies

 $(\sigma^{\sharp},\tau^{\sharp})$ and $(\sigma^{\ddagger},\,\tau^{\ddagger})$ pairs of optimal strategies.

Then $(\sigma^{\ddagger}, \tau^{\ddagger})$ and $(\sigma^{\ddagger}, \tau^{\ddagger})$ are also optimal.

Moreover,

reward $(p_{\mathcal{A}}(s,\sigma^{\ddagger},\tau^{\ddagger})) \sqsubseteq \operatorname{reward}(p_{\mathcal{A}}(s,\sigma^{\ddagger},\tau^{\ddagger})) \sqsubseteq \operatorname{reward}(p_{\mathcal{A}}(s,\sigma^{\ddagger},\tau^{\ddagger}))$.