

Constraint Logic Programming

Sylvain Soliman, François Fages and Nicolas Beldiceanu
{Sylvain.Soliman,Francois.Fages}@inria.fr

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- Transitions
- Properties
- Observables
- $CC(\mathcal{FD})$

CC(\mathcal{X}) Transitions

Interleaving semantics

$$\text{Procedure call} \quad \frac{(p(\vec{y}) = A) \in \mathcal{D}}{(\vec{x}; c; p(\vec{y}), \Gamma) \longrightarrow (\vec{x}; c; A, \Gamma)}$$

$$\text{Tell} \quad (\vec{x}; c; \text{tell}(d), \Gamma) \longrightarrow (\vec{x}; c \wedge d; \Gamma)$$

$$\text{Ask} \quad \frac{c \vdash_{\mathcal{X}} d[\vec{t}/\vec{y}]}{(\vec{x}; c; \forall \vec{y}(d \rightarrow A), \Gamma) \longrightarrow (\vec{x}; c; A[\vec{t}/\vec{y}], \Gamma)}$$

$$\text{Blind choice} \quad (\vec{x}; c; A + B, \Gamma) \longrightarrow (\vec{x}; c; A, \Gamma)$$

$$\text{(local/internal)} \quad (\vec{x}; c; A + B, \Gamma) \longrightarrow (\vec{x}; c; B, \Gamma)$$

Properties of CC Transitions (1)

Theorem (Monotonicity)

If $(\vec{x}; c; \Gamma) \rightarrow (\vec{y}; d; \Delta)$ then $(\vec{x}; c \wedge e; \Gamma, \Sigma) \rightarrow (\vec{y}; d \wedge e; \Delta, \Sigma)$ for every constraint e and agents Δ .

Proof.

tell and ask are monotonic (monotonic conditions in guards). \square

Corollary

Strong fairness and weak fairness are equivalent.

Properties of CC Transitions (3)

Theorem (Extensivity)

If $(\vec{x}; c; \Gamma) \rightarrow (\vec{y}; d; \Delta)$ then $\exists \vec{y}d \vdash_{\mathcal{X}} \exists \vec{x}c$.

Proof.

For any constraint e , $c \wedge e \vdash_{\mathcal{X}} c$.

Theorem (Restartability)

If $(\vec{x}; c; \Gamma) \rightarrow^ (\vec{y}; d; \Delta)$ then $(\vec{x}; \exists \vec{y}d; \Gamma) \rightarrow^* (\vec{y}; d; \Delta)$.*

Proof.

By extensivity and monotonicity.

CC(\mathcal{X}) Operational Semantics

- observing the set of **success stores**,

$$\mathcal{O}_{ss}(\mathcal{D}.A; c) = \{\exists \vec{x}d \in \mathcal{X} \mid (\emptyset; c; A) \longrightarrow^* (\vec{x}; d; \epsilon)\}$$

- observing the set of **terminal stores** (successes and suspensions),

$$\mathcal{O}_{ts}(\mathcal{D}.A; c) = \{\exists \vec{x}d \in \mathcal{X} \mid (\emptyset; c; A) \longrightarrow^* (\vec{x}; d; \Gamma) \not\mapsto\}$$

- observing the set of **accessible stores**,

$$\mathcal{O}_{as}(\mathcal{D}.A; c) = \{\exists \vec{x}d \in \mathcal{X} \mid (\emptyset; c; A) \longrightarrow^* (\vec{x}; d; B)\}$$

- observing the set of **limit stores**?

$$\mathcal{O}_{\infty}(\mathcal{D}.A; c_0) = \{\sqcup? \{\exists \vec{x}_i c_i\}_{i \geq 0} \mid (\emptyset; c_0; A) \longrightarrow (\vec{x}_1; c_1; \Gamma_1) \longrightarrow \dots\}$$

Part VI

CC - Denotational Semantics

Part VI: CC - Denotational Semantics

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Deterministic CC

Agents:

$$A ::= \text{tell}(c) \mid c \rightarrow A \mid A \parallel A \mid \exists xA \mid p(\vec{x})$$

- No choice operator
- Deterministic ask.

Replace non-deterministic pattern matching

$$\forall \vec{x}(c \rightarrow A)$$

by deterministic ask and tell:

$$(\exists \vec{x}c) \rightarrow \exists \vec{x}(\text{tell}(c) \parallel A)$$

Denotational semantics: input/output function

Input: **initial store** c_0

Output: **terminal store** c or *false* for infinite computations

Order the lattice of constraints (\mathcal{C}, \leq) by the information ordering:

$\forall c, d \in \mathcal{C} \ c \leq d$ iff $d \vdash_{\mathcal{X}} c$ iff $\uparrow d \subseteq \uparrow c$ where

$\uparrow c = \{d \in \mathcal{C} \mid c \leq d\}$.

$\llbracket \mathcal{D}.A \rrbracket : \mathcal{C} \rightarrow \mathcal{C}$ is

- ① Extensive: $\forall c \ c \leq \llbracket \mathcal{D}.A \rrbracket c$
- ② Monotone: $\forall c, d \ c \leq d \Rightarrow \llbracket \mathcal{D}.A \rrbracket c \leq \llbracket \mathcal{D}.A \rrbracket d$
- ③ Idempotent: $\forall c \ \llbracket \mathcal{D}.A \rrbracket c = \llbracket \mathcal{D}.A \rrbracket (\llbracket \mathcal{D}.A \rrbracket c)$

i.e. $\llbracket \mathcal{D}.A \rrbracket$ is a over (\mathcal{C}, \leq) .

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i.e. $\llbracket \mathcal{D}.A \rrbracket$ is a **closure operator** over (\mathcal{C}, \leq) .

Closure Operators

Proposition

A closure operator f is characterized by the set of its fixpoints $Fix(f)$.

Proof.

We show that $f = \lambda x. \min(Fix(f) \cap \uparrow x)$.

Let $y = f(x)$. By idempotence and extensivity, $y \in Fix(f) \cap \uparrow x$.

By monotonicity $y = f(x) \leq f(y')$ for any $y' \in \uparrow x$.

Hence, if $y' \in Fix(f) \cap \uparrow x$ then $y \leq y'$. □

Semantic Equations

Let $\llbracket \cdot \rrbracket : \mathcal{D} \times A \rightarrow \mathcal{P}(\mathcal{C})$ be a **closure operator** presented by the set of its fixpoints, and defined as **the least fixpoint set** of the equations:

$$\llbracket \mathcal{D}.tell(c) \rrbracket = \uparrow c \quad (\simeq \lambda s.s \wedge c)$$

$$\llbracket \mathcal{D}.c \rightarrow A \rrbracket = (\mathcal{C} \setminus \uparrow c) \cup (\uparrow c \cap \llbracket \mathcal{D}.A \rrbracket)$$

$(\simeq \lambda s. \text{if } s \vdash_{\mathcal{C}} c \text{ then } \llbracket \mathcal{D}.A \rrbracket s \text{ else } s)$

$$\llbracket \mathcal{D}.A \parallel B \rrbracket = \llbracket \mathcal{D}.A \rrbracket \cap \llbracket \mathcal{D}.B \rrbracket \quad (\simeq \bigvee (\lambda s. \llbracket \mathcal{D}.A \rrbracket \llbracket \mathcal{D}.B \rrbracket s))$$

$$\llbracket \mathcal{D}.\exists x A \rrbracket = \{d \mid c \in \llbracket \mathcal{D}.A \rrbracket, \exists xc = \exists xd\} \quad (\simeq \lambda s. \exists x [\llbracket \mathcal{D}.A \rrbracket \exists xs])$$

$$\llbracket \mathcal{D}.p(\vec{x}) \rrbracket = \llbracket \mathcal{D}.A[\vec{x}/\vec{y}] \rrbracket \text{ if } p(\vec{y}) = A \in \mathcal{D} \quad (\simeq \lambda s. \llbracket \mathcal{D}.A[\vec{x}/\vec{y}] \rrbracket s)$$

Theorem ([SRP91])

For any deterministic process $\mathcal{D}.A$

$$O_{ts}(\mathcal{D}.A; c) = \begin{cases} \{\min(\llbracket \mathcal{D}.A \rrbracket \cap \uparrow c)\} & \text{if } \llbracket \mathcal{D}.A \rrbracket \neq \emptyset \\ \emptyset & \text{otherwise} \end{cases}$$

Constraint Propagation and Closure Operators

An **environment** $E : \mathcal{V} \rightarrow 2^D$ associates a domain of possible values to each variable.

Consider the lattice of environments $(\mathcal{E}, \sqsubseteq)$, for the **information ordering** defined by $E \sqsubseteq E'$ if and only if $\forall x \in \mathcal{V}, E(x) \supseteq E'(x)$.

The semantics of a constraint propagator c can be defined as a closure operator over \mathcal{E} , noted \bar{c} , i.e. a mapping $\mathcal{E} \rightarrow \mathcal{E}$ satisfying

- 1 (extensivity) $E \sqsubseteq \bar{c}(E)$,
- 2 (monotonicity) if $E \sqsubseteq E'$ then $\bar{c}(E) \sqsubseteq \bar{c}(E')$
- 3 (idempotence) $\bar{c}(\bar{c}(E)) = \bar{c}(E)$.

Example in $CC(\mathcal{FD})$

Let $b = (x > y)$ and $c = (y > x)$.

Let $E(x) = [1, 10]$, $E(y) = [1, 10]$ be the initial environment
 we have

$$\begin{aligned}\bar{b}E(x) &= [2, 10] \\ \bar{c}E(x) &= [1, 9] \\ (\bar{b} \sqcup \bar{c})E(x) &= [2, 9]\end{aligned}$$

The closure operator $\overline{b, c}$ associated to the conjunction of
 constraints $b \wedge c$ gives the intended semantics:

$$\overline{b, c}E(x) = Y(\lambda s. \bar{b}(\bar{c}(s)))E(x) = \emptyset$$

Chaotic Iteration of Monotone Operators

Let $L(\sqsubseteq, \perp, \top, \sqcup, \sqcap)$ be a complete lattice, and $F : L^n \rightarrow L^n$ a monotone operator over L^n with $n > 0$.

The **chaotic iteration** of F from $D \in L^n$ for a fair transfinite choice sequence $\langle J^\delta : \delta \in Ord \rangle$ is the sequence $\langle X^\delta \rangle$:

$$X^0 = D,$$

$$X_i^{\delta+1} = F_i(X^\delta) \text{ if } i \in J^\delta, X_i^{\delta+1} = X_i^\delta \text{ otherwise,}$$

$$X_i^\delta = \bigsqcup_{\alpha < \delta} X_i^\alpha \text{ for any limit ordinal } \delta.$$

Theorem ([CC77])

Let $D \in L^n$ be a pre fixpoint of F (i.e. $D \sqsubseteq F(D)$). Any chaotic iteration of F starting from D is increasing and has for limit the least fixpoint of F above D .

Constraint Propagation as Chaotic Iteration

Corollary (Correctness of constraint propagation)

Let $c = a_1 \wedge \dots \wedge a_n$, and E be an environment. Then $\bar{c}(E)$ is the limit of any fair iteration of closure operators $\bar{a}_1, \dots, \bar{a}_n$ from E .

Let $F : L^{n+1} \rightarrow L^{n+1}$ be defined by its projections F_i 's:

$$\left\{ \begin{array}{l} E_1 = \bar{a}_1(E) = F_1(E_1, \dots, E_n, E) \\ E_2 = \bar{a}_2(E) = F_2(E_1, \dots, E_n, E) \\ \dots \\ E_n = \bar{a}_n(E) = F_n(E_1, \dots, E_n, E) \\ E = E_1 \cap \dots \cap E_n = F_{n+1}(E_1, \dots, E_n, E) \end{array} \right.$$

The functions F_i 's are obviously monotonic, any fair iteration of $\bar{a}_1, \dots, \bar{a}_n$ is thus a chaotic iteration of F_1, \dots, F_{n+1} therefore its limit is equal to the least fixpoint greater than E , i.e. $\bar{c}(E)$.

Denotational Semantics of Non-deterministic CC

Problem: the set of terminal stores of a CC process with **one step guarded choice** (i.e. *global choice*) is **not compositional**:

$$\begin{aligned}
 A &= \text{ask}(x = a) \rightarrow \text{tell}(y = a) \\
 &\quad + \text{ask}(\text{true}) \rightarrow \text{tell}(\text{false}) \\
 B &= \text{tell}(x = a \wedge y = a)
 \end{aligned}$$

A and B have the same set of terminal stores

but that is not the case for $\exists x B$ and $\exists x A$

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$y = a$ is a terminal store for $\exists x B$ and not for $\exists x A \dots$

Non-deterministic $CC(\mathcal{X})$ with Local Choice (1)

The set of terminal stores of a CC process with **blind choice** can be characterized easily by adding the semantic equation:

$$\llbracket \mathcal{D}.A + B \rrbracket = \llbracket \mathcal{D}.A \rrbracket \cup \llbracket \mathcal{D}.B \rrbracket$$

Theorem ([dBGP96])

$$\llbracket \mathcal{D}.A \rrbracket = \bigcup_{c \in \mathcal{C}} \mathcal{O}_{ts}(\mathcal{D}.A; c)$$

but the input-output relation cannot be recovered from $\llbracket \mathcal{D}.A \rrbracket$:

$$\begin{aligned} \llbracket \text{tell}(true) \rrbracket &= \\ \llbracket \text{tell}(true) + \text{tell}(c) \rrbracket &= \\ \mathcal{O}_{ts}(\text{tell}(true); true) &= \\ \mathcal{O}_{ts}(\text{tell}(true) + \text{tell}(c); true) &= \end{aligned}$$

Idea:

Non-deterministic $CC(\mathcal{X})$ with Local Choice (1)

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$$\llbracket \text{tell}(true) \rrbracket = \mathcal{C}$$

$$\llbracket \text{tell}(true) + \text{tell}(c) \rrbracket =$$

$$\mathcal{O}_{ts}(\text{tell}(true); true) =$$

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$$\llbracket \text{tell}(\text{true}) \rrbracket = \mathcal{C}$$

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$$\mathcal{O}_{ts}(\text{tell}(\text{true}); \text{true}) =$$

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$$\llbracket \text{tell}(\text{true}) + \text{tell}(c) \rrbracket = \mathcal{C}$$

$$\mathcal{O}_{ts}(\text{tell}(\text{true}); \text{true}) = \{\text{true}\}$$

$$\mathcal{O}_{ts}(\text{tell}(\text{true}) + \text{tell}(c); \text{true}) =$$

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$$\mathcal{O}_{ts}(\text{tell}(true); true) = \{true\}$$

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Idea:

Non-deterministic $CC(\mathcal{X})$ with Local Choice (1)

The set of terminal stores of a CC process with **blind choice** can be characterized easily by adding the semantic equation:

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Theorem ([dBGP96])

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$$\llbracket \text{tell}(true) + \text{tell}(c) \rrbracket = \mathcal{C}$$

$$\mathcal{O}_{ts}(\text{tell}(true); true) = \{true\}$$

$$\mathcal{O}_{ts}(\text{tell}(true) + \text{tell}(c); true) = \{true, c\}$$

Idea: define $\llbracket \cdot \rrbracket : \mathcal{D} \times A \rightarrow \mathcal{P}(\mathcal{P}(\mathcal{C}))$ to distinguish between branches.

Non-deterministic $CC(\mathcal{X})$ with Local Choice (2)

Let $\llbracket \cdot \rrbracket : \mathcal{D} \times A \rightarrow \mathcal{P}(\mathcal{P}(\mathcal{C}))$ be the least fixpoint (for \subseteq) of

$$\begin{aligned} \llbracket \mathcal{D}.c \rrbracket &= \{\uparrow c\} \\ \llbracket \mathcal{D}.c \rightarrow A \rrbracket &= \{\mathcal{C} \setminus \uparrow c\} \cup \{\uparrow c \cap X \mid X \in \llbracket \mathcal{D}.A \rrbracket\} \\ \llbracket \mathcal{D}.A \parallel B \rrbracket &= \{X \cap Y \mid X \in \llbracket \mathcal{D}.A \rrbracket, Y \in \llbracket \mathcal{D}.B \rrbracket\} \\ \llbracket \mathcal{D}.A + B \rrbracket &= \llbracket \mathcal{D}.A \rrbracket \cup \llbracket \mathcal{D}.B \rrbracket \\ \llbracket \mathcal{D}.\exists x A \rrbracket &= \{\{d \mid \exists xc = \exists xd, c \in X\} \mid X \in \llbracket \mathcal{D}.A \rrbracket\} \\ \llbracket \mathcal{D}.p(\vec{x}) \rrbracket &= \llbracket \mathcal{D}.A[\vec{x}/\vec{y}] \rrbracket \end{aligned}$$

Theorem ([MFP97])

For any process $\mathcal{D}.A$,

$$\mathcal{O}_{ts}(\mathcal{D}.A; c) = \{d \mid \text{there exists } X \in \llbracket \mathcal{D}.A \rrbracket \text{ s.t. } d = \min(\uparrow c \cap X)\}.$$

'merge' Example Revisited

Merging streams

$$\begin{aligned}
 \text{merge}(A, B, C) = & \\
 & (A = [] \rightarrow \text{tell}(C = B)) \parallel \\
 & (B = [] \rightarrow \text{tell}(C = A)) \parallel \\
 & (\forall X, L(A = [X|L] \rightarrow \text{tell}(C = [X|R]) \parallel \text{merge}(L, B, R)) + \\
 & \forall X, L(B = [X|L] \rightarrow \text{tell}(C = [X|R]) \parallel \text{merge}(A, L, R)))
 \end{aligned}$$

Do we have the expected terminal stores?

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 & \forall X, L(B = [X|L] \rightarrow \text{tell}(C = [X|R]) \parallel \text{merge}(A, L, R)))
 \end{aligned}$$

Do we have the expected terminal stores?

No!

for $\text{merge}(X, [1|Y], Z)$ we don't get 1 in Z , the merging is not greedy...

Sequentiality

Let us define a new operator, \bullet , as follows:

$$\frac{(X; c; A) \longrightarrow (Y; d; B)}{(X; c; A \bullet C, \Gamma) \longrightarrow (Y; d; B \bullet C, \Gamma)} \quad (X; c; \emptyset \bullet A) \longrightarrow (X; c; A)$$

We can characterize completely the observables of any CC_{seq} program, $\mathcal{D}.A$, by those of a new CC (without \bullet) program, $\mathcal{D}^\bullet.A^\bullet$, in a new constraint system, \mathcal{C}^\bullet .

Proof

Let ok be a **new** relation symbol of arity one. \mathcal{C}^\bullet is the constraint system \mathcal{C} to which ok is added, without any non-logical axiom. The program $\mathcal{D}^\bullet.A^\bullet$ is defined inductively as follows:

$$(p(\vec{y}) = A)^\bullet = p^\bullet(x, \vec{y}) = A_x^\bullet$$

$$A^\bullet = \exists x A_x^\bullet$$

$$tell(c)_x^\bullet = tell(c \wedge ok(x))$$

$$p(\vec{y})_x^\bullet = p^\bullet(x, \vec{y})$$

$$(A \parallel B)_x^\bullet = \exists y, z (A_y^\bullet \parallel B_z^\bullet \parallel (ok(y) \wedge ok(z)) \rightarrow ok(x))$$

$$(A + B)_x^\bullet = A_x^\bullet + B_x^\bullet$$

$$(\forall \vec{y} (c \rightarrow A))_x^\bullet = \forall \vec{z} (c[\vec{z}/\vec{y}] \rightarrow A[\vec{z}/\vec{y}]_x^\bullet) \text{ with } x \notin \vec{z}$$

$$(\exists y A)_x^\bullet = \exists z A[z/y]_x^\bullet \text{ with } z \neq x$$

$$(A \bullet B)_x^\bullet =$$

Proof

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$$(A \bullet B)_x^\bullet = \exists y (A_y^\bullet \parallel ok(y) \rightarrow B_x^\bullet)$$

Part VII

CC and Linear Logic

Part VII: CC and Linear Logic

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 - Linear
 - Soundness
 - Completeness
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 - Completeness
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 - Equivalence
 - Phase Semantics
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 - Syntax and Operational Semantics
 - Examples

Logical Semantics of CC?

- CC calculus is sound but not complete w.r.t. CLP logical semantics (interpreting *asks* as *tells*)
- Interpreting *ask*($c \rightarrow A$) as logical implication leads to identify **CC transitions** with **logical deductions**:

$$\text{left} \rightarrow \frac{c \vdash_C d}{c \wedge (d \rightarrow A^\dagger) \vdash c \wedge A^\dagger} \quad \frac{p(\vec{x}) \vdash_{\mathcal{D}} A^\dagger}{c \wedge p(\vec{x}) \vdash c \wedge A^\dagger}$$

(reverses the arrow of CLP interpretation...)

- To distinguish between successes and accessible stores agents shouldn't disappear by the **weakening rule**:

$$\text{leftW} \frac{\Gamma \vdash c}{\Gamma, A^\dagger \vdash c}$$

Linear Logic

- Introduced by Jean-Yves Girard in 1986 as a new *constructive* logic without the asymmetry of intuitionistic logic (sequent calculus with symmetric left and right sides)
- Logic of **resource consumption**

$$A \otimes A \not\vdash_{LL} A$$

$$A \otimes (A \multimap B) \vdash_{LL} B$$

$$A \otimes (A \multimap B) \not\vdash_{LL} A \otimes B$$

- $!A$ provides arbitrary duplication (unbounded throwable resource)

$$!A \otimes (A \multimap B) \vdash_{LL} !A \otimes B \vdash_{LL} B$$

- Sequent calculus **without weakening and contraction**

Intuitionistic Linear Logic

Multiplicatives

$$\frac{\Gamma, A, B \vdash C}{\Gamma, A \otimes B \vdash C} \quad \frac{\Gamma \vdash A \quad \Delta \vdash B}{\Gamma, \Delta \vdash A \otimes B} \quad \frac{\Gamma \vdash A \quad \Delta, B \vdash C}{\Delta, \Gamma, A \multimap B \vdash C} \quad \frac{\Gamma, A \vdash B}{\Gamma \vdash A \multimap B}$$

Additives

$$\frac{\Gamma, A \vdash C \quad \Gamma, B \vdash C}{\Gamma, A \oplus B \vdash C} \quad \frac{\Gamma \vdash A}{\Gamma \vdash A \oplus B} \quad \frac{\Gamma \vdash B}{\Gamma \vdash A \oplus B}$$

$$\frac{\Gamma, A \vdash C}{\Gamma, A \& B \vdash C} \quad \frac{\Gamma, B \vdash C}{\Gamma, A \& B \vdash C} \quad \frac{\Gamma \vdash A \quad \Gamma \vdash B}{\Gamma \vdash A \& B}$$

Constants

$$\frac{\Gamma \vdash A}{\Gamma, \mathbf{1} \vdash A} \quad \vdash \mathbf{1} \quad \perp \vdash \quad \frac{\Gamma \vdash}{\Gamma \vdash \perp} \quad \Gamma \vdash \top \quad \Gamma, \mathbf{0} \vdash A$$

Intuitionistic Linear Logic (cont.)

Axiom - Cut

$$A \vdash A \quad \frac{\Gamma \vdash A \quad \Delta, A \vdash B}{\Delta, \Gamma \vdash B}$$

Bang

$$\frac{\Gamma, A \vdash B}{\Gamma, !A \vdash B} \quad \frac{\Gamma, !A, !A \vdash B}{\Gamma, !A \vdash B} \quad \frac{\Gamma \vdash B}{\Gamma, !A \vdash B} \quad \frac{! \Gamma \vdash A}{! \Gamma \vdash !A}$$

Quantifiers

$$\frac{\Gamma, A[t/x] \vdash B}{\Gamma, \forall x A \vdash B} \quad \frac{\Gamma \vdash A}{\Gamma \vdash \forall x A} \quad x \notin \text{fv}(\Gamma)$$

$$\frac{\Gamma, A \vdash B}{\Gamma, \exists x A \vdash B} \quad x \notin \text{fv}(\Gamma, B) \quad \frac{\Gamma \vdash A[t/x]}{\Gamma \vdash \exists x A}$$

Intuit. Linear Logic = the Logic of CC agents

Translation:

$$\begin{array}{lll} (c \rightarrow A)^\dagger = c \multimap A^\dagger & (A \parallel B)^\dagger = A^\dagger \otimes B^\dagger & \text{tell}(c)^\dagger = !c \\ (A + B)^\dagger = A^\dagger \& B^\dagger & (\exists x A)^\dagger = \exists x A^\dagger & p(\vec{x})^\dagger = p(\vec{x}) \\ (X; c; \Gamma)^\dagger = \exists X(!c \otimes \Gamma^\dagger) & & \end{array}$$

Axioms: $!c \vdash !d$ for all $c \vdash_C d$ $p(\vec{x}) \vdash A^\dagger$ for all $p(\vec{x}) = A \in \mathcal{D}$

Soundness and Completeness

If $(c; \Gamma) \longrightarrow_{CC} (d; \Delta)$ then $c^\dagger \otimes \Gamma^\dagger \vdash_{ILL(c, \mathcal{D})} d^\dagger \otimes \Delta^\dagger$.

If $A^\dagger \vdash_{ILL(c, \mathcal{D})} c$ then *there exists a **success store** d such that $(\text{true}; A) \longrightarrow_{CC} (d; \emptyset)$ and $d \vdash_C c$.*

If $A^\dagger \vdash_{ILL(c, \mathcal{D})} c \otimes \top$ then *there exists an **accessible store** d such that $(\text{true}; A) \longrightarrow_{CC} (d; \Gamma)$ and $d \vdash_C c$.*

Soundness

Theorem (Soundness of transitions)

Let $(X; c; \Gamma)$ and $(Y; d; \Delta)$ be CC configurations.

If $(X; c; \Gamma) \equiv (Y; d; \Delta)$ then $(X; c; \Gamma)^\dagger \dashv\vdash_{ILL(\mathcal{C}, \mathcal{D})} (Y; d; \Delta)^\dagger$.

If $(X; c; \Gamma) \longrightarrow (Y; d; \Delta)$ then $(X; c; \Gamma)^\dagger \vdash_{ILL(\mathcal{C}, \mathcal{D})} (Y; d; \Delta)^\dagger$.

Proof.

By induction on \equiv . Immediate.

By induction on \longrightarrow .

The choice operator $+$ is translated by the additive conjunction $\&$, which expresses “may” properties: $A \& B \vdash A$ and $A \& B \vdash B$. \square

Completeness I

Theorem (Observation of successes)

Let A be a CC agent and c be a constraint.

If $A^\dagger \vdash_{ILL(\mathcal{C}, \mathcal{D})} c$, then there exists a constraint d such that $(\emptyset; 1; A) \longrightarrow (X; d; \emptyset)$ and $\exists X d \vdash_{\mathcal{C}} c$.

Proof.

By induction on a sequent calculus proof π of $A_1^\dagger, \dots, A_n^\dagger \vdash_{ILL(\mathcal{C}, \mathcal{D})} \phi$,

where the A_i 's are agents and ϕ is either a constraint or a procedure name.



Completeness II

Recall that \top is the additive true constant neutral for $\&$.

Theorem (Observation of accessible stores)

Let A be a CC agent and c be a constraint.

*If $A^\dagger \vdash_{ILL(\mathcal{C}, \mathcal{D})} c \otimes \top$, then c is a store accessible from A ,
i.e. there exist a constraint d and a multiset Γ of agents such that
 $(\emptyset; 1; A) \longrightarrow (X; d; \Gamma)$ and $\exists Xd \vdash_{\mathcal{C}} c$.*

Proof.

The proof uses the first completeness theorem, and proceeds by an easy induction for the right introduction of the tensor connective in $c \otimes \top$. □

Observing “must” Properties

Properties true on **all branches** on the derivation tree.
Redefine the operational semantics by a rewriting relation on **frontiers**, i.e. multisets of configurations

Blind choice

$$\langle (X; c; A + B), \Phi \rangle \Longrightarrow \langle (X; c; A), (X; c; B), \Phi \rangle$$

Tell

$$\langle (X; c; \text{tell}(d), \Gamma), \Phi \rangle \Longrightarrow \langle (X; c \wedge d; \Gamma), \Phi \rangle$$

Ask

$$\frac{c \vdash_c d \otimes e}{\langle (X; c; e \rightarrow A, \Gamma), \Phi \rangle \Longrightarrow \langle (X; d; A, \Gamma), \Phi \rangle}$$

Procedure calls

$$\frac{(p(\vec{y}) = A) \in \mathcal{D}}{\langle (X; c; p(\vec{y}), \Gamma), \Phi \rangle \Longrightarrow \langle (X; c; A, \Gamma), \Phi \rangle}$$

Translating the Frontier Calculus in LL with \oplus

Translate

$$(A + B)^{\ddagger} = A^{\ddagger} \oplus B^{\ddagger}$$

$$\langle (X; c; A), \Phi \rangle^{\ddagger} = \exists X (c^{\ddagger} \otimes A^{\ddagger}) \oplus \Phi^{\ddagger}$$

same translation for the other operations

Theorem (Soundness of transitions)

Let Φ and Ψ be two frontiers.

If $\Phi \equiv \Psi$ then $(\Phi)^{\ddagger} \dashv\vdash_{ILL(\mathcal{C}, \mathcal{D})} (\Psi)^{\ddagger}$.

If $\Phi \Longrightarrow \Psi$ then $\Phi^{\ddagger} \vdash_{ILL(\mathcal{C}, \mathcal{D})} \Psi^{\ddagger}$.

Completeness III for “must” Properties

Theorem (Observation of frontiers' accessible stores)

Let A be a CC agent and c be a constraint.

If $A^\dagger \vdash_{ILL(C,D)} c \otimes \top$

then $\langle (\emptyset; 1; A) \rangle \Longrightarrow \langle (X_1; d_1; \Gamma_1), \dots, (X_n; d_n; \Gamma_n) \rangle$ with

$\forall j \exists X_j d_j \vdash_C c$

Theorem (Observation of frontiers' success stores)

Let A be an CC agent and c be a constraint.

If $A^\dagger \vdash_{ILL(C,D)} c$

then $\langle (\emptyset; 1; A) \rangle \Longrightarrow \langle (X_1; d_1; \emptyset), \dots, (X_n; d_n; \emptyset) \rangle$ with $\forall j \exists X_j d_j \vdash_C c$

Logical Equivalence of CC programs

Let $P = \mathcal{D}.A$ be a $CC(\mathcal{C})$ process.

Corollary

If $P^\dagger \dashv\vdash_{ILL(\mathcal{C}, \mathcal{D})} P'^\dagger$
then $\mathcal{O}_{ss}(P) = \mathcal{O}_{ss}(P')$ (same set of success stores)
and $\mathcal{O}_{as}(P) = \mathcal{O}_{as}(P')$ (same set of accessible stores).

Corollary

If $P^\ddagger \dashv\vdash_{ILL(\mathcal{C}, \mathcal{D})} P'^\ddagger$
then P and P' have the same set of accessible stores on all
branches
and the same success frontiers.

Proving Properties of CC Programs

- Proving *logical equivalence* of CC programs with the sequent calculus of LL:
 - focusing proofs (deterministic rules for the additives first)
 - lazy splitting (input/output contexts for the multiplicatives)
- Proving *safety properties* of CC programs with the *phase semantics* of LL [FRS98]

Soundness gives $\Gamma \vdash_{ILL} A$ implies $\forall \mathbf{P} \forall \eta \mathbf{P}, \eta \models (\Gamma \vdash A)$.

$\exists \mathbf{P}, \eta$, s.t. $\mathbf{P}, \eta \not\models (\Gamma \vdash A)$ implies $\Gamma \not\vdash_{ILL, \mathcal{D}} A$.

Corollary

To prove a safety property $(c, A) \dashrightarrow (d, B)$, it is enough to show that \exists a phase space \mathbf{P} , a valuation η , and an element $a \in \eta((c, A)^\dagger)$ such that $a \notin \eta((d, B)^\dagger)$.

Implementations of LL Sequent Calculi

- Forum [Miller&al.] specification languages based on LL
- LO [Andreoli] Property of “focusing proofs” in LL
- Lolli [Cervesato Hodas Pfenning] Search for “Uniform proofs”
- Lygon [Harland Winikoff] Linear Logic Programming language

Problem of lazy splitting:

$$\frac{\vdash A, \Gamma \quad \vdash B, \Delta}{\vdash A \otimes B, \Gamma, \Delta} (\otimes)$$

First idea:

$$\frac{\vdash A - (\Gamma, \Delta); \Delta \quad \vdash B, \Delta}{\vdash A \otimes B, \Gamma, \Delta} (\otimes)$$

- problems with the rules for ! and for \top ...
- stacks are necessary

Linear Constraint Systems $(\mathcal{C}, \vdash_{\mathcal{C}})$

\mathcal{C} is a set of formulas built from V, Σ with logical operators: $1, \otimes, \exists$ and $!$;

$\vdash_{\mathcal{C}} \subseteq \mathcal{C} \times \mathcal{C}$ defines the non-logical axioms of the constraint system.

$\vdash_{\mathcal{C}}$ is the least subset of $\mathcal{C}^* \times \mathcal{C}$ containing $\vdash_{\mathcal{C}}$ and closed by:

$$\begin{array}{c}
 c \vdash c \quad \frac{\Gamma, c \vdash d \quad \Delta \vdash c}{\Gamma, \Delta \vdash d} \quad \vdash 1 \quad \frac{\Gamma \vdash c}{\Gamma, 1 \vdash c} \\
 \\
 \frac{\Gamma \vdash c_1 \quad \Delta \vdash c_2}{\Gamma, \Delta \vdash c_1 \otimes c_2} \quad \frac{\Gamma, c_1, c_2 \vdash c}{\Gamma, c_1 \otimes c_2 \vdash c} \quad \frac{\Gamma \vdash c[t/x]}{\Gamma \vdash \exists x c} \quad \frac{\Gamma, c \vdash d}{\Gamma, \exists x c \vdash d} \quad x \notin \text{fv}(\Gamma, d) \\
 \\
 \frac{\Gamma, c \vdash d}{\Gamma, !c \vdash d} \quad \frac{! \Gamma \vdash d}{! \Gamma \vdash !d} \quad \frac{\Gamma \vdash d}{\Gamma, !c \vdash d} \quad \frac{\Gamma, !c, !c \vdash d}{\Gamma, !c \vdash d}
 \end{array}$$

A **synchronization constraint** is a constraint not appearing in $\vdash_{\mathcal{C}}$

Linear-CC(\mathcal{C}) Operational Semantics

$$\text{Equivalence} \quad \frac{(X; c; \Gamma) \equiv (X'; c'; \Gamma') \longrightarrow (Y'; d'; \Delta') \equiv (Y; d; \Delta)}{(X; c; \Gamma) \longrightarrow (Y; d; \Delta)}$$

$$\text{Tell} \quad (X; c; \text{tell}(d), \Gamma) \longrightarrow (X; c \otimes d; \Gamma)$$

$$\text{Ask} \quad \frac{c \vdash_c d[\vec{t}/\vec{y}] \otimes e}{(X; c; \forall \vec{y}(d \rightarrow A), \Gamma) \longrightarrow (X; e; A[\vec{t}/\vec{y}], \Gamma)}$$

$$\text{Hiding} \quad \frac{y \notin X \cup \text{fv}(c, \Gamma)}{(X; c; \exists y A, \Gamma) \longrightarrow (X \cup \{y\}; c; A, \Gamma)}$$

$$\text{Procedure calls} \quad \frac{(p(\vec{y}) = A) \in \mathcal{D}}{(X; c; p(\vec{y}), \Gamma) \longrightarrow (X; c; A, \Gamma)}$$

An LCC(\mathcal{FD}) program for the dining philosophers

Goal(N) = RecPhil(1,N).

RecPhil(M,P) =

$M \neq P \rightarrow (\text{Philo}(M,P) \parallel \text{fork}(M) \parallel \text{RecPhil}(M+1,P))$

\parallel

$M = P \rightarrow (\text{Philo}(M,P) \parallel \text{fork}(M)).$

Philo(I,N) =

$(\text{fork}(I) \otimes \text{fork}(I+1 \bmod N)) \rightarrow$

$(\text{eat}(I) \parallel$

$\text{eat}(I) \rightarrow (\text{fork}(I) \parallel \text{fork}(I+1 \bmod N) \parallel$

$\text{Philo}(I,N))).$

Safety properties: deadlock freeness, two neighbors don't eat at the same time, etc.

Encoding Linda in LCC(\mathcal{H})

- Shared tuple space
- Asynchronous communication (through tuple space)
- *input* consumes the tuple, *read* doesn't
- One-step guarded choice
- Conditional with **else** case (check the absence of tuple) not encodable in LCC.

Encoding the π -calculus in LCC(\mathcal{H})

- Direct encoding of the asynchronous π -calculus:

$$\begin{aligned} [0] &= 1 \\ [(y)P] &= \exists y[P] \\ [\bar{x}y.0] &= \\ [x(y).P] &= \\ [P|Q] &= [P]||[Q] \\ [[x = y]P] &= (x = y) \rightarrow [P] \\ [P + Q] &= [P] + [Q] \end{aligned}$$

- The usual (synchronous) π -calculus can be simulated with a synchronous communication protocol.

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- The usual (synchronous) π -calculus can be simulated with a synchronous communication protocol.

Producer Consumer Protocol in LCC

$$P = \text{dem} \rightarrow (\text{pro} \parallel P)$$
$$C = \text{pro} \rightarrow (\text{dem} \parallel C)$$
$$\text{init} = \text{dem}^n \parallel P^m \parallel C^k$$

Deadlock-freeness: $\text{init} \not\rightarrow_{LCC} \text{dem}^{n'} \parallel P^{m'} \parallel C^{k'} \parallel \text{pro}^{l'}$, with either $n' = l' = 0$ or $m' = 0$ or $k' = 0$

Number of units consumed always $<$ number of units produced:

$$P = \text{dem} \rightarrow (\text{pro} \parallel P \parallel \forall X (\text{np}=X \rightarrow \text{np}=X+1))$$
$$C = \text{pro} \rightarrow (\text{dem} \parallel C \parallel \forall X (\text{nc}=X \rightarrow \text{nc}=X+1))$$
$$\text{init} = \text{dem}^n \parallel P^m \parallel C^k \parallel \text{np}=0 \parallel \text{nc}=0$$
$$\text{init} \not\rightarrow_{LCC} \text{dem}^{n'} \parallel \text{pro}^{l'} \parallel P^m \parallel C^k \parallel \text{np}=\text{np}_0 \parallel \text{nc}=\text{nc}_0$$

with $\text{nc}_0 > \text{np}_0$

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