

# Numerical-Integration Based Eigensolvers

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- Numerical linear algebra is a core subject in computational methods
- The two major themes within numerical linear algebra are
  1. Solutions of linear system: Given matrix  $A$  and vector  $\mathbf{b}$ , find vector  $\mathbf{x}$  such that  $A\mathbf{x} \approx \mathbf{b}$
  2. Eigenproblems:
    - Standard eigenproblem: Given matrix  $A$ , find scalar  $\lambda$  and vector  $\mathbf{x}$  such that  $A\mathbf{x} = \lambda\mathbf{x}$
    - Generalized eigenproblem: Given matrices  $A$  and  $B$ , find scalar  $\lambda$  and vector  $\mathbf{x}$  such that  $A\mathbf{x} = \lambda B\mathbf{x}$ .

Eigenvalue problems is of major importance in many scientific and engineering applications. Quoting verbatim from Saad's textbook:

- Structural dynamics
- Electrical networks
- Combustion processes
- Macro economics
- Normal mode techniques
- Quantum chemistry
- Markov chain techniques
- Chemical reactions
- Magneto hydrodynamics
- Control theory

- When the matrix is of moderate size, there are well established method and robust software, such as LAPACK.
- When the underlying matrix is large and perhaps sparse, solving for part of the spectrum is still an active research area
- Recently, a new type of methods have been proposed that involve the use of analytic function theory and numerical integration
  - Sakurai and collaborators used a pole finding technique (SS algorithms)
  - Polizzi and collaborators used an approximate subspace projector (FEAST algorithm)
  - Both use numerical integration
- I will mainly use the FEAST algorithm to introduce these integration-based methods

## High-Level Outline

- FEAST as filtered subspace iteration, for Hermitian problems
- FEAST for non-Hermitian problems
- SS method as filtered Krylov subspace method
- Function approximation and computer arithmetic studies related to the filter



## FEAST for Hermitian Problems

- FEAST as filtered subspace iteration for standard Hermitian eigenproblem
- The approximate spectral projector filter
- Convergence analysis of filtered subspace iteration
- FEAST for generalized Hermitian problem

# Review: Subspace Iteration for HEP

Recall the standard fact about Hermitian matrices.

For any Hermitian matrix  $M$ ,  $n$ -by- $n$ ,

$M$  can be diagonalized by a unitary matrix  $U$ :

$$M = U\Lambda U^H, \quad \Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n), \quad U^H U = I$$

$U$  consists of  $n$  orthogonal eigenvectors,

and the  $\lambda_j \in \mathbb{R}$  are eigenvalues.

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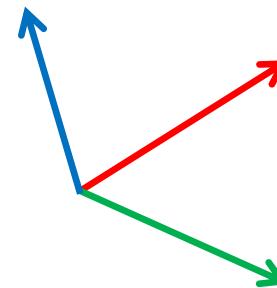
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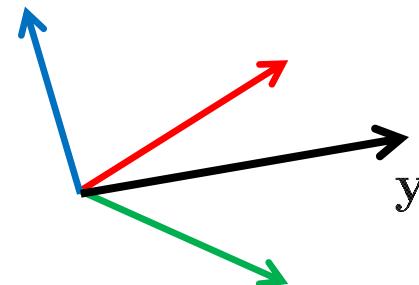
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consider  $\mathbf{y} = \mathbf{x}_1 + \mathbf{x}_2 + \mathbf{x}_3$



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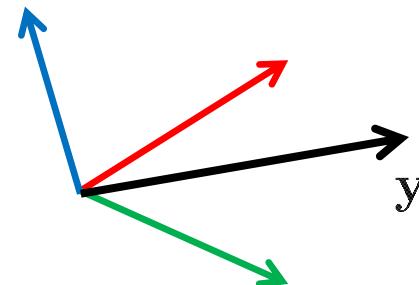
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$$\begin{aligned} \text{consider } \mathbf{y} &= \mathbf{x}_1 + \mathbf{x}_2 + \mathbf{x}_3 \\ A\mathbf{y} &= 10\mathbf{x}_1 + \mathbf{x}_2 + \mathbf{x}_3 \end{aligned}$$



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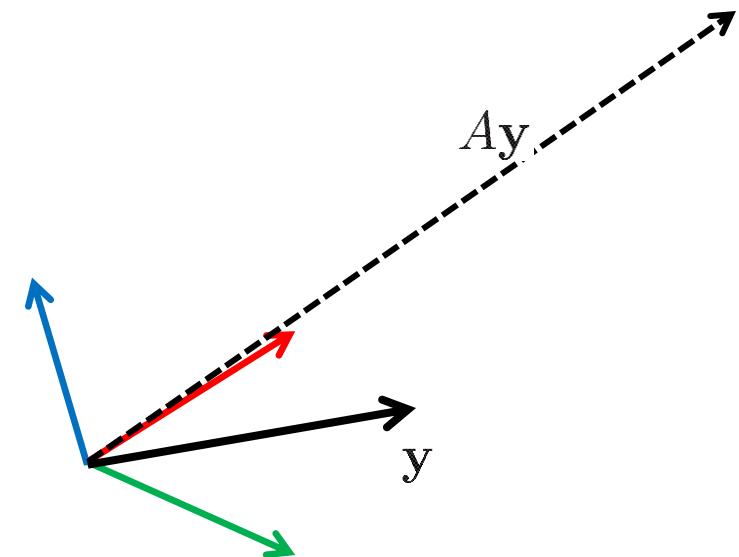
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consider  $\mathbf{y} = \mathbf{x}_1 + \mathbf{x}_2 + \mathbf{x}_3$   
 $A\mathbf{y} = 10\mathbf{x}_1 + \mathbf{x}_2 + \mathbf{x}_3$

$A\mathbf{y}$  is close to direction of  $\mathbf{x}_1$



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Matrix  $M$ ,  $n$ -by- $n$

eigenvalues  $\lambda$ , eigenvectors  $\mathbf{x}$

$$M\mathbf{x} = \lambda\mathbf{x}$$

*Subspace Iteration:*

Random  $Q_0 = [y_1, y_2, \dots, y_p]$ ,  $p \ll n$

Loop  $k = 1, 2, 3 \dots$

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$Q_k^T M Q_k$  captures the “big”

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Informally:

If  $|\lambda_i| > |\lambda_{p+1}|$

then  $\text{distance}(\mathbf{x}_i, \mathcal{Q}_k) \rightarrow 0$

$\mathcal{Q}_k$  = subspace spanned by  $Q_k$

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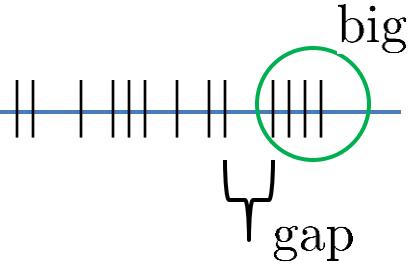
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Formally:

If  $|\lambda_i| > |\lambda_{p+1}|$

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$P_k$  is orthogonal projection to  $\mathcal{Q}_k$ ,

i.e.  $P_k = Q_k Q_k^H$

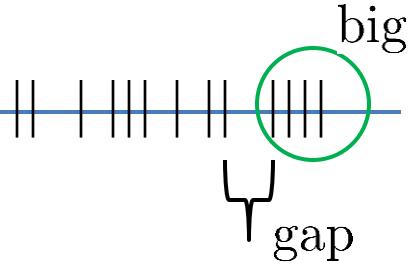
$$\|(I - P_k)\mathbf{x}_i\|_2 \leq \alpha |\lambda_{p+1}/\lambda_i|^k$$

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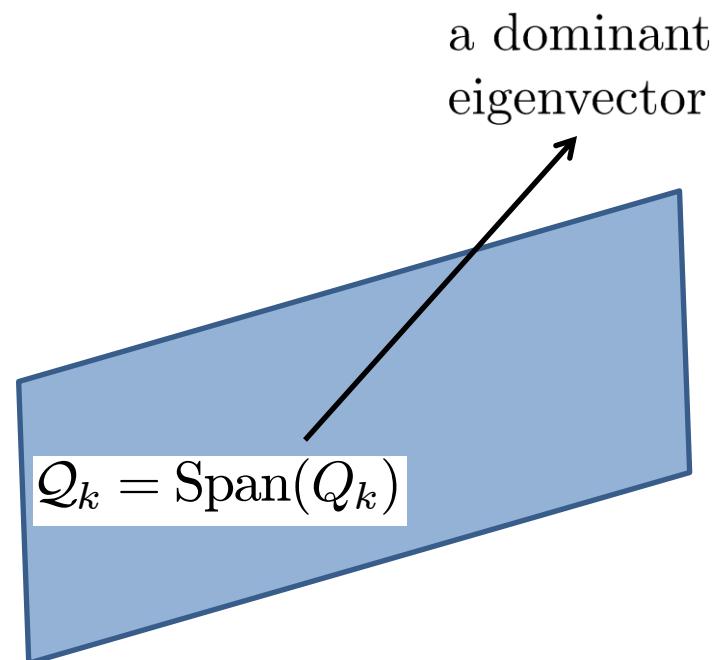
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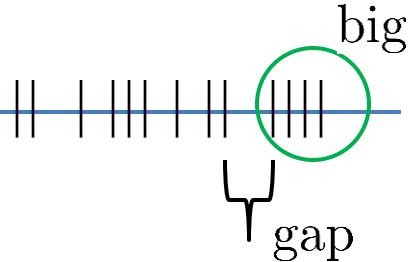


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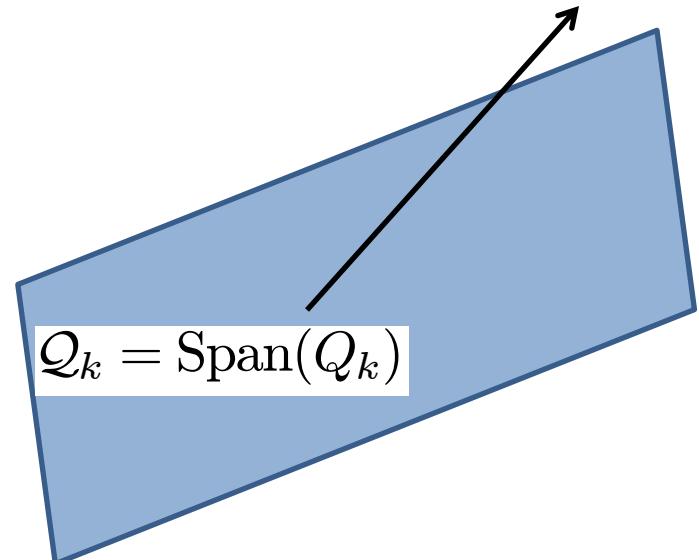
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a dominant eigenvector

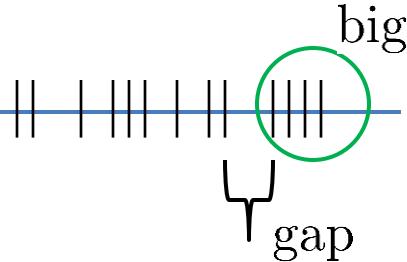


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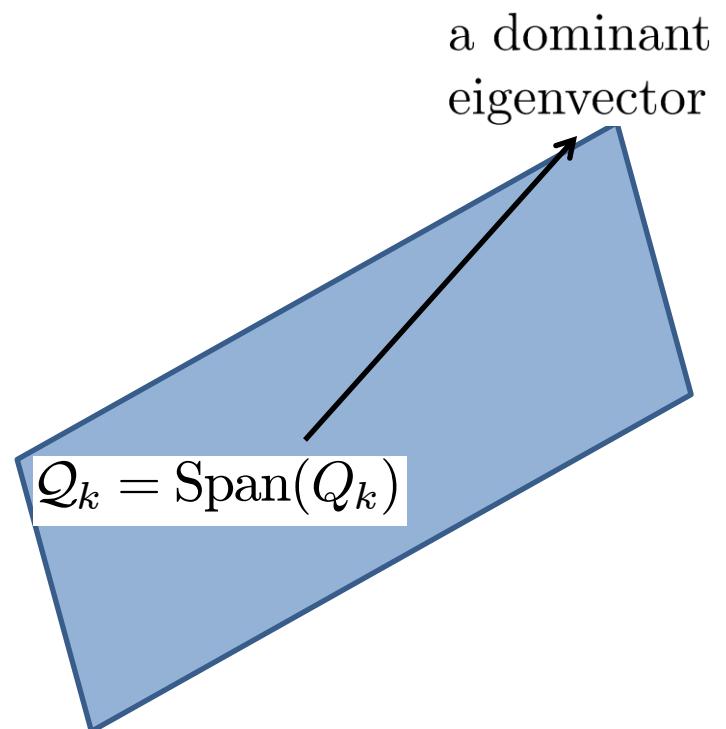
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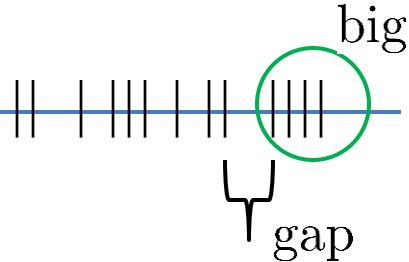


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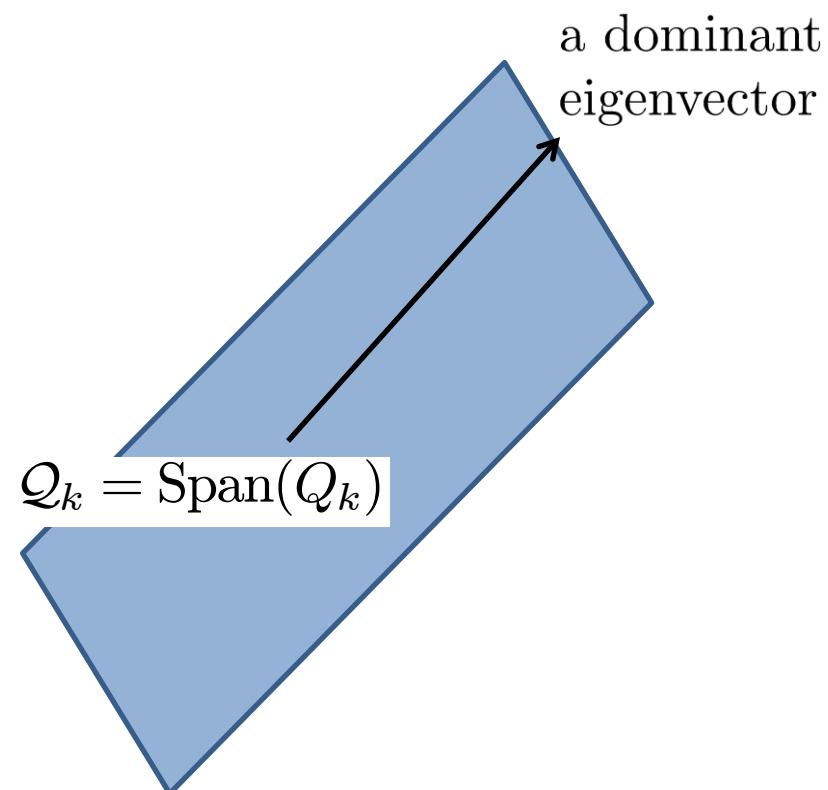
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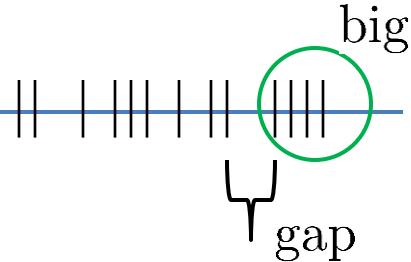


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Only works for “big”

Speed at the mercy of “gap”

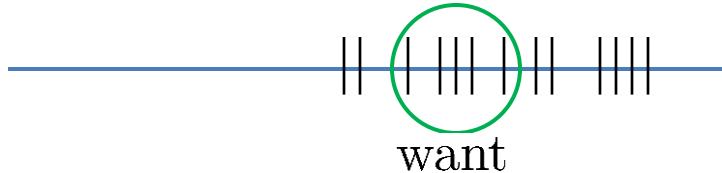
Can be VERY slow

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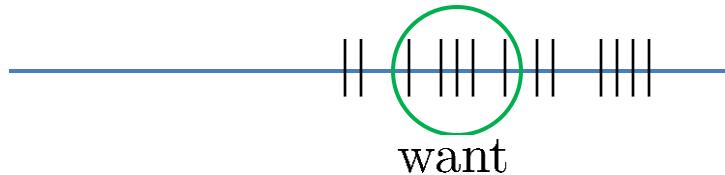
CANNOT give what you WANT

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Loop  $k = 1, 2, 3 \dots$

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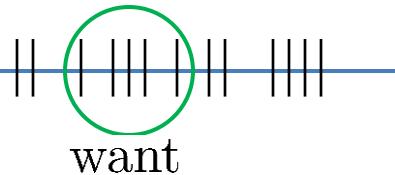
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heart of FEAST

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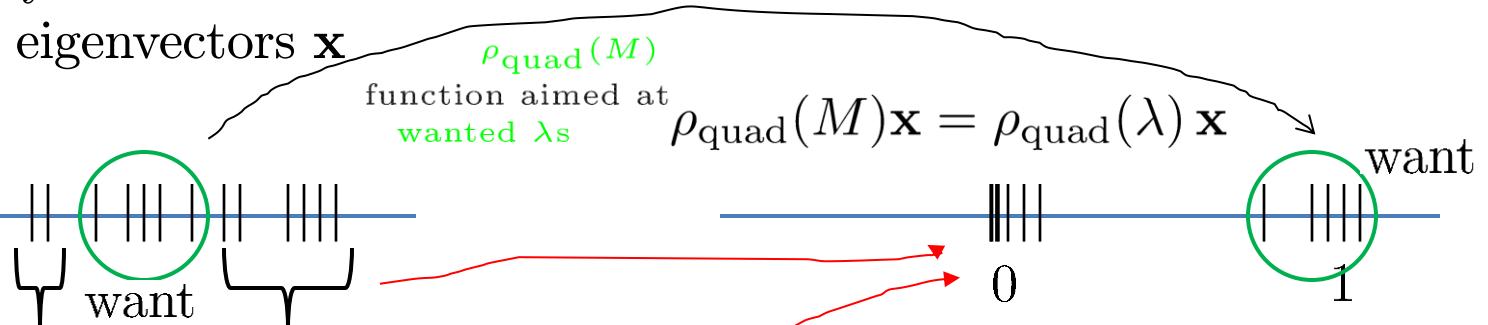
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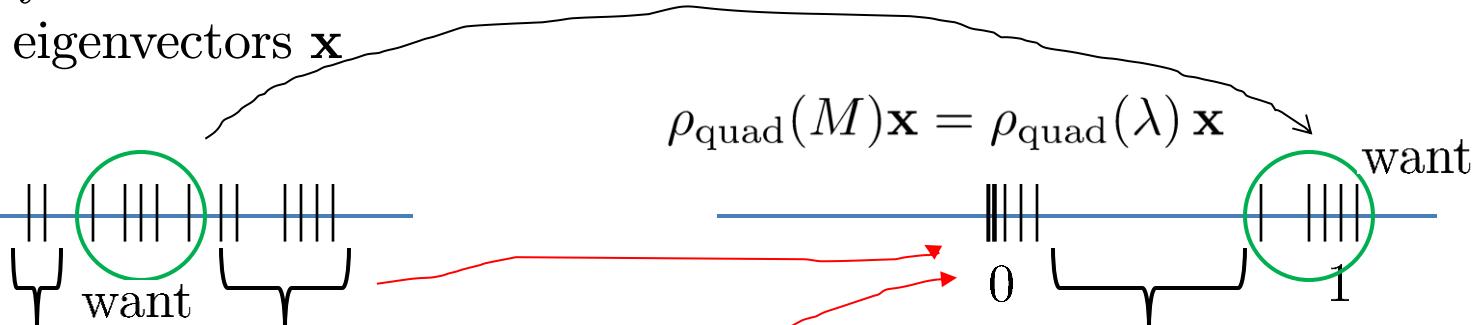
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## FEAST for Hermitian Problems

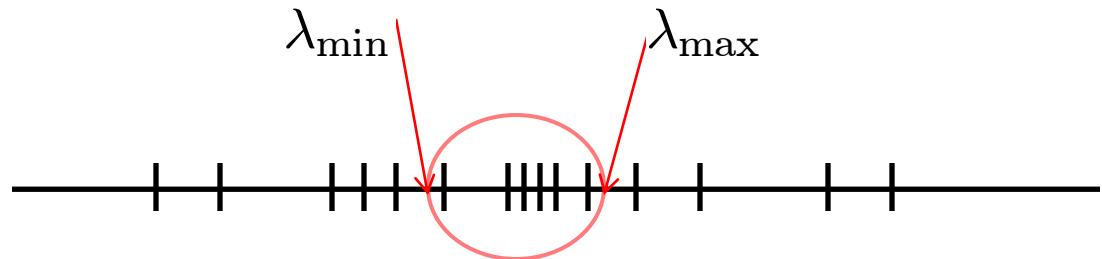
- FEAST as filtered subspace iteration for standard Hermitian eigenproblem
- The approximate spectral projector filter
- Convergence analysis of filtered subspace iteration
- FEAST for generalized Hermitian problem

# Spectral Projector and $\rho_{\text{quad}}(M)$

$M = X \Lambda X^{-1}$ ,  $X$  is orthonormal

- we are interested in  $\lambda$  inside  $[\lambda_{\min}, \lambda_{\max}]$

$$M = X \begin{pmatrix} \lambda_{\text{smallest}} & & \\ & \ddots & \\ & & \lambda_{\text{largest}} \end{pmatrix} X^{-1}$$



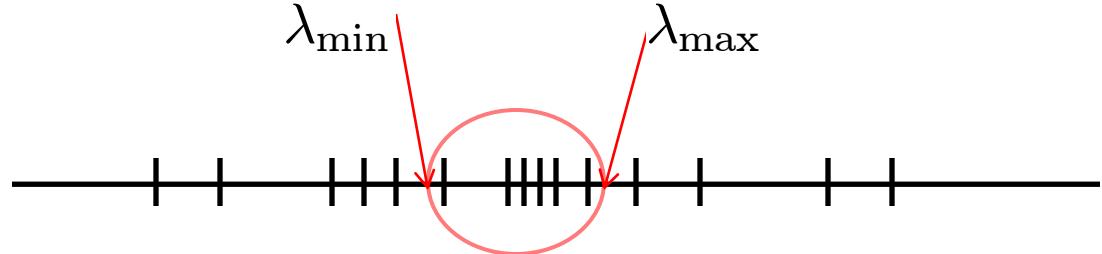
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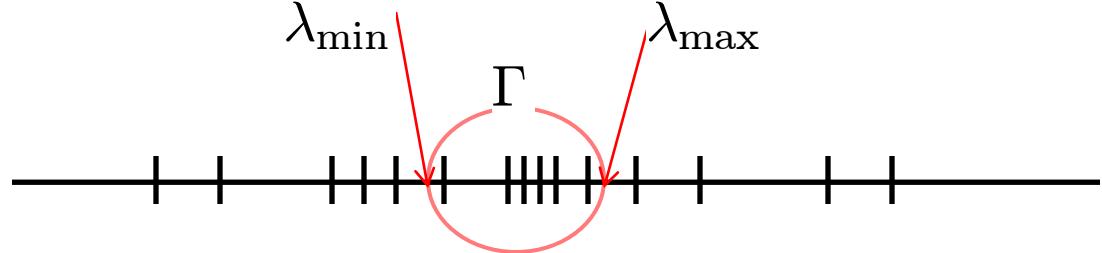
$$M = X \begin{pmatrix} \lambda_{\text{smallest}} & & \\ & \ddots & \\ & & \lambda_{\text{largest}} \end{pmatrix} X^{-1}$$

$$\Pi(M) = X \begin{pmatrix} 0 & & \\ & 1 & \\ & & 0 \end{pmatrix} X^{-1}$$



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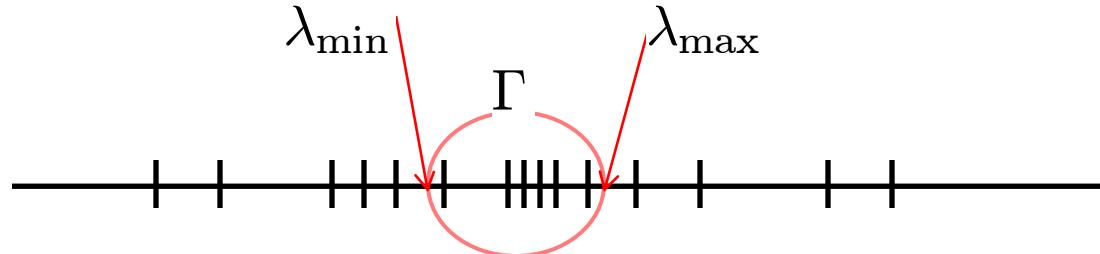


$$M = X \Lambda X^{-1}, X \text{ is orthonormal}$$

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Want scalar function  $\rho(\lambda)$  where

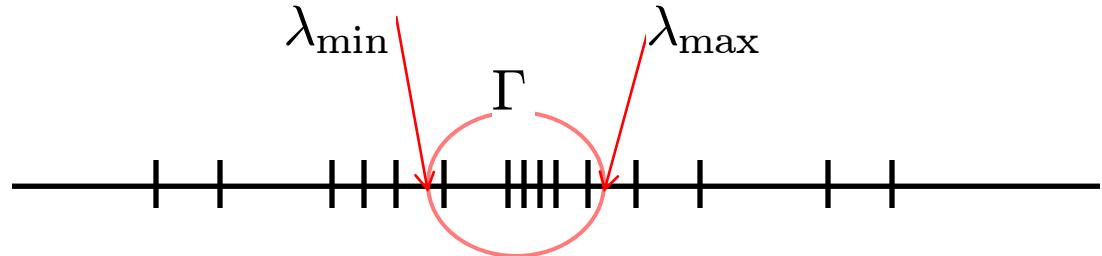
- $\rho(\lambda)$  is close to 1 for  $\lambda$  inside interval
- $\rho(\lambda)$  is close to 0
- The matrix function  $\rho(M)Y$  is practical to compute



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Want scalar function  $\rho(\lambda)$  where

- $\rho(\lambda)$  is close to 1 for  $\lambda$  inside interval
- $\rho(\lambda)$  is close to 0
- The matrix function  $\rho(M)Y$  is practical to compute



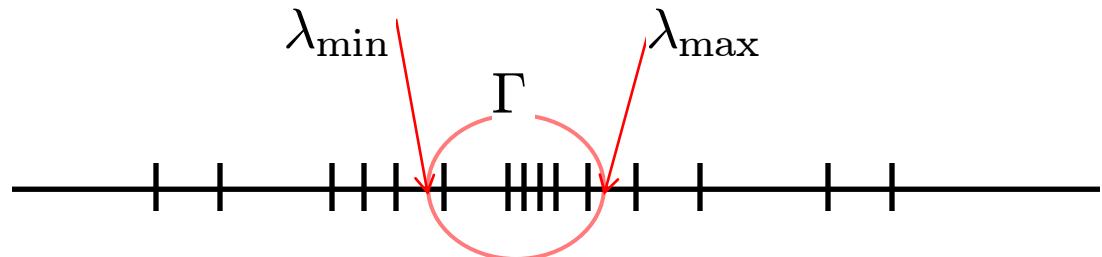
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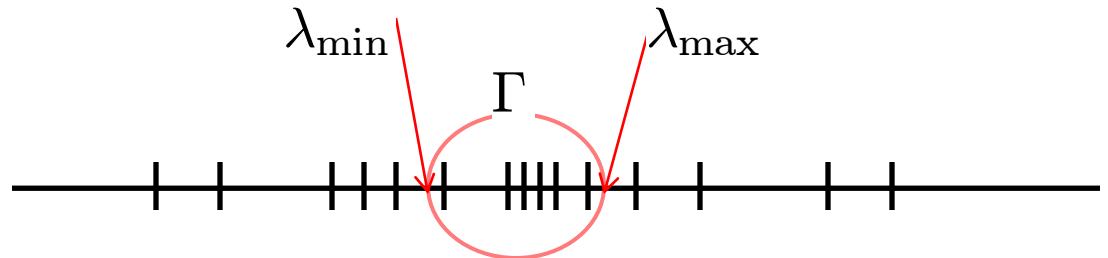
$$\pi(\lambda) = \frac{1}{2\pi\iota} \oint_{\Gamma} (z - \lambda)^{-1} dz = \begin{cases} 1 & \lambda \in \Gamma \text{'s interior,} \\ 0 & \text{otherwise.} \end{cases}$$



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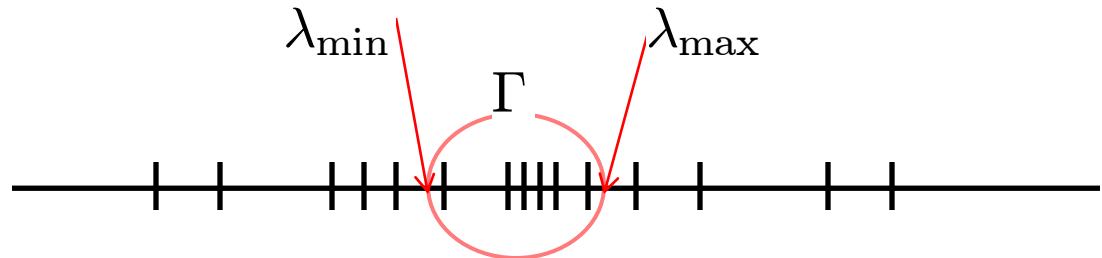
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$$\rho_{\text{quad}}(\lambda) \stackrel{\text{def}}{=} \sum_{k=1}^q w_k (z_k - \lambda)^{-1}$$



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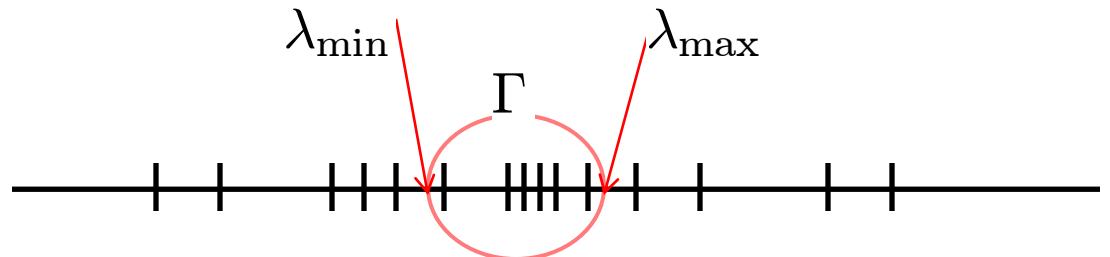
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Easy to see

$$\rho_{\text{quad}}(M)Y = \sum_{k=1}^q w_k (z_k I - M)^{-1}Y$$



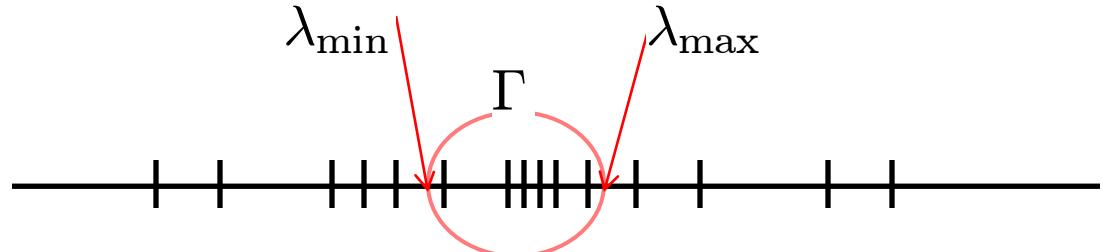
# Approximate Spectral Projector

$M = X \Lambda X^{-1}$ ,  $X$  is orthonormal

$$\rho_{\text{quad}}(M) = X \rho_{\text{quad}}(\Lambda) X^{-1}$$

$$\rho_{\text{quad}}(\lambda) = \sum_{k=1}^q w_k(z_k - \lambda)^{-1}$$

- $\rho_{\text{quad}}(\lambda)$  is close to 1 for  $\lambda$  inside interval
- $\rho_{\text{quad}}(\lambda)$  is close to 0
- Once quadrature rule is fixed, we know  $\rho_{\text{quad}}$  exactly



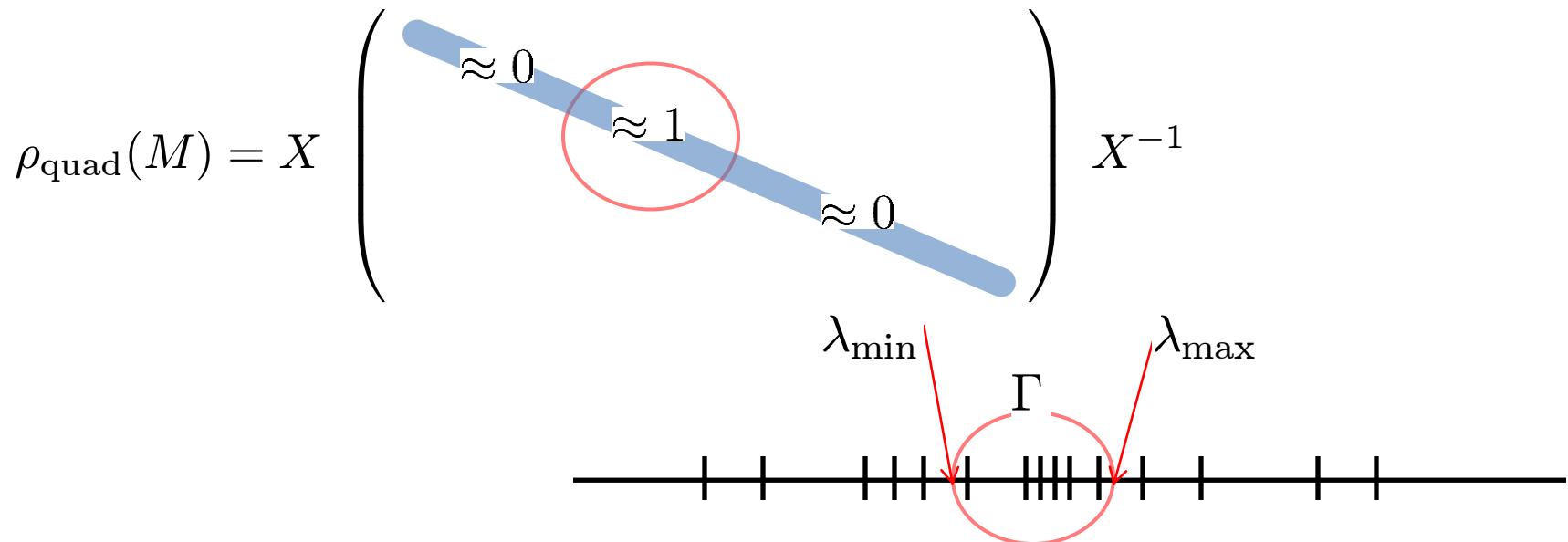
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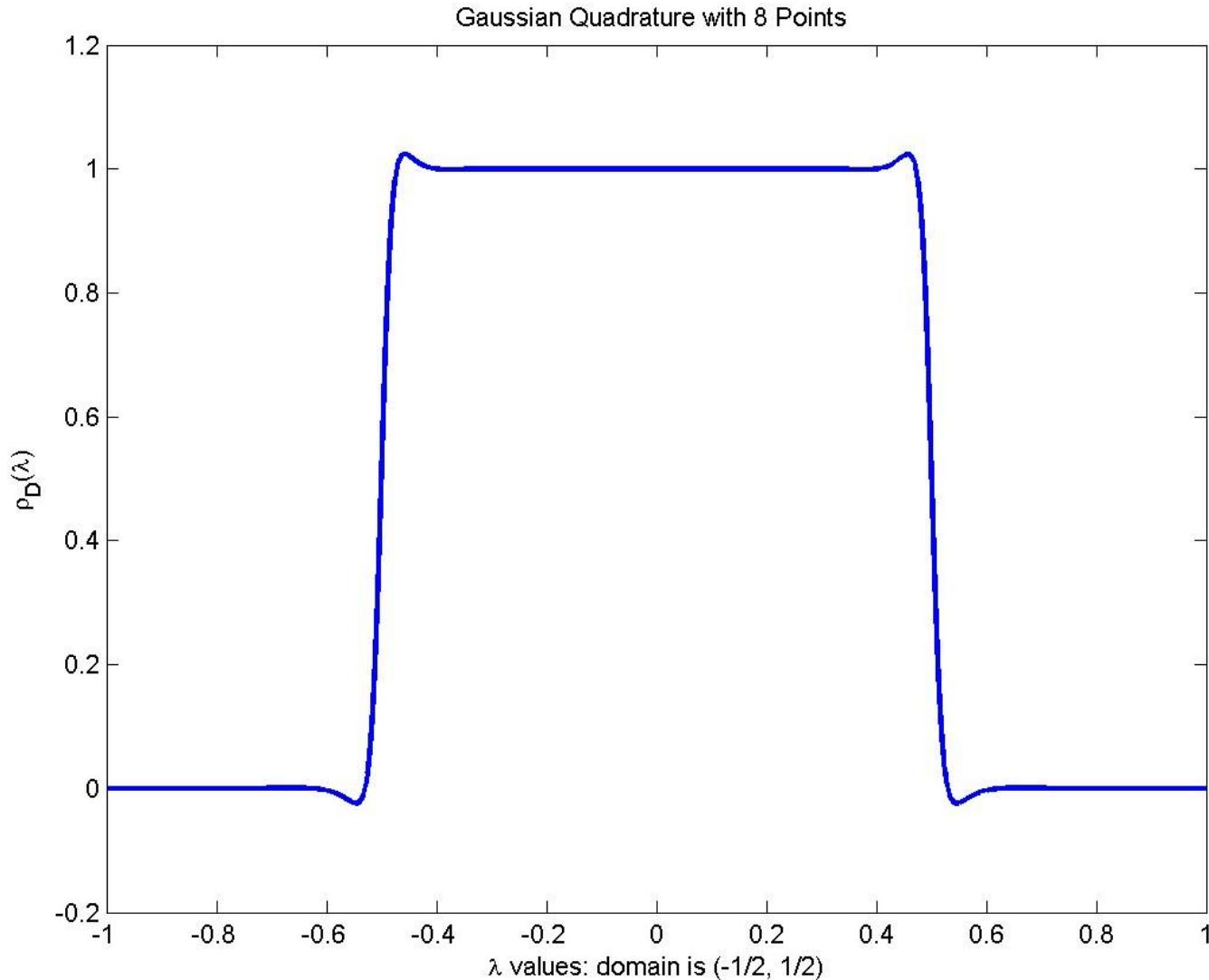
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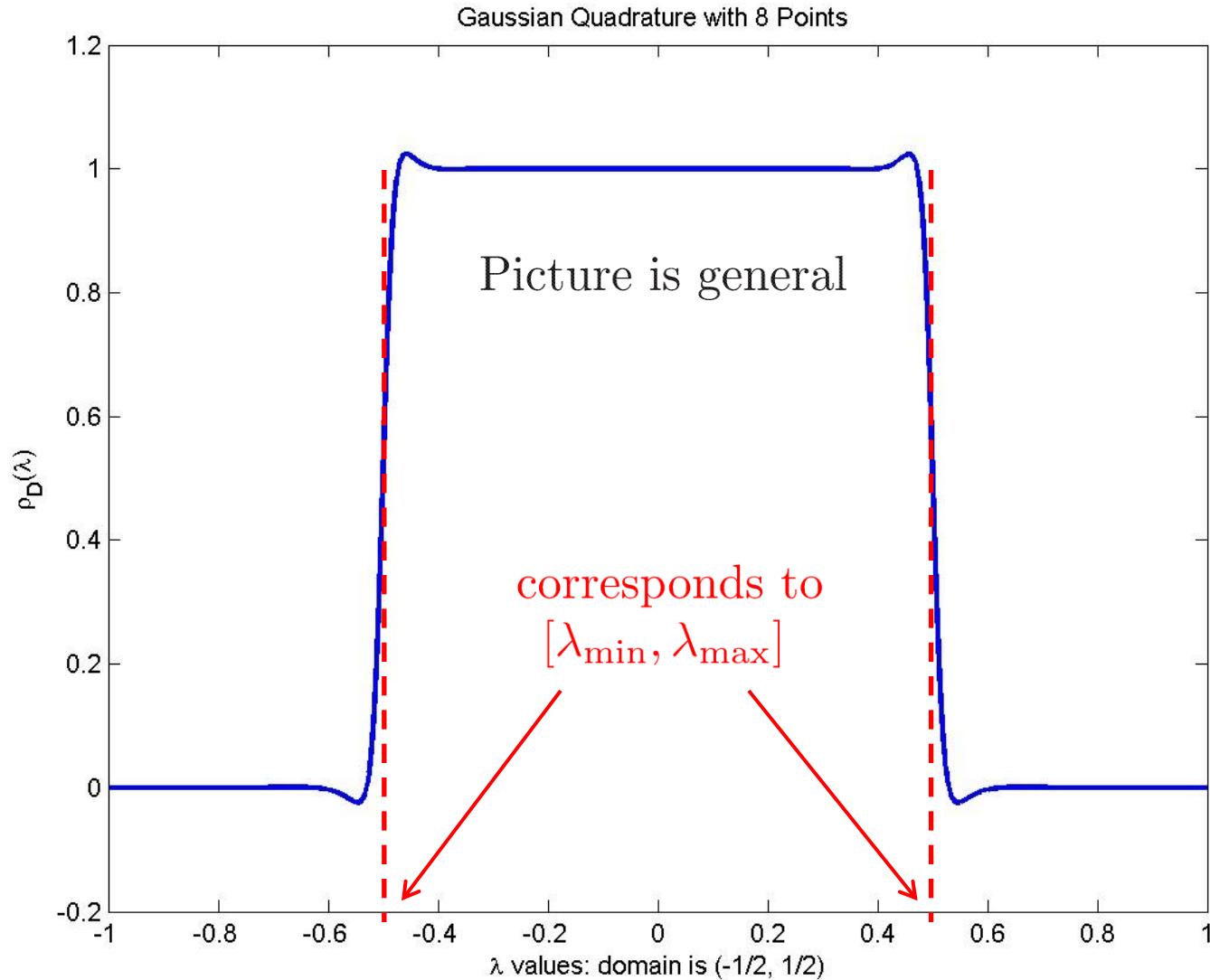
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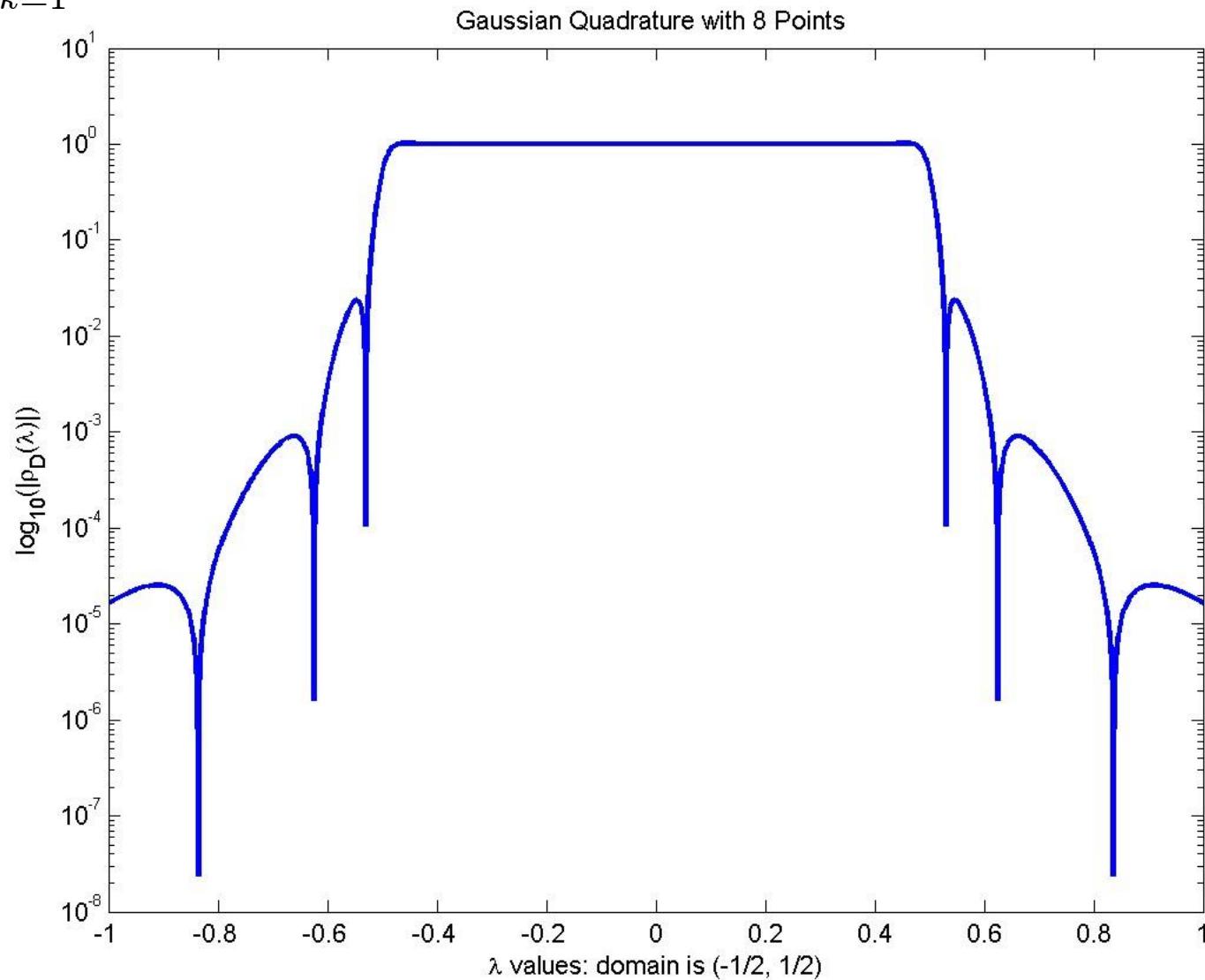
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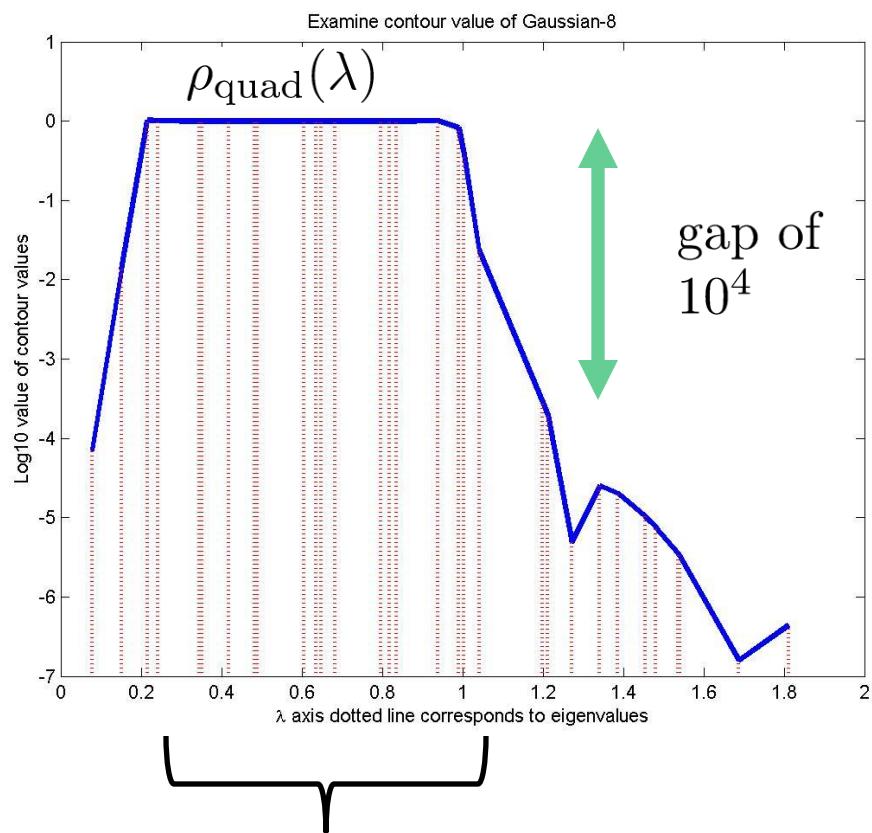
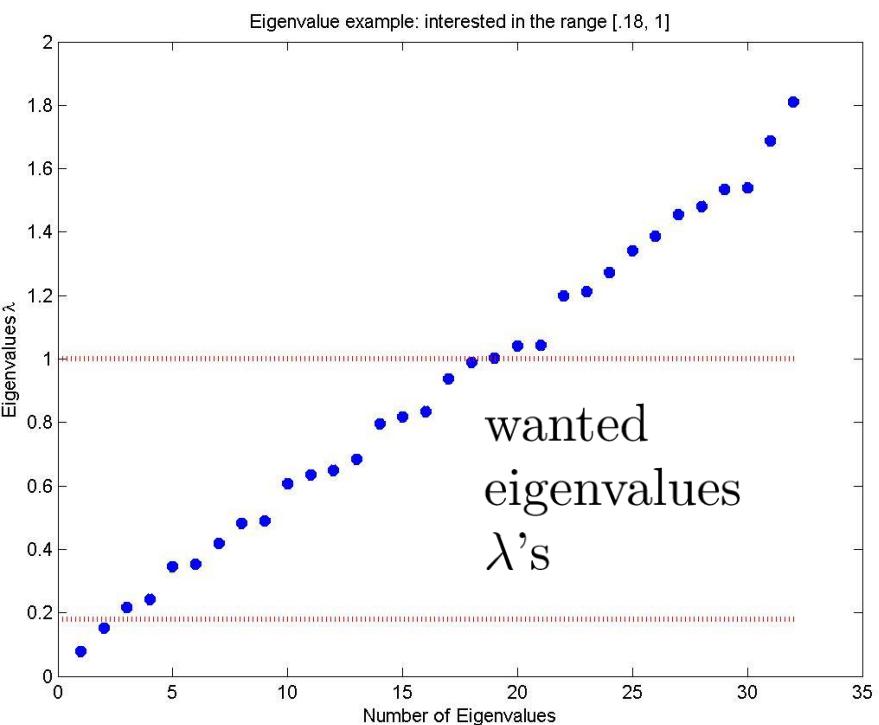


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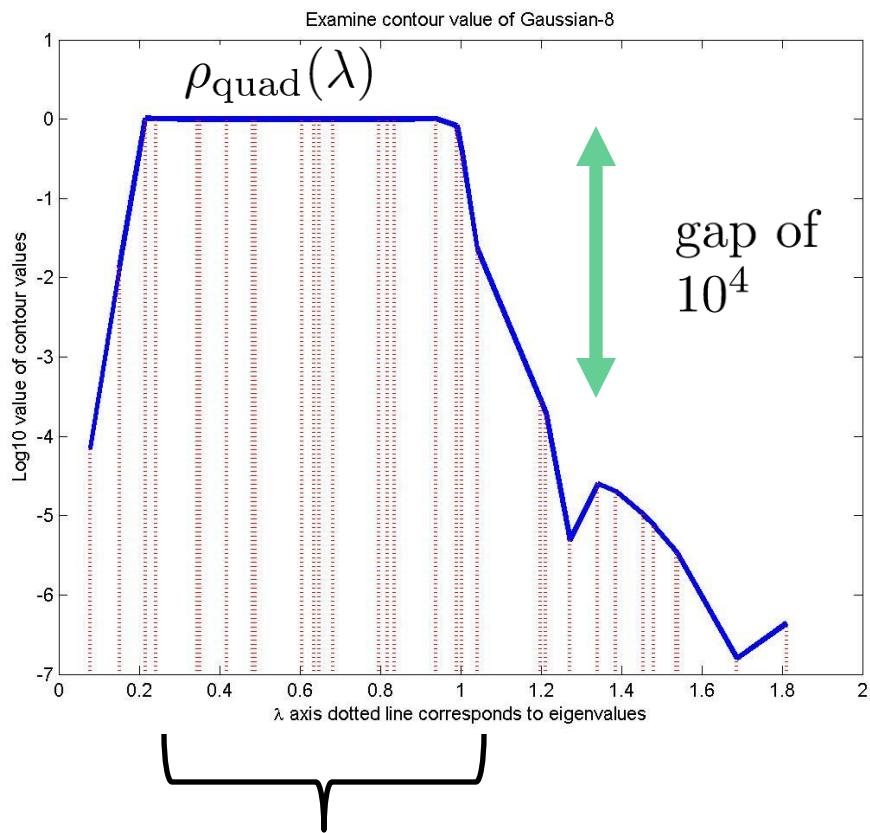
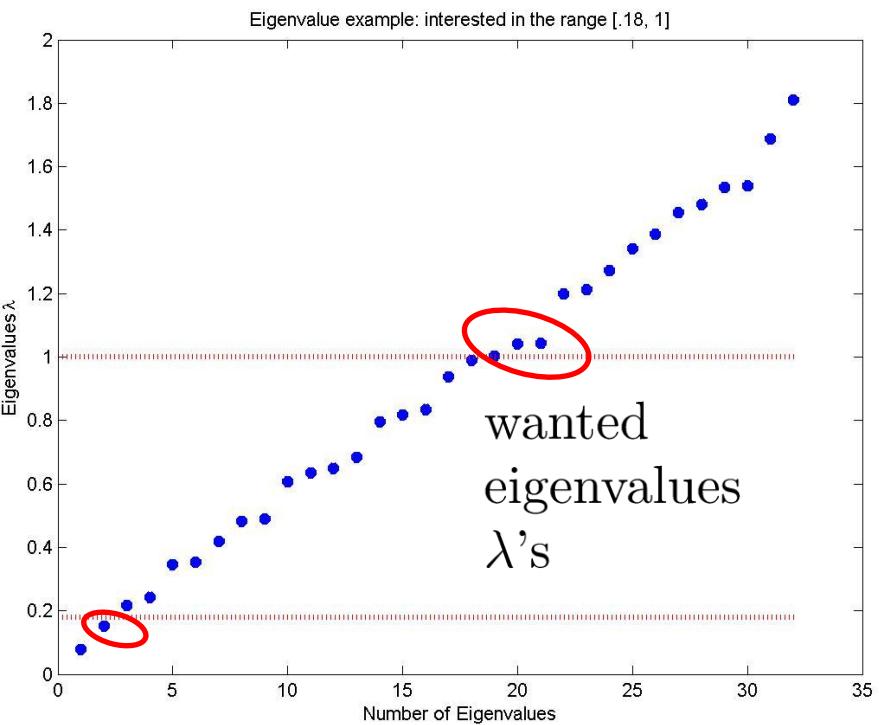


- 16 eigenvalues in search interval

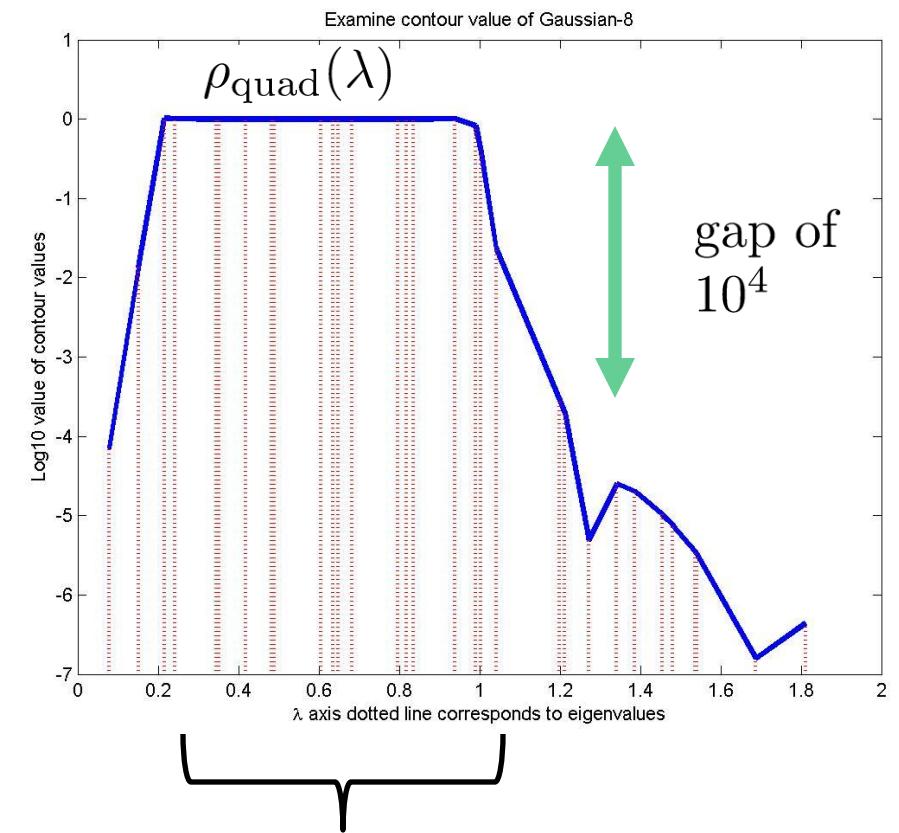
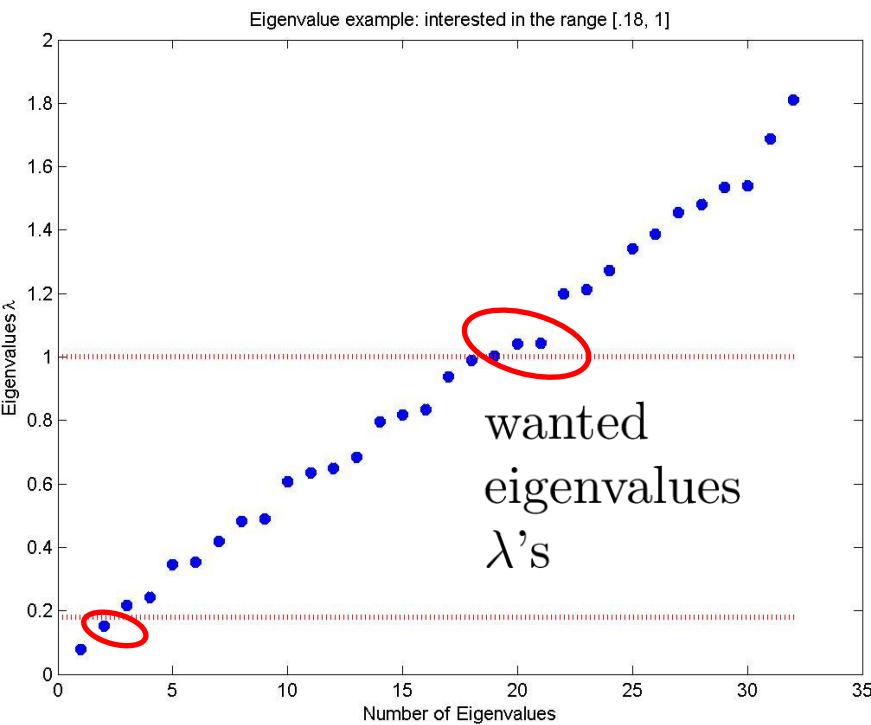


*Example from an actual application*

- 16 eigenvalues in search interval
- note  $\rho(\lambda_{20}) \approx 1$  and  $|\rho(\lambda_{21})| \approx 10^{-4}$
- As long as  $p$  is chosen  $\geq 20$

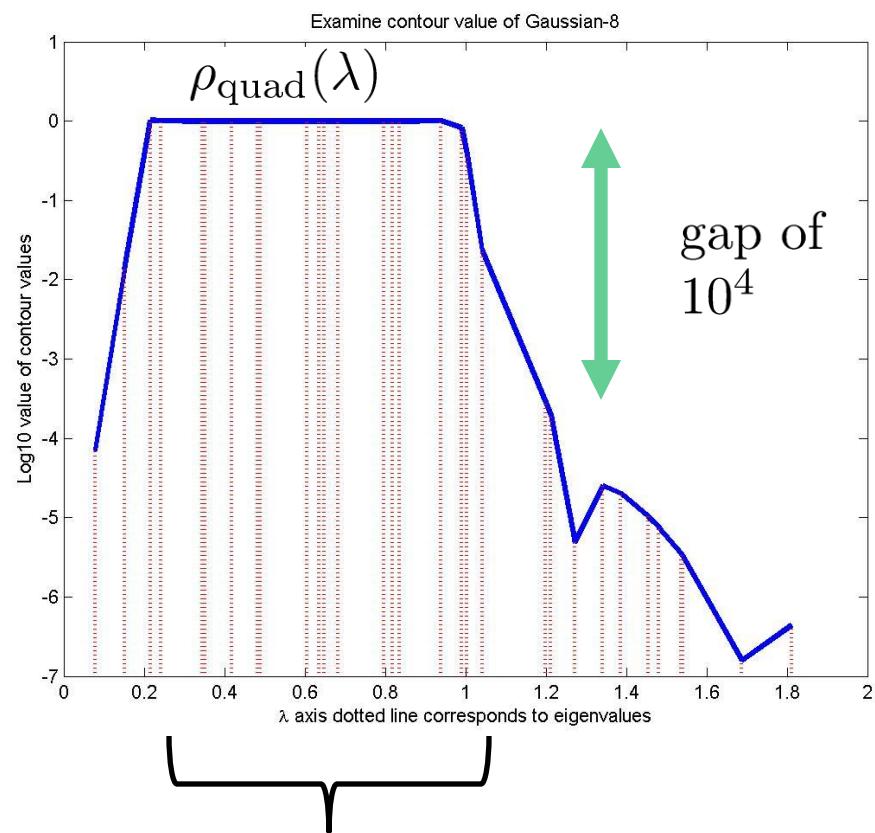
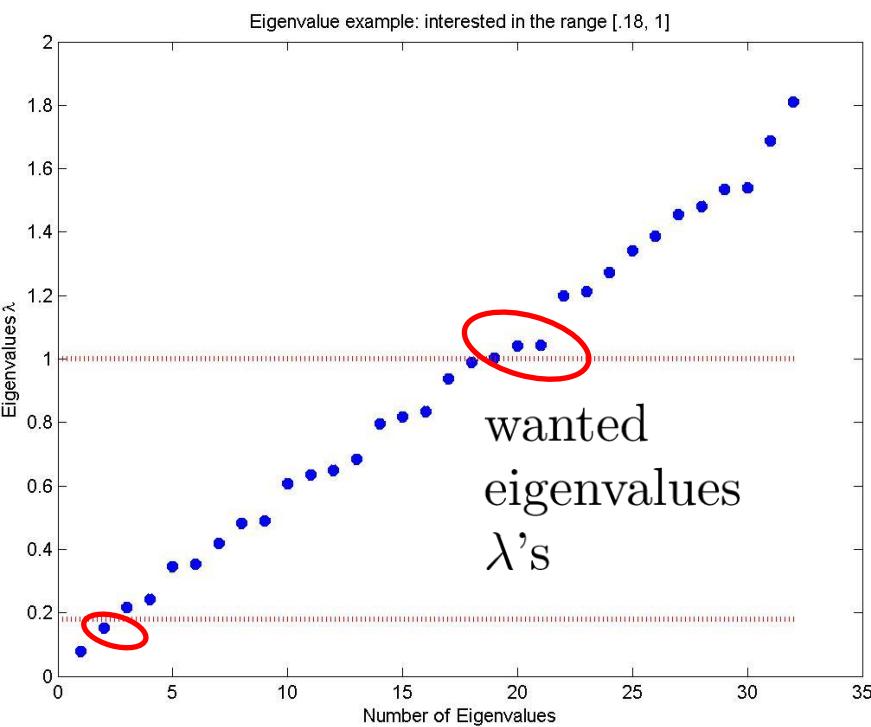


- 16 eigenvalues in search interval
- note  $\rho(\lambda_{20}) \approx 1$  and  $|\rho(\lambda_{21})| \approx 10^{-4}$
- As long as  $p$  is chosen  $\geq 20$
- convergence rate  $\approx 4$  digits/iteration
- Also, we will capture more than the target space

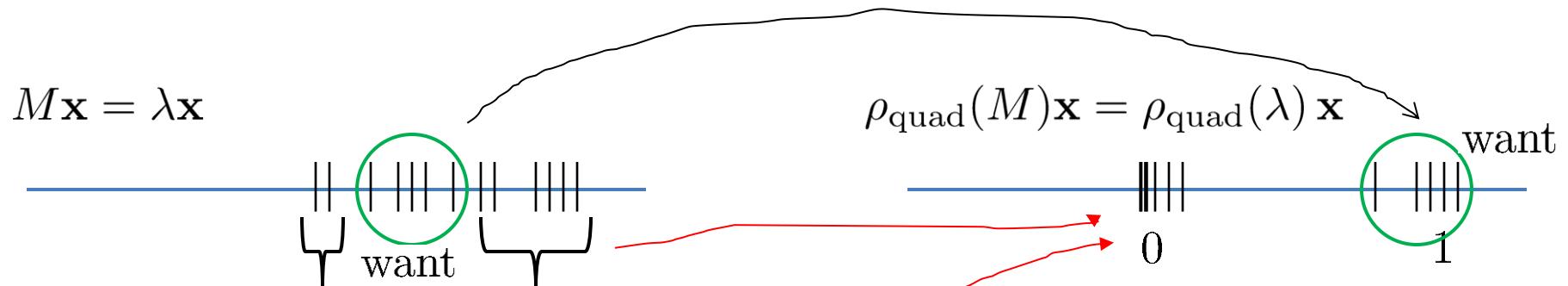


wanted eigenvalues  $\lambda$ 's

- If  $p < 20$ ,  $|\nu_{p+1}/\nu_i| \approx 1$  for  $i = 1, 2, \dots, p$ .
- Iterations will almost surely fail to converge!



# FEAST as subspace Iteration



*FEAST:*

Random  $Q_0 = [y_1, y_2, \dots, y_p]$ ,  $p \ll n$   
Loop  $k = 1, 2, 3 \dots$

$$Y_k \leftarrow \rho_{\text{quad}}(M) Q_{k-1}$$

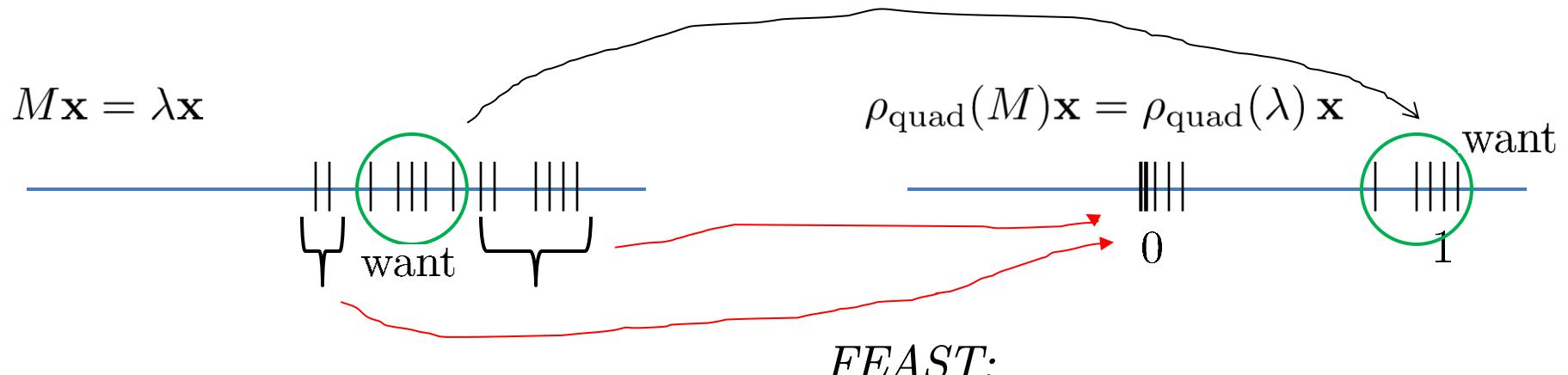
$$Q_k \leftarrow \text{orthonormalize}(Y_k)$$

$$k \leftarrow k + 1$$

End Loop:

$Q_k^T M Q_k$  captures WANT, **FAST!**

# FEAST as subspace Iteration



We know:  $\mathcal{Q}_k$  captures the  $\mathbf{x}_i$ :  
distance( $\mathbf{x}_i, \mathcal{Q}_k$ )  $\rightarrow 0$   
for  $i = 1, 2, \dots, m$ ,  $m_\lambda \leq m \leq p$

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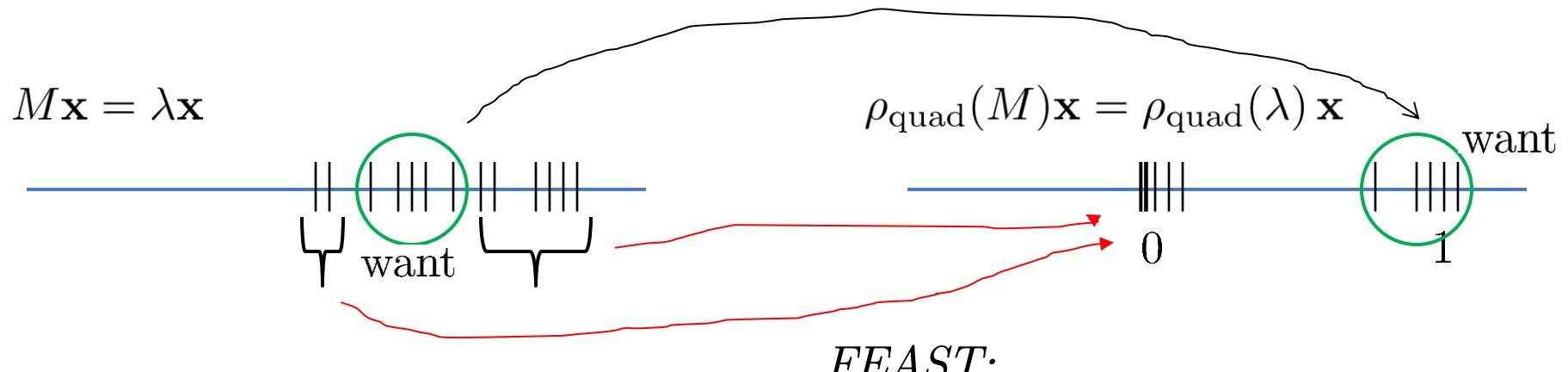
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$m_\lambda$  is the  
 exact # of eigenvalues  
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But still need to know how to  
 actually obtain  $\mathbf{x}_i$  and  $\lambda_i$

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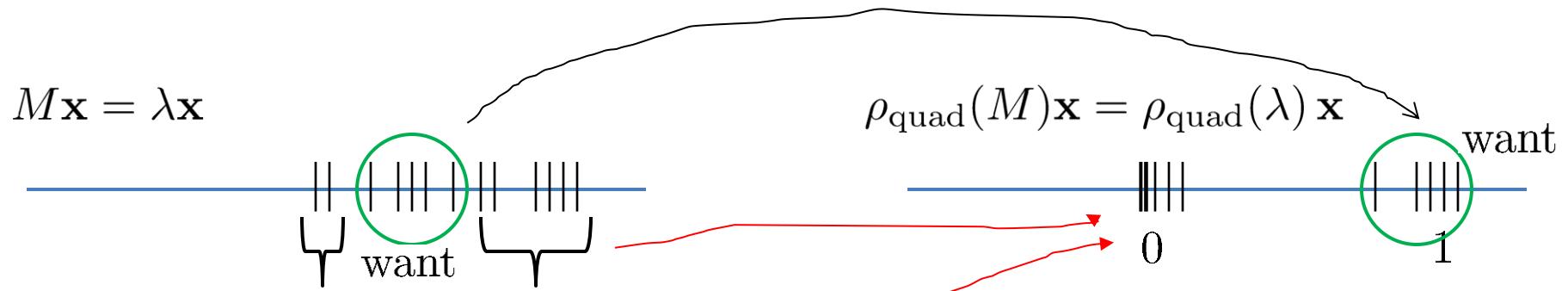
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## FEAST for Hermitian Problems

- FEAST as filtered subspace iteration for standard Hermitian eigenproblem
- The approximate spectral projector filter
- Convergence analysis of filtered subspace iteration
- FEAST for generalized Hermitian problem

# Convergence analysis



We know:  $\mathcal{Q}_k$  captures the  $\mathbf{x}_i$ :  
distance( $\mathbf{x}_i, \mathcal{Q}_k$ )  $\rightarrow 0$   
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$m_\lambda$  is the  
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But still need to know how to  
actually obtain  $x_i$  and  $\lambda_i$

Examine  
more closely

*FEAST:*

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End Loop:

$Q_k^T M Q_k$  captures WANT, FAST!

# Structure of Subspace

Let  $Q = [q_1, q_2, \dots, q_m, q_{m+1}, \dots, q_p]$  be orthonormal from iteration

orthogonal change of basis

$W = [w_1, w_2, \dots, w_m, w_{m+1}, \dots, w_p]$  orthonormal

very close

$X = [x_1, x_2, \dots, x_m, x_{m+1}, \dots, x_p, x_{p+1}, \dots, x_n]$  orthonormal

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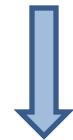
$X = [x_1, x_2, \dots, x_m, x_{m+1}, \dots, x_p, x_{p+1}, \dots, x_n]$  orthonormal

$$X^H W = \begin{array}{c} n \\ \uparrow \\ \left[ \begin{array}{c|c} I_m & \mathbf{0} \\ \hline \mathbf{0} & G \end{array} \right] \\ \downarrow \\ p \end{array} + \Delta$$

$$G^H G = I_{p-m}, \quad \|\Delta\| = O(\epsilon)$$

# Structure of Subspace

Let  $Q = [q_1, q_2, \dots, q_m, q_{m+1}, \dots, q_p]$  be orthonormal from iteration



orthogonal change of basis

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$$\text{eig}(Q^H M Q) = \text{eig}(W^H M W)$$

$$M = X \Lambda X^H$$

$$X^H W = \begin{array}{c} n \\ \uparrow \end{array} \begin{bmatrix} I_m & \mathbf{0} \\ \mathbf{0} & G \end{bmatrix} + \Delta$$

$\xleftarrow[p]{}$

$$W^H M W = (W^H X) \Lambda (X^H W)$$

$$= \begin{array}{c} p \\ \uparrow \end{array} \begin{bmatrix} \Lambda_m & \mathbf{0} \\ \mathbf{0} & S \end{bmatrix} + \Delta'$$

$\xleftarrow[p]{}$

$$S = G^H \Lambda_{n-m} G \quad \|\Delta'\| = O(\epsilon)$$

$$G^H G = I_{p-m}, \quad \|\Delta\| = O(\epsilon)$$

# Structure of Subspace

Let  $Q = [q_1, q_2, \dots, q_m, q_{m+1}, \dots, q_p]$  be orthonormal from iteration

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$$W^H M W = (W^H X) \Lambda (X^H W)$$

$$= \begin{array}{c|c} \begin{matrix} \Lambda_m \\ \vdots \\ O \end{matrix} & \begin{matrix} O \\ \vdots \\ S \end{matrix} \end{array} + \Delta'$$

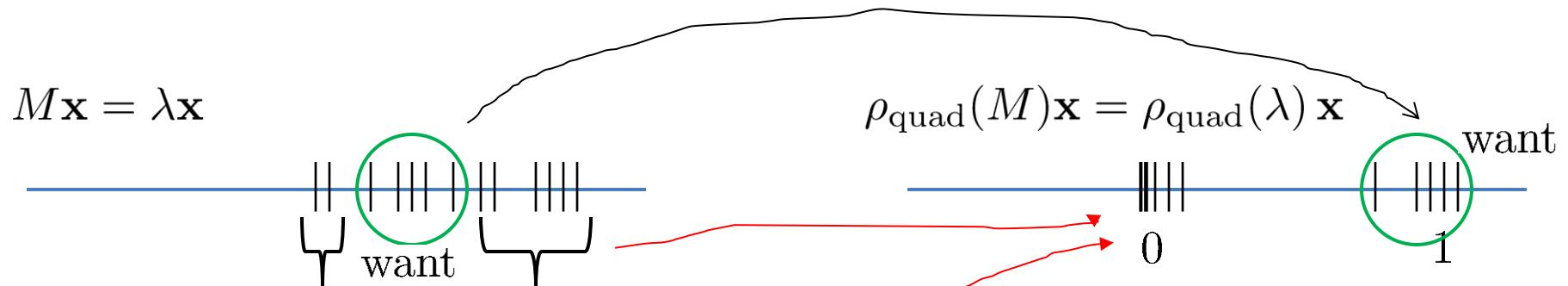
$p$        $p$

So  $m$  eigenvalues of  $Q^H A Q$  close to targets

And the remaining  $p - m$  between min/max of remaining  $n - m$  eigenvalues

$$S = G^H \Lambda_{n-m} G \quad \| \Delta' \| = O(\epsilon)$$

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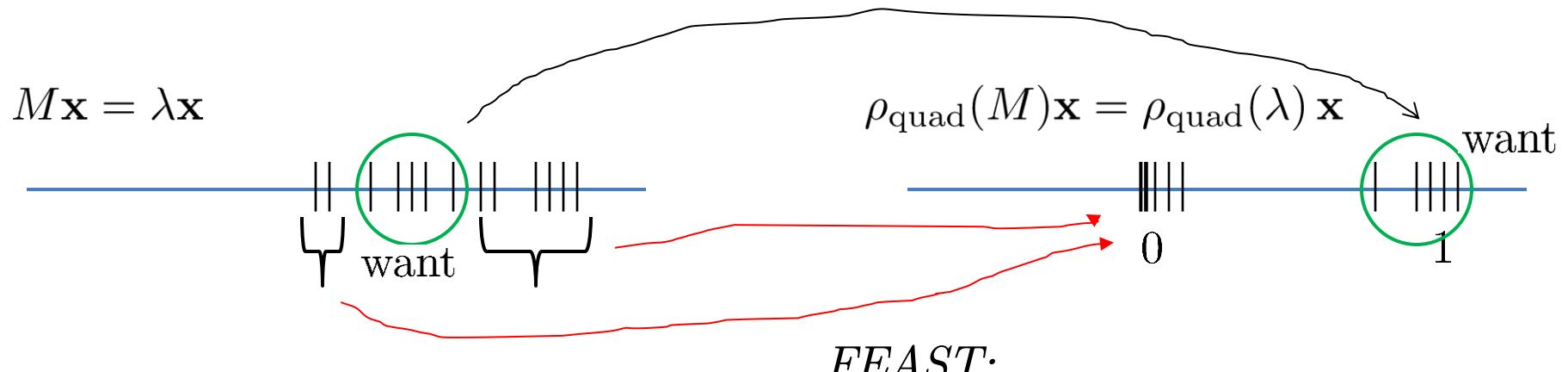
$$Q_k \leftarrow \text{orthonormalize}(Y_k)$$

$$k \leftarrow k + 1$$

End Loop:

$Q_k^T M Q_k$  captures WANT, **FAST!**

# FEAST as subspace Iteration



To orthonormalize, one can

1. Form  $A_p \leftarrow Y_k^H M Y_k$ ,  $B_p \leftarrow Y_k^H Y_k$
2. Solve GHEP  $A_p V = B_p V \Lambda'$
3.  $Q_k \leftarrow Y_k V$

Random  $Q_0 = [y_1, y_2, \dots, y_p]$ ,  $p \ll n$   
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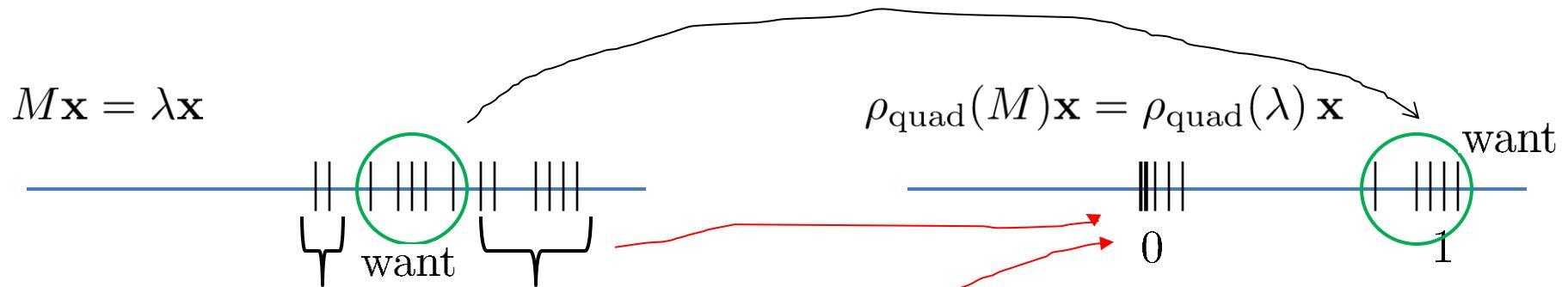
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$$A_p \leftarrow Y_k^H M Y_k, B_p \leftarrow Y_k^H Y_k$$

$$\text{Solve GHEP } A_p V = B_p V \Lambda'$$

$$Q_k \leftarrow Y_k V$$

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End Loop:

# FEAST as subspace Iteration

Standard eigenvalue problem

$$A\mathbf{x} = \lambda\mathbf{x}, A^H = A$$

$$A = X\Lambda X^H, X^H X = I$$

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Solve GHEP  $A_p V = B_p V \Lambda'$

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Standard eigenvalue problem  
 $A\mathbf{x} = \lambda\mathbf{x}$ ,  $A^H = A$

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Generalized eigenvalue problem  
 $A\mathbf{x} = \lambda B\mathbf{x}$ ,  $A, B$  Hermitian  
 $B$  positive definite  
 $B^{-1}A = X\Lambda X^{-1}, \quad X^H BX = I$

*FEAST:*

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Loop  $k = 1, 2, 3\dots$

$$Y_k \leftarrow \rho_{\text{quad}}(A) Q_{k-1}$$

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Generalized eigenvalue problem

$$A\mathbf{x} = \lambda B\mathbf{x}, \quad A, B \text{ Hermitian}$$

$B$  positive definite

$$B^{-1}A = X\Lambda X^{-1}, \quad X^H B X = I$$

$$\rho(B^{-1}A) = X\rho(\Lambda)X^{-1}$$

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$$\rho_{\text{quad}}(B^{-1}A)$$

$$= \sum_{k=1}^q w_k (z_k I - B^{-1}A)^{-1}$$

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$$\rho(B^{-1}A) = X\rho(\Lambda)X^{-1}$$

$$\rho_{\text{quad}}(B^{-1}A)$$

$$= \sum_{k=1}^q w_k (z_k I - B^{-1}A)^{-1}$$

$$= \sum_{k=1}^q w_k (z_k B - A)^{-1} B$$

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Loop  $k = 1, 2, 3\dots$

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$$A_p \leftarrow Y_k^H A Y_k, \quad B_p \leftarrow Y_k^H B Y_k$$

Solve GHEP  $A_p V = B_p V \Lambda'$

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