

High-Level Outline

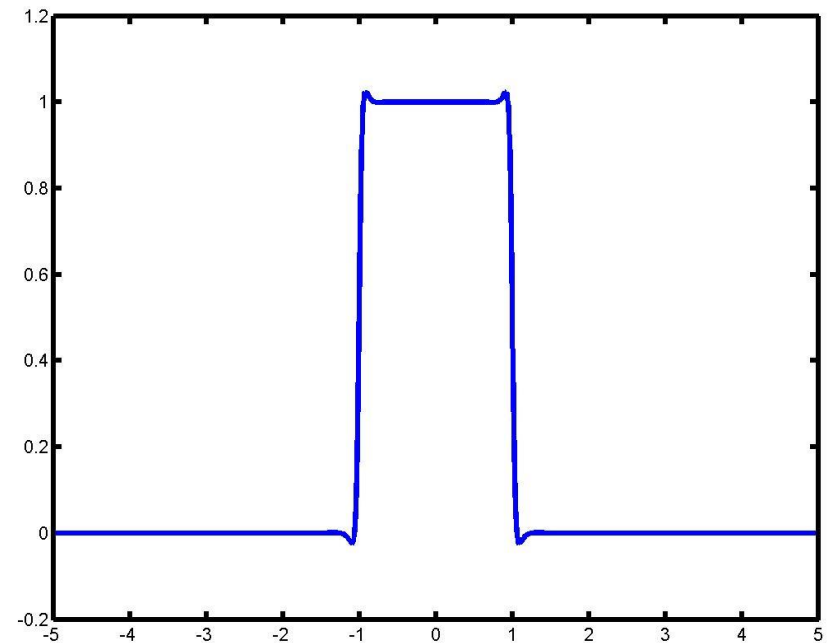
- FEAST as filtered subspace iteration, for Hermitian problems
- FEAST for non-Hermitian problems
- SS method as filtered Krylov subspace method
- Function approximation and computer arithmetic studies related to the filter

Some Function Approximation Connections

The filter function $\rho(\lambda)$ plays a crucial role in convergence, and convergence rate

Consider reference case of $\mathcal{I} = [-1, 1]$.

We need $\rho(\lambda)$ big on \mathcal{I}
and small on all large $|\lambda|$

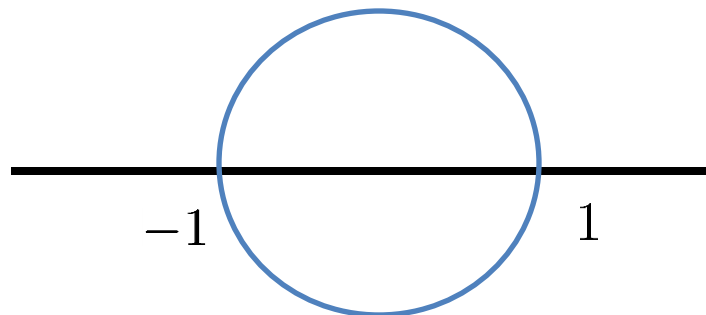


Let's examine the construction of a Gaussian based $\rho(\lambda)$ in detail

$$\pi(\mu) = \frac{1}{2\pi\iota} \oint \frac{1}{z - \mu} dz$$

parametrize: for $-1 \leq t \leq 3$

$$\phi(t) = e^{\iota \frac{\pi}{2}(1+t)}, \quad \phi'(t) = \iota \frac{\pi}{2} \phi(t)$$



$$\begin{aligned} \pi(\mu) &= \frac{1}{2\pi\iota} \int_{-1}^3 \frac{\phi'(t)}{\phi(t) - \mu} dt \\ &= \frac{1}{2\pi\iota} \int_{-1}^1 \left[\frac{\phi'(t)}{\phi(t) - \mu} - \frac{\overline{\phi'(t)}}{\overline{\phi(t)} - \mu} \right] dt \\ &= \frac{1}{4} \int_{-1}^1 \left[\frac{\phi(t)}{\phi(t) - \mu} - \frac{\overline{\phi(t)}}{\overline{\phi(t)} - \mu} \right] dt \end{aligned}$$

For real μ

$$\pi(\mu) = \frac{1}{2} \int_{-1}^1 \operatorname{Re} \left(\frac{\phi(t)}{\phi(t) - \mu} \right) dt$$

For Gauss-Legendre rule, (w_k, t_k) , $k = 1, 2, \dots, q$,

$$\begin{aligned}\pi(\mu) \approx \rho(\mu) &= \frac{1}{2} \sum_{k=1}^q w_k \operatorname{Re} \left(\frac{\phi(t_k)}{\phi(t_k) - \mu} \right) \\ &= \frac{1}{2} \sum_{k=1}^q w_k \frac{1 + \mu s_k}{1 + 2\mu s_k + \mu^2}, \quad s_k = \sin(\pi t_k/2).\end{aligned}$$

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While for a finite interval $[-A, A]$ we can examine $\rho(\mu)$ numerically,

we NEED a better justification for $|\mu| > A$.

$$\begin{aligned}
\pi(\mu) &= \frac{1}{2} \int_{-1}^1 \operatorname{Re} \left(\frac{\phi(t)}{\phi(t) - \mu} \right) dt \\
&= \frac{1}{2} \int_{-1}^1 f_\mu(t) dt, \quad f_\mu(t) = \frac{1}{2} \frac{1 + \mu \sin(\mu t/2)}{1 + 2\mu \sin(\mu t/2) + \mu^2}
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Standard theory on Gaussian-Legendra quadrature says:

$$\left| \int_{-1}^1 f_\mu(t) dt - \rho(\mu) \right| = \frac{2^{2q+1} (q!)^4}{(2q+1)((2q!))^2} \left| \frac{f_\mu^{(2q)}(t_0)}{(2q)!} \right|$$

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But $\int_{-1}^1 f_\mu(t) dt = 0$ for $|\mu| > 1$, and thus

$$\left| \int_{-1}^1 f_\mu(t) dt - \rho(\mu) \right| = |\rho(\mu)|, \quad \text{for } |\mu| > 1$$

Recap: for any $\mu > 1$,

$$|\rho(\mu)| = \frac{2^{2q+1}(q!)^4}{(2q+1)((2q!))^2} \left| \frac{f_\mu^{(2q)}(t_0)}{(2q)!} \right|, \quad \text{for some } t_0 \in (-1, 1)$$

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One can construct a function $\xi_q(\mu)$ such that

- $\xi_q(\mu) \geq \frac{2^{2q+1}(q!)^4}{(2q+1)((2q!))^2} \max_{t \in [-1, 1]} \left| \frac{f_\mu^{(2q)}(t)}{(2q)!} \right|$
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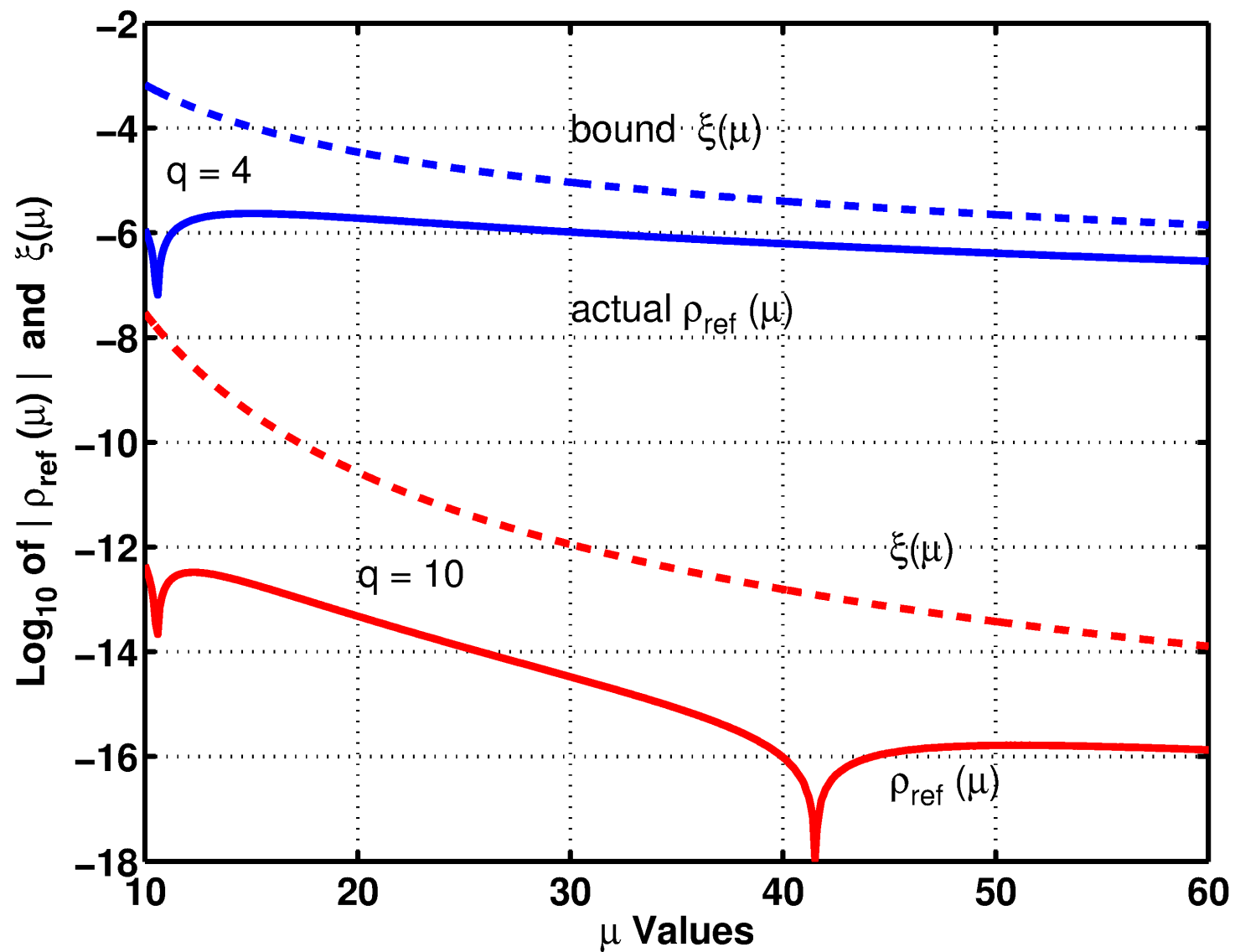
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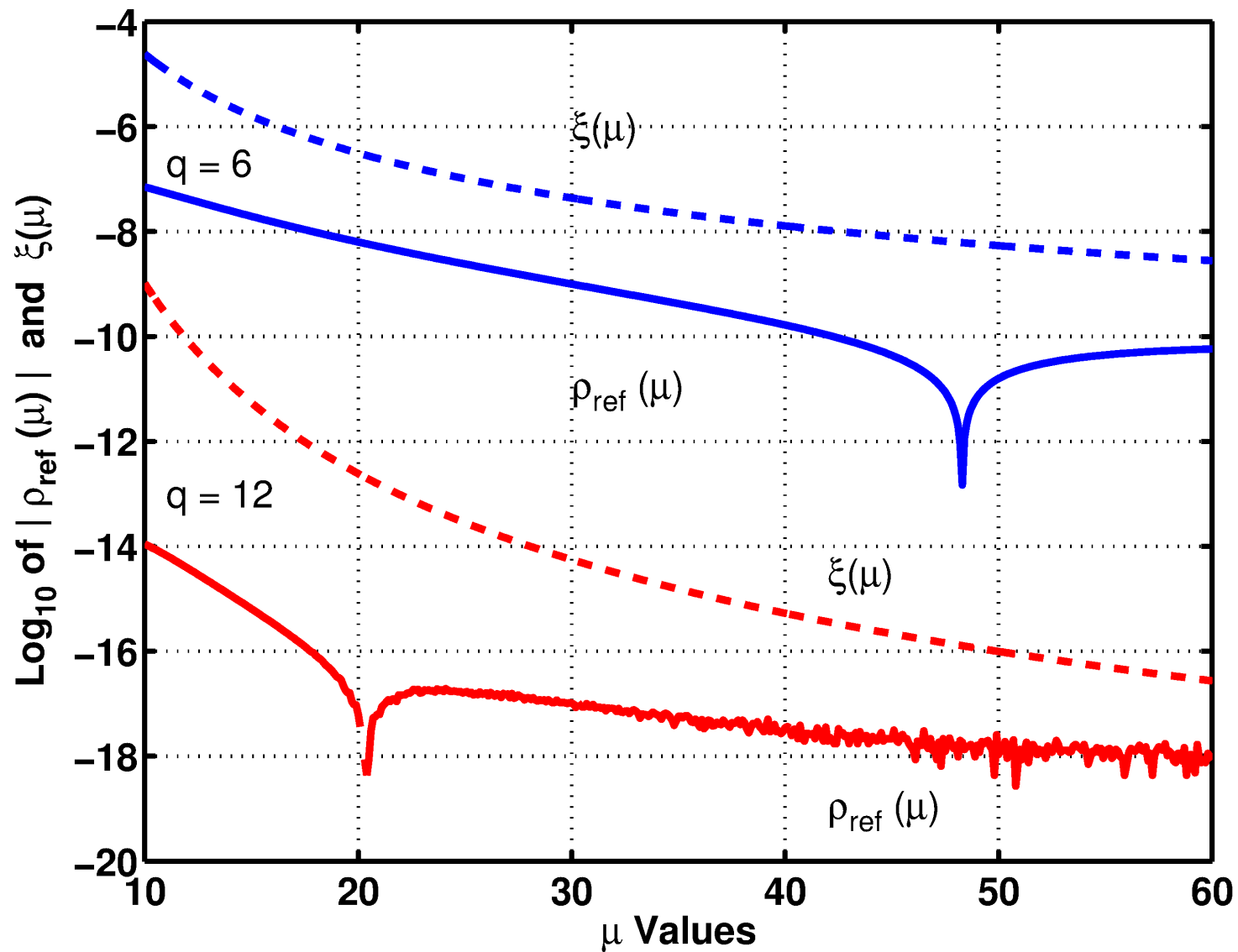
Thus, evaluation $\xi_q(A)$ at a single point A

gives a bound on $|\rho(\mu)|$ for all $\mu \geq A$.

Bound $\xi(\mu)$ vs. Actual $|\rho_{\text{ref}}(\mu)|$, $q = 4, 10$

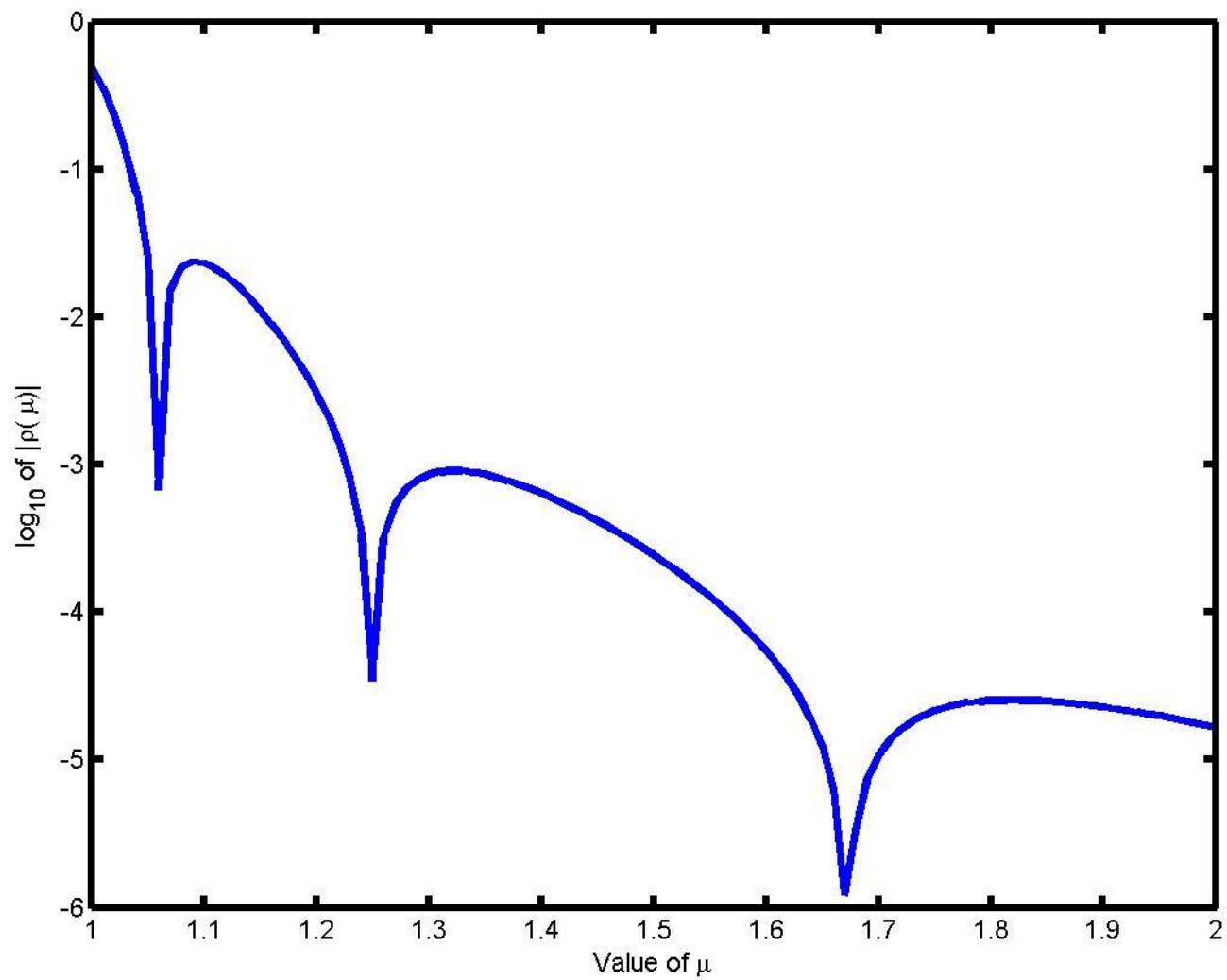


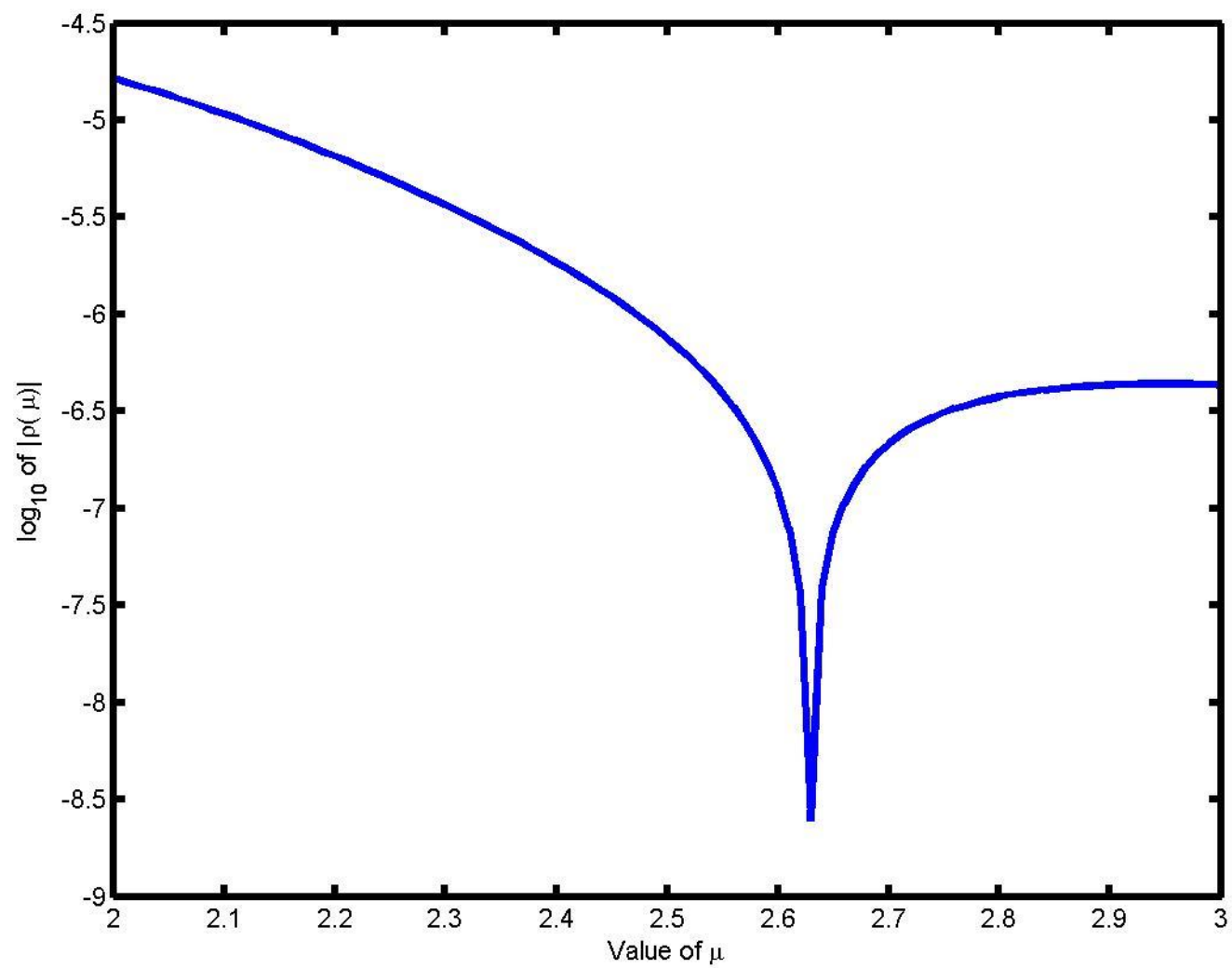
Bound $\xi(\mu)$ vs. Actual $|\rho_{\text{ref}}(\mu)|$, $q = 6, 12$

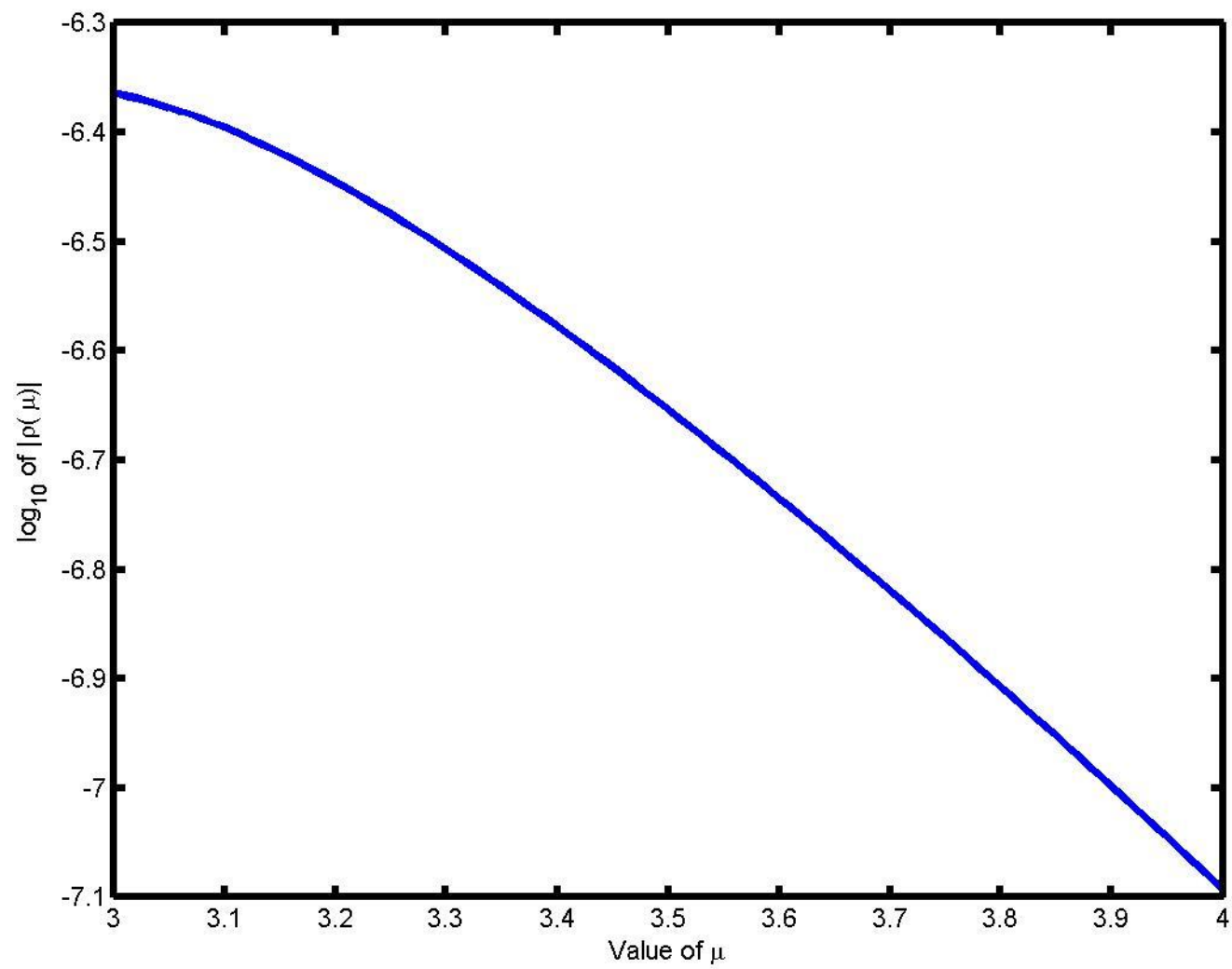


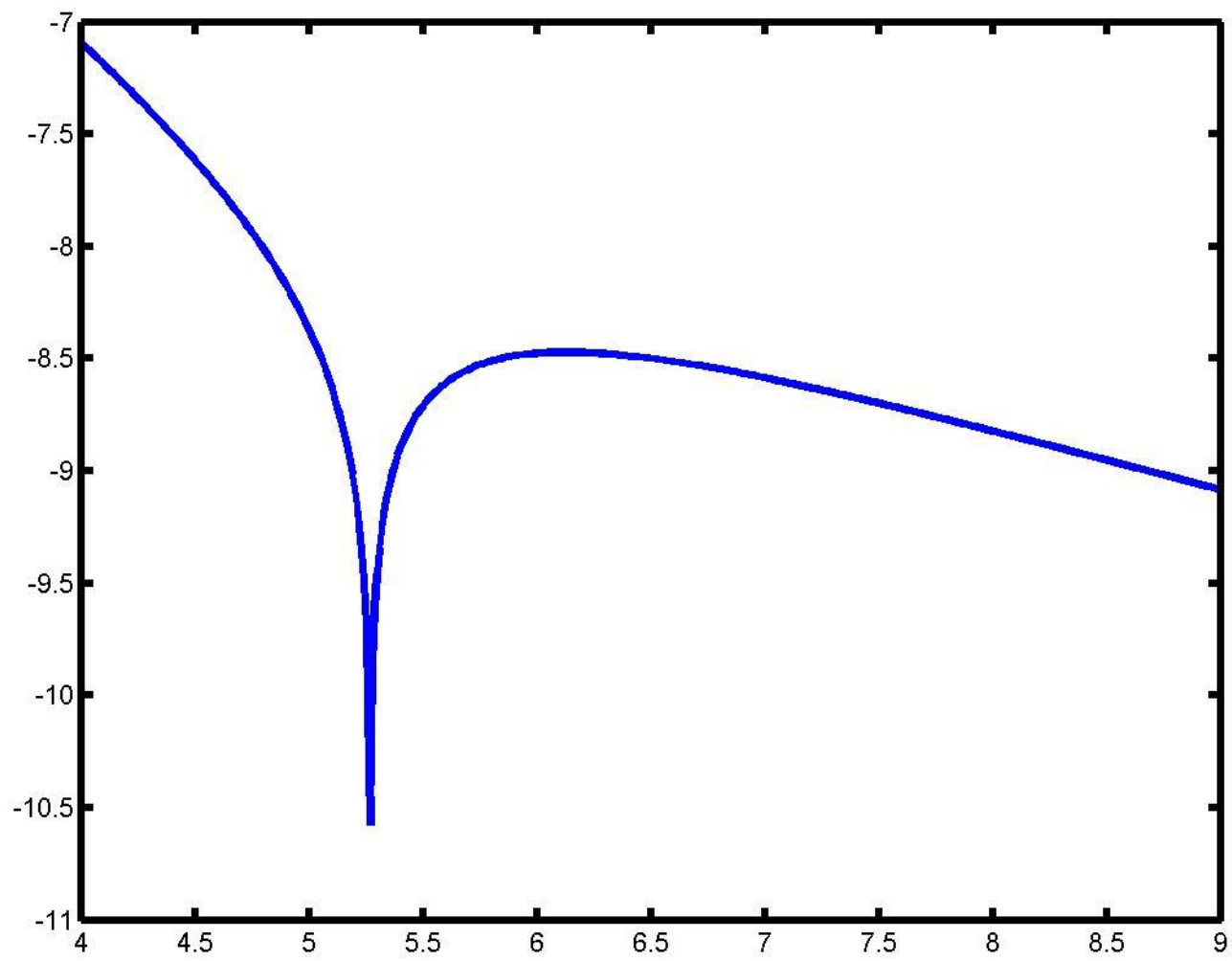
Formal-verification based method is an alternative (dormant work that can use help to revive).

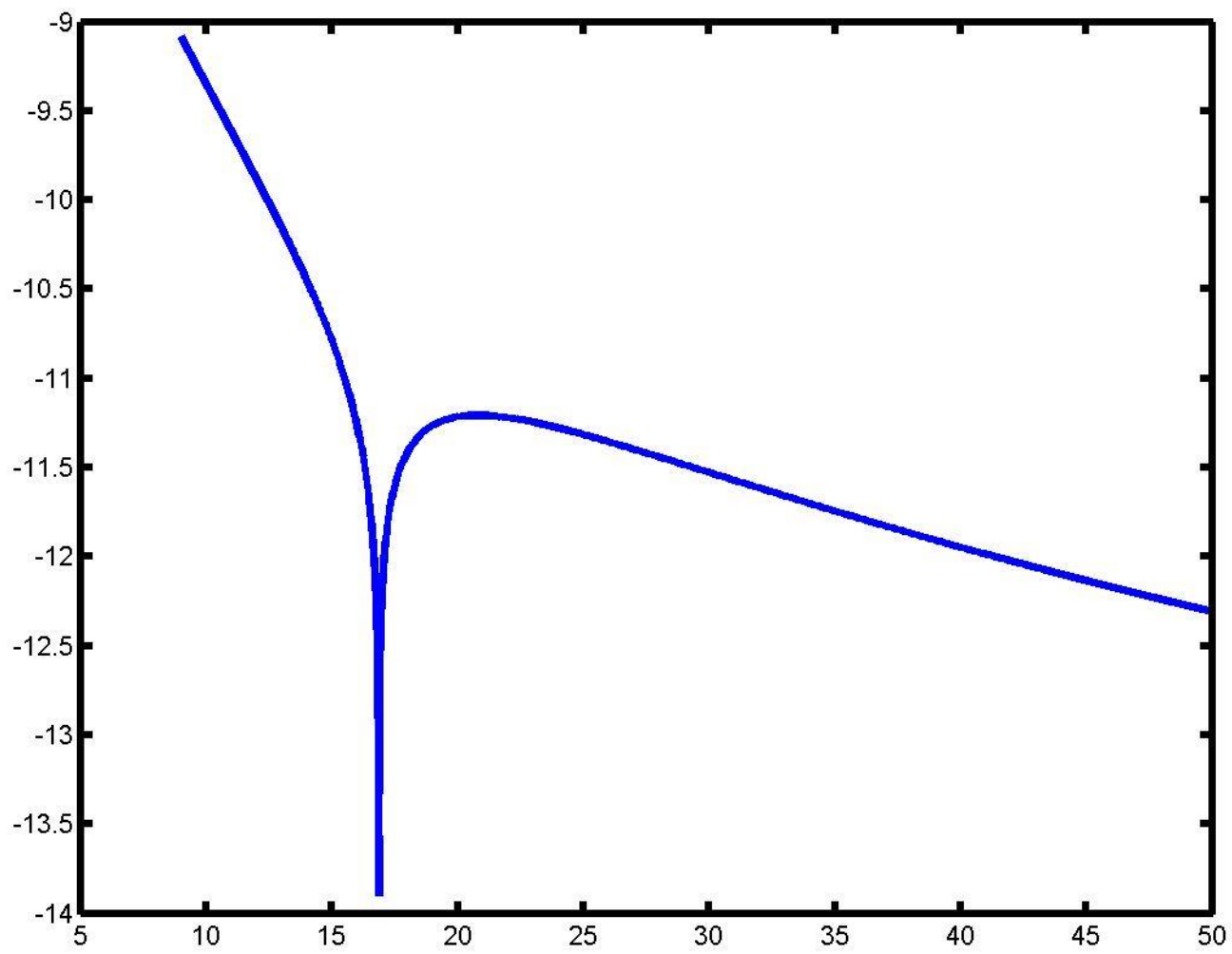
$\rho(\mu)$ is a rational function, no poles. Can use FV to enumerate all local min/max.









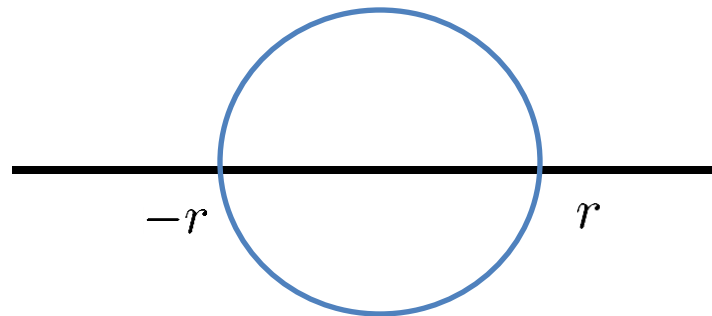


Some Computer Arithmetic Connections

For Gauss-Legendra rule, (w_k, t_k) , $k = 1, 2, \dots, q$,

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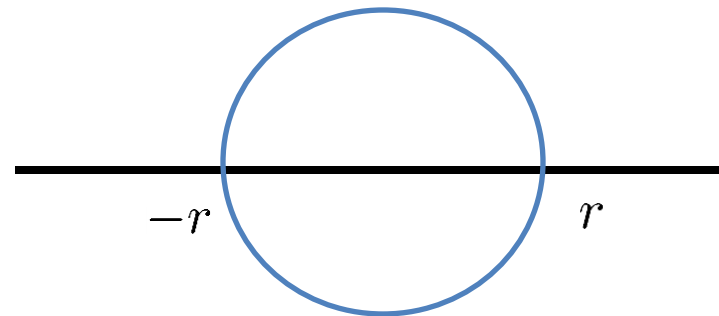
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Let (λ, \mathbf{x}) be an eigenpair for A : $A\mathbf{x} = \lambda\mathbf{x}$

If computed exactly, $\rho(A)\mathbf{x} = \rho(\lambda)\mathbf{x}$



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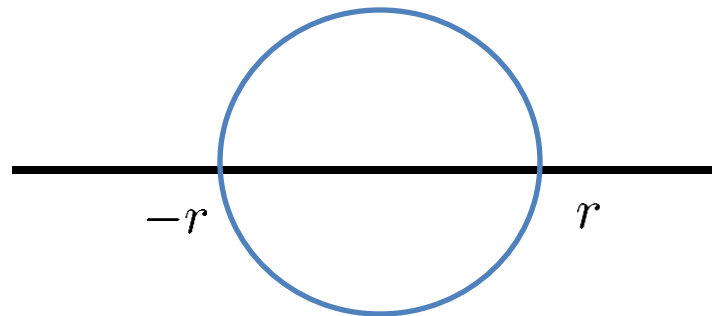
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But solutions of the linear systems are not exact.



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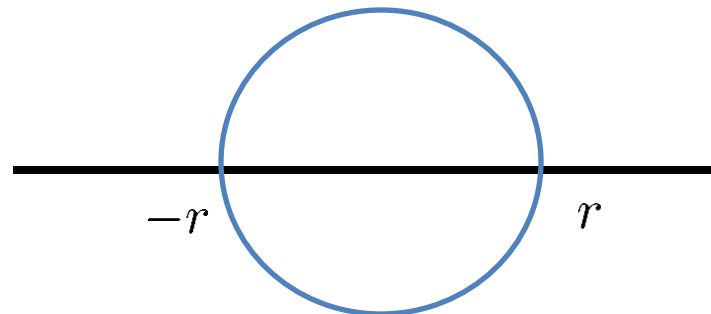
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$$\sum_{k=1}^q w_k \phi(t_k) \mathbf{x}_k \quad \text{vs} \quad \sum_{k=1}^q w_k \phi(t_k) \hat{\mathbf{x}}_k$$

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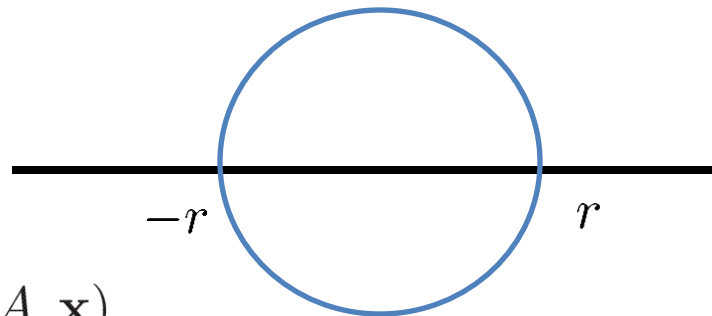
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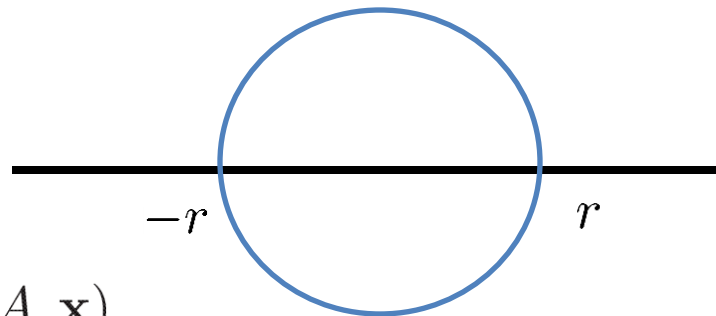
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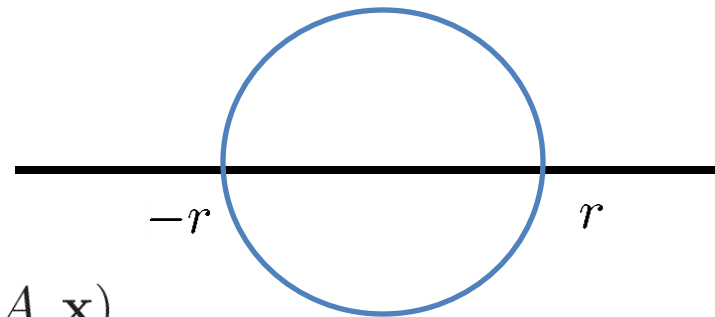
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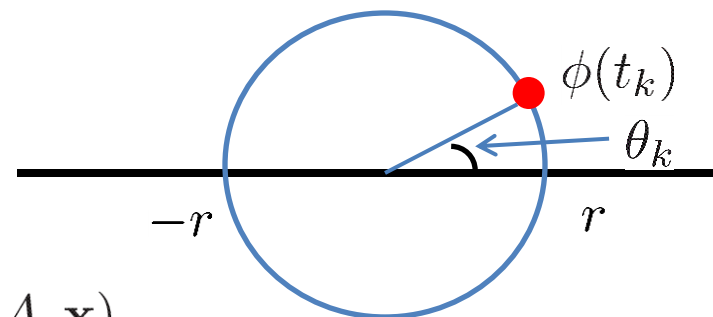
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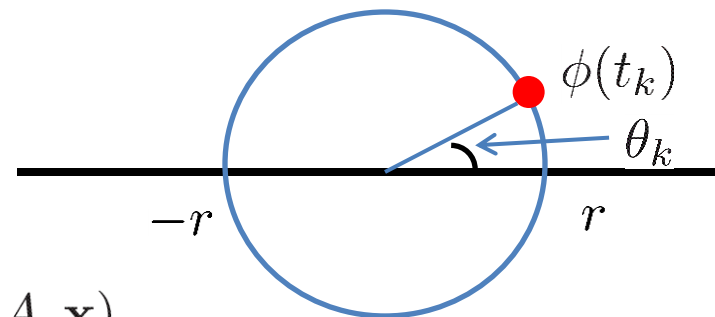
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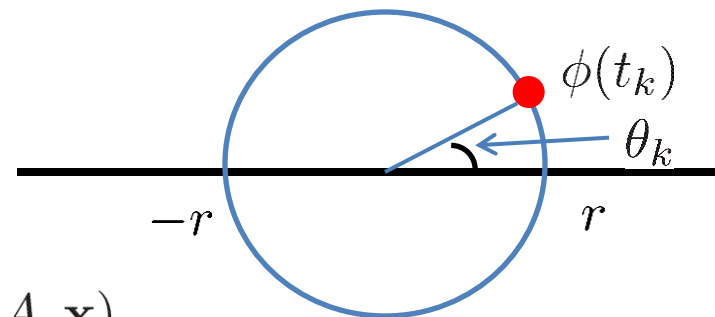
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Determined by quadrature rule.
For Gauss, 8-node, this is ≤ 60

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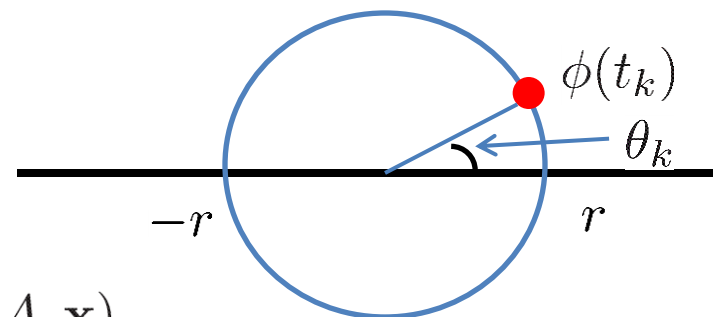
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Iterative refinement (for higher accuracy) relies critically on accurate residual:

$$\text{residual vector} = \mathbf{x} - A_k \hat{\mathbf{x}}_k = \mathbf{x} - (\phi(t_k) \hat{\mathbf{x}}_k - A_k \hat{\mathbf{x}}_k)$$

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Can use various computer arithmetic technique such as two-sum and error-free transformation (e.g. Rump's method)

Concluding Remarks

- Integral-based methods and approximate spectral projectors are very useful tools.
- They can be used in different contexts: subspace iterations, Krylov methods, spectrum estimation (not covered), and more.
- Sakurai and collaborators proposed SS method 2003; Polizzi proposed FEAST 2008.
- Tang/Polizzi published detail analysis on FEAST 2014.
- Intel Math Kernel Library has incorporated in it a FEAST-based eigensolver.
- Many problems need to be solved still; do jump in!
- Will include more references in posted material.