

Model based clustering using color and depth information

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Journée SIERRA - Méthodes et modèles adaptatifs
the 25th of March, 2014

Outline

- 1 Clustering with mixtures and BD
 - Exponential families (EF) and Bregman Divergence (BD)
 - Mixture model
 - Estimation of number of components
- 2 MBC with directional distributions
 - Directional distributions in \mathbb{R}^p
 - Mixture model and normals of surfaces
 - Results on depth images (NYU database)
- 3 MBC and RGB-D data
 - Mixture Model and RGB-D data
 - First results on NYU Database
 - Results based on aggregation of planar regions
- 4 Conclusion

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Exponential families (EF) of distributions

$$f(x|\theta) = \exp \{ \langle \theta, t(x) \rangle - F(\theta) + g(x) \}, x \in \Omega_{X_s}$$

with

- $t(x)$, the sufficient statistic,
- $\theta \in \mathcal{P}_\Theta$, with dimension D (the order of the family), the natural parameter
- $F(\cdot)$, the log-normalizer, $F(\theta) = \log \int_{\Omega_{X_s}} \exp(\langle \theta, t(x) \rangle + g(x)) dx$
- $g(\cdot)$, the carrier measure.
- $\eta = \eta(\theta) = \nabla F(\theta)$, the expectation parameters.

Examples : Gaussian, Wishart, Poisson, Rayleigh, ... laws (see [1])

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Examples : Gaussian, Wishart, Poisson, Rayleigh, ... laws (see [1])

Example: univariate Gaussian distribution

- $t(x) = (x, x^2)$, $m = (\mu, \sigma^2)$, $\theta = (\frac{\mu}{\sigma^2}, -\frac{1}{2\sigma^2}) = (\theta_1, \theta_2)$
- $F(\theta) = \left(-\frac{\theta_1^2}{4\theta_2} + \frac{1}{2} \log \left(-\frac{\pi}{\theta_2} \right) \right)$
- $g(x) = 0$
- $\eta = (\eta_1, \eta_2) = \left(-\frac{\theta_1}{2\theta_2}, -\frac{1}{2\theta_2} + \frac{\theta_1^2}{4\theta_2^2} \right) = (\mu, \sigma^2 + \mu^2)$

EF and Bregman Divergence (BD) (see [1] and [2])

$$f(x|\theta) = \exp\{-d_{F^*}(t(x), \eta)\} b_{F^*}(t(x)), x \in \Omega_{X_s}$$

- d_{F^*} , the Bregman divergence associated with F^* , the conjugate function (Legendre dual) of F , which is a strictly convex function :

$$d_{F^*}(\eta_1, \eta_2) = F^*(\eta_1) - F^*(\eta_2) - \langle \eta_1 - \eta_2, \nabla F^*(\eta_2) \rangle = d_F(\theta_2, \theta_1)$$

- For EF, $KL(\theta_1, \theta_2) = d_{F^*}(\eta_1, \eta_2) = d_F(\theta_2, \theta_1)$
- $F^*(\eta) = \sup_{t \in \mathcal{P}_\Theta} \{\langle \eta, t \rangle - F(t)\}$
- $\theta = \theta(\eta) = \nabla F^*(\eta)$
- $b_{F^*}(t(x)) = \exp(F^*(t(x)) + g(x))$

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Example: univariate Gaussian distribution

- $F^*(\eta) = -\frac{1}{2} \log(\eta_1^2 - \eta_2) + C$ avec $\eta = (\eta_1, \eta_2) = (\mu, \sigma^2 + \mu^2)$

Bregman divergence and information geometry [1, 2, 3]

- For different convex functions:
 - Quadratic form distances (Euclidean, Mahalanobis, ...) which are the only symmetric Bregman divergences.
 - Kullback-Leibler divergence (KL),
 - ...
- For two members, θ_1 and θ_2 , of the same exponential family :

$$KL(\theta_1, \theta_2) = \int f(x|\theta_1) \log \left(\frac{f(x|\theta_1)}{f(x|\theta_2)} \right) dx = d_F(\theta_2, \theta_1) = d_{F^*}(\eta_1, \eta_2)$$

- Meaning of Kullback-Leibler divergence:
 - Relative entropy between $f(x|\theta_1)$ and $f(x|\theta_2)$
 - Cencov [4] proved that the only Riemannian metric that “makes sense” for statistical manifolds is the Fisher information metric.
 - When θ_2 is closed to θ_1

$$2KL(\theta_1, \theta_2) = \|\theta_1 - \theta_2\|_I^2 (1 + o(1)),$$

with $\|\cdot\|_I$ the norm based on the Fisher information metric.

BD and information geometry [3]

- Computation of centroids for K parametric distributions:
 - left-sided centroid (for natural parameters)

$$\theta_L = \arg \min_{\theta \in \mathcal{P}_\Theta} \frac{1}{K} \sum_{k=1}^K d_F(\theta, \theta_k) = \nabla F^* \left(\frac{\sum_{k=1}^K \alpha_k \nabla F(\theta_k)}{\sum_{k=1}^K \alpha_k} \right)$$

- right-sided centroid (for natural parameters)

$$\theta_R = \arg \min_{\theta \in \mathcal{P}_\Theta} \frac{1}{K} \sum_{k=1}^K d_F(\theta_k, \theta) = \frac{\sum_{k=1}^K \alpha_k \theta_k}{\sum_{k=1}^K \alpha_k}$$

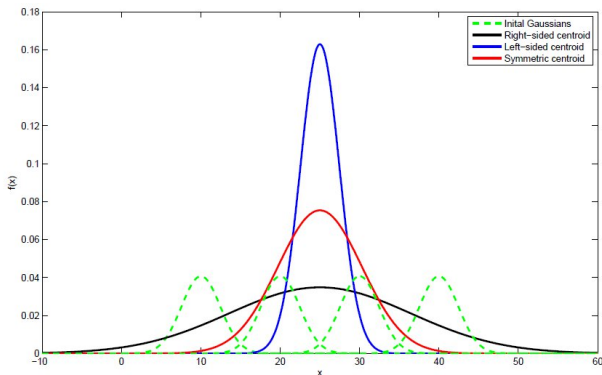
- symmetric centroid (belongs to the geodesic link between θ_L and θ_R)

$$\theta_S = \arg \min_{\theta \in \mathcal{P}_\Theta} \frac{1}{K} \sum_{k=1}^K \frac{1}{2} (d_F(\theta, \theta_k) + d_F(\theta_k, \theta))$$

Exponential families (EF) and Bregman Divergence (BD)

Computation of Bregman centroids

Example in a Gaussian univariate case [5]



- Initial set contains 4 univariate Gaussians $\sigma^2 = 6$
- Right-sided centroid
- Left-sided centroid
- Symmetric centroid

Mixture model

- $x = \{x_s\}_{s \in \Lambda}$, samples of **i.i.d.** (independently and identically distributed) random vectors with dimension p .

$$f(x) = \prod_{s \in \Lambda} f(x_s)$$

- **General hypothesis:** the distribution of each sample is a mixture with K components.

$$f(x_s) = f_K(x_s) = \sum_{k \in K} f(x_s, k) \quad (1)$$

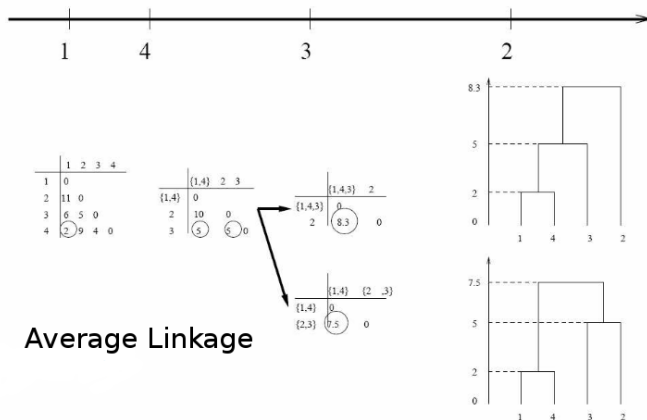
$$= \sum_{k \in K} f(x_s | \theta_k) P(k) \quad (2)$$

- ✚ K number of components, **unknown a priori**.
- ✚ $\alpha_k = P(k)$ “a priori” probability of k th component,
 $\sum_{k=1}^K \alpha_k = 1$.
- ✚ θ_k natural parameters of component k and
 $\Theta_K = \{\alpha_k, \theta_k\}_{k=1, \dots, K}$.

Approach developped in [1, 2, 5]

- Initialization:
 - Fix $K = K_{\max}$, the maximum number of components.
 - Bregman hard clustering (kmeans based on Bregman divergence)
 - First estimation of $\{\alpha_{l,K_{\max}}, \theta_{l,K_{\max}}\}_{l=1,\dots,K_{\max}}$.
- Bregman soft clustering (An EM type algorithm based on Bregman divergence)
 - Final estimation of $\{\alpha_{l,K_{\max}}, \theta_{l,K_{\max}}\}_{l=1,\dots,K_{\max}}$.
- Bregman hierarchical clustering (**fast simplification process**)
 - Choice of the Bregman divergence and associated cendroid
 - Choice of the linkage criterion
 - **Estimation of K (\hat{K} using IC) and $\{\alpha_{l,\hat{K}}, \theta_{l,\hat{K}}\}_{l=1,\dots,\hat{K}}$.**

Hierarchical clustering



Average Linkage

IC and principle of parsimony

✚ A formulation justified by theory of information.

$$IC(K) = \underbrace{-2 \log f(x | \hat{\Theta}_K^{ML}, K)}_{\text{Representation}} + \underbrace{p(|\Theta_K|, N)}_{\text{Complexity}}$$

$$\hat{K}^{IC} = \arg \min_K IC(K)$$

ML for Maximum Likelihood. N is the number of samples.

IC and principle of parsimony

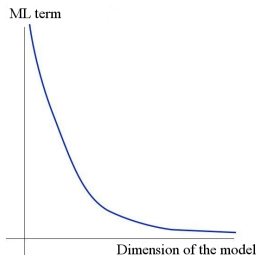
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✦ Typical curves obtained in the case of nested models:



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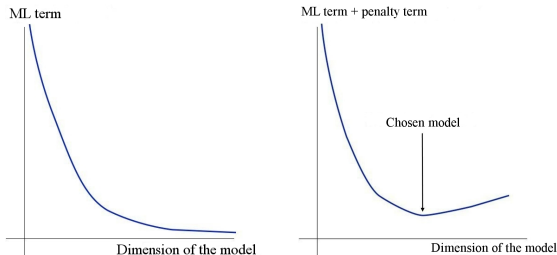
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ML for Maximum Likelihood. N is the number of samples.

- ✚ Typical curves obtained in the case of nested models:



Criteria for the estimation of K (see [6])

✚ “Classical” form:

$$IC(K) = -2 \log \left(f(x | \hat{\theta}_K) \right) + C(N) P(K)$$

$P(K)$ number of free parameters.

◇ AIC (Akaike Information Criterion, 1974) : $C(N) = 2$

derived using KL divergence

◇ BIC (Bayesian Information Criterion, Schwarz 1978) : $C(N) = \log N$

◇ ϕ_β (El Matouat, Hallin 1996) : $C(N) = N^\beta \log \log(N)$ avec $\beta = \frac{\log \log N}{\log N}$.

✚ Other forms:

◇ ICOMP (Information complexity criterion - Bozdogan 93).

◇ ICL (Integrated Completed Likelihood - Biernacki, Celeux, Govaert 2000) :
BIC + estimated mean entropy.

◇ MML (Minimum Message Length - Figueiredo, Jain 2002).

✚ IC + Piecewise Linear Regression (PLR) (see [7]).

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Von Mises-Fisher distribution

$x \in \mathbb{R}^p$ with $\|x\|_2 = 1$. Set of parameters: θ

Definition

$$f(x|\theta) = C_p(\kappa) \exp(\kappa \mu^T x)$$

$\theta = \{\kappa, \mu\}$ with κ concentration parameter and μ mean direction.

- **Von Mises distribution** for $p = 2$: $C_p(\kappa) = \frac{1}{2\pi I_0(\kappa)}$ and $\mu^T x = \cos(x - \mu)$
 $I_0(x)$ modified Bessel function of order 0.
- $p = 3$: $C_p(\kappa) = \frac{\kappa}{4\pi \sinh \kappa}$ using polar coordinates, $C_p(\kappa) = \frac{\kappa}{\sinh \kappa}$ otherwise.
- $p > 3$: $C_p(\kappa) = \frac{\kappa^{p/2-1}}{(2\pi)^{p/2} I_{p/2-1}(\kappa)}$

Applications found in electric field, geology, bioinformatics, text mining, ...

Other directional distributions

$x \in \mathbb{R}^p$ with $\|x\|_2 = 1$. Set of parameters: θ

Watson distribution

$$f(x|\theta) = M\left(\frac{1}{2}, \frac{p}{2}, \kappa\right)^{-1} \exp\left(\kappa (\mu^T x)^2\right)$$

$\theta = \{\kappa, \mu\}$ with κ concentration parameter and μ mean direction.
 $M(\cdot)$ Kummer function.

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 $M(\cdot)$ Kummer function.

Fisher-Bingham or Kent distribution ($p = 3$)

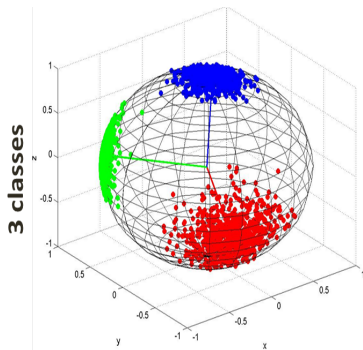
$$f(x|\theta) = c(\kappa, \beta) \exp\left(\kappa \mu_1^T x + \beta \left((\mu_2^T x)^2 - (\mu_3^T x)^2\right)\right)$$

$\theta = \{\kappa, \beta, \mu_1, \mu_2, \mu_3\}$ with κ concentration parameter, β ,
 $0 \leq \beta < \kappa$, ellipticity of the contours of equal probability, μ_1 mean
 direction, μ_2 major axis and μ_3 minor axis.

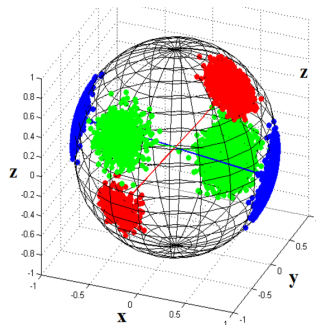
Examples with $p = 3$

Simulation of three different directional distributions:

von Mises Fisher distributions



Watson distributions



Application to depth images: surface normals are unit vectors in \mathbb{R}^3 .

Directional distributions and EF

vMF distribution with $p = 3$, $x \in S^2 \subset \mathbb{R}^3$

- $t(x) = x$
- $\theta = \kappa\mu$, the natural parameters with $\kappa = \|\theta\|$ and $\mu = \frac{\theta}{\|\theta\|}$
- $F(\theta) = \log\left(\frac{\sinh(\kappa)}{\kappa}\right) = \log\left(\frac{\sinh(\|\theta\|)}{\|\theta\|}\right)$
- $g(x) = 0$
- $\eta = (\tanh(\kappa)^{-1} - \kappa^{-1})\mu$

Directional distributions and EF

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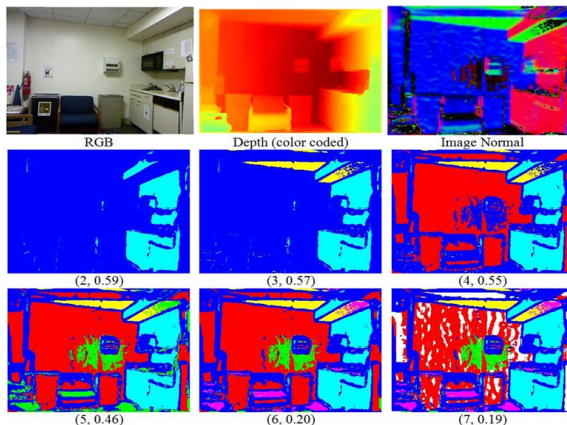
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- $g(x) = 0$
- $\eta = (\tanh(\kappa)^{-1} - \kappa^{-1})\mu$

Watson distribution with $x = [x_1, x_2, \dots, x_p]^T \in S^{p-1} \subset \mathbb{R}^p$

- $t(x) = [x_1^2, \dots, x_p^2, \sqrt{2}x_1x_2, \dots, \sqrt{2}x_{p-1}x_p]^T$
- $\theta = \kappa [\mu_1^2, \dots, \mu_p^2, \sqrt{2}\mu_1\mu_2, \dots, \sqrt{2}\mu_{p-1}\mu_p]^T$ with $\kappa = \|\theta\|$
- $F(\theta) = \log\left(M\left(\frac{1}{2}, \frac{p}{2}, \kappa\right)\right)$
- $g(x) = 0$
- $\eta = \frac{1}{p} \frac{M\left(\frac{3}{2}, \frac{p+2}{2}, \kappa\right)}{M\left(\frac{1}{2}, \frac{p}{2}, \kappa\right)} \frac{\theta}{\kappa}$

Results with an exemplar of depth image (vMF)

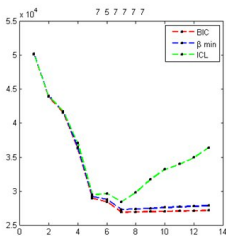
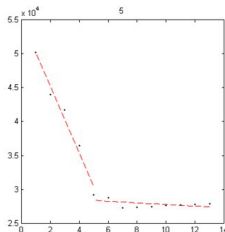
Segmentation of a depth image generated by clustering image normals.



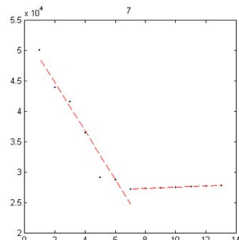
How to choose the number of components automatically ?

Mixture model and normals of surfaces

Curves of IC - Mixture of vMF with 7 classes

Curve: BIC, β_{min} , ICL

PLR, un-weighted

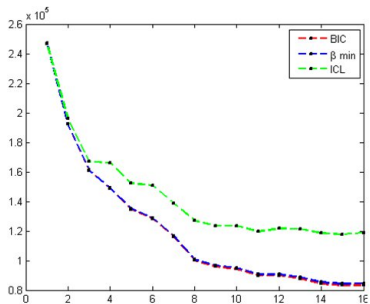


W-PLR [1,30]

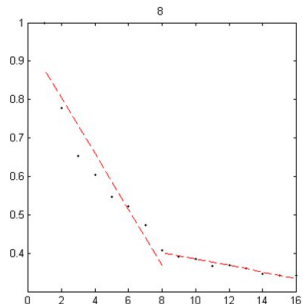
PLR and Weighted-PLR (proposed development)

$$\hat{k} = \underset{k}{\operatorname{argmin}} (\omega_l RMSE_{left} + \omega_r RMSE_{right})$$

Curves of IC - depth image



Curve: BIC, β_{min} , ICL



W-PLR [1,30]

- Proposed W-PLR provides
 - MoVMF case:** equivalent results as BIC, $\phi_{\beta_{min}}$ or ICL for simulated data
 - Watson distribution case:** ICL is equivalent or better to W-PLR ($\omega_l = \omega_r = 1$)
 - Better component selection for real image data

Proposed methods

MBC-vMFMM and MBC-WMM

Validated by a study on synthetic data

(Model Based Clustering for von Mises-Fisher Mixture Model)

(Model Based Clustering for Watson Mixture Model)

		MBC-vMFMM	MBC-WMM
1st step with $K = K_{\max}$	Initialization	kmeans++	DM
	EM type procedure	BSC	BSC
2nd step HAC	Distance	right-sided BD	right-sided BD
	Linkage	Average	Average
	\hat{K}	IC & W-PLR	IC & W-PLR

DM: Diametrical clustering.

Dhillon et. Al, (2003), Diametrical Clustering for identifying anti-correlated gene clusters, Bioinformatics, vol 19, pp. 1612-1619.

Estimation of the number of components MBC-vMFMM

Comparison between MBC-vMFMM and a method containing state-of-the-art methods called MBC-MoVMF.

	Acc (%)		Comp. Time (sec)	
	MBC-MoVMF	MBC-vMFMM	MBC-MoVMF	MBC-vMFMM
3,ws	87.913	99.992	8.9187	2.953
5,ws	84.487	99.995	8.1757	2.9494
7,ws	76.991	99.994	7.8314	2.8663
3,nws	93.788	99.039	10.74	2.9201
5,nws	90.012	97.156	8.6715	2.9004
7,nws	80.709	92.966	7.9239	2.8822

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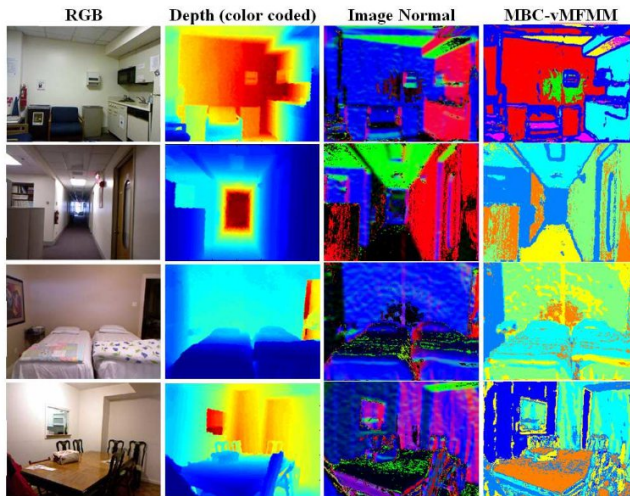
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100 % of correct number of components selection with MBC-vMFMM using :

- $\phi_{\beta_{\min}} IC$
- W-PLR on BIC curve with $\omega_l = 1$ and $\omega_r = 300$

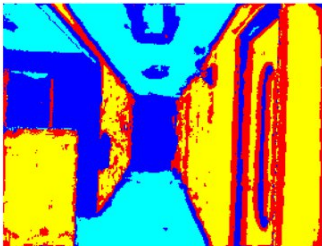
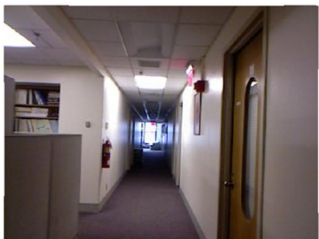
Results on depth images (NYU database)

With von Mises-Fisher MM (MBC-vMFMM using W-PLR)



Results on depth images (NYU database)

With Watson MM (MBC-WMM using W-PLR)



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A mixture model for RGB-D data

$x = \{(x_{s,D}, x_{s,C})\}_{s \in \Lambda}$, samples of **i.i.d.** (independently and identically distributed) random vectors with dimension $p = p_D + p_C$.

$$f(x_s) = \sum_{k \in K} P(\theta_k) f(x_{s,D}, x_{s,C} | \theta_k)$$

$x_{s,D}$ can contain spatial positions, depths, normals, ...

$x_{s,C}$ can be issued from different color spaces.

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Different hypothesis

- $x_{s,D}$ and $x_{s,C}$ are not independant
- $x_{s,D}$ and $x_{s,C}$ are independant
- What distributions can be used ?

A first proposal

- ✦ $x_{s,N}$ is the normal in s : vMF or W distributions
- ✦ $x_{s,P}$ is the position in s : Multidimensional Gaussian
- ✦ $x_{s,C}$ is the color in s using Lab: Multidimensional Gaussian
- ✦ Independance assumption $\theta_k = \{\theta_{N,k}, \theta_{P,k}, \theta_{C,k}\}$

$$f(x_s) = \sum_{k \in K} P(\theta_k) f_N(x_{s,N} | \theta_{N,k}) f_P(x_{s,P} | \theta_{P,k}) f_C(x_{s,C} | \theta_{C,k})$$

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Direct extension of previous method

- The combined BD is the sum of the three BD
- Centroids are computed independantly

First results on NYU Database

First results on NYU Database

	PRI	Vol	GCE	BDE
N-WMM	0,718	3,523	0,511	12,221
N-VMFMM	0,726	3,770	0,540	12,555
C-MGMM	0,634	3,048	0,352	17,218
P-MGMM	0,702	2,619	0,294	25,471
N+C+P	0,694	2,602	0,296	23,516

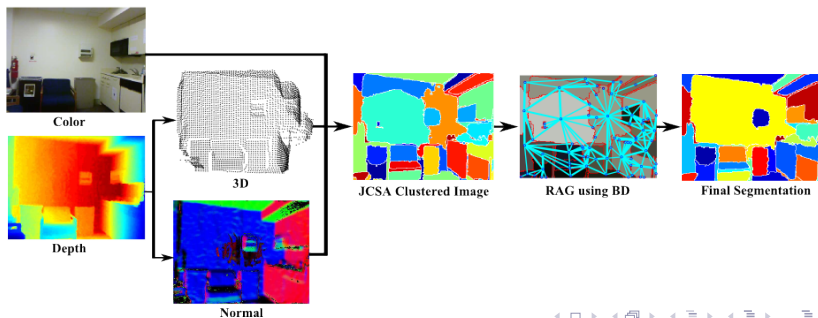
Lower results than the most recent methods.

- ✦ **PRI**: Probabilistic Rand Index. Measuring the likelihood of a pair of pixels being grouped consistently in two segmentations.
- ✦ **Vol**: Variation of Information. Computing the amount of information of one result not contained in the other.
- ✦ **GCE**: Global Consistency Error. Measuring the extent to which one segmentation is a refinement of the other.
- ✦ **BDE**: Boundary Displacement Error. Computing the average displacement between the boundaries of two segmentations.

Results based on aggregation of planar regions

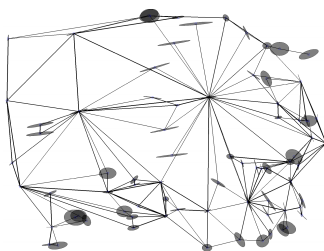
A RAG based method

- ✦ Another exploration of the hierarchy of models based on the following considerations:
 - The shadow zones are noisy.
 - Some planar regions deserve to be merged.
 - A need to take into account the boundaries of the RGB-D image in order to limit the merging processus.
- ✦ Block diagram of the proposed method :



Results based on aggregation of planar regions

A RAG based method - Example of obtained Graph



$R = \{r_i\}_{i=1,\dots,M}$, and undirected graph $G = (V, E)$

- ✚ v_i : node i corresponds to region i and is associated with mean direction, μ , and concentration κ of Watson distribution.
- ✚ e_{ij} : edge linking nodes i and j associated with two weights based on statistical dissimilarity, based on Watson distribution, and boundary strength ($I_G^{rgb}(\cdot)$ normalized gradient value):

$$w_d(v_i, v_j) = \min(D_W(r_i, r_j), D_W(r_j, r_i))$$

$$w_b(v_i, v_j) = \frac{1}{|r_i \cap r_j|} \sum_{b \in r_i \cap r_j} I_G^{rgb}(b)$$

Results based on aggregation of planar regions

A RAG based method - Proposed algorithm

$$cand(v_i) = \begin{cases} true, & \text{if } \kappa(r_i) > \kappa_{planar}, \\ false, & \text{otherwise.} \end{cases} \quad P_{ij} = \begin{cases} true, & \text{if (a) } cand(v_j) = true; \text{ and} \\ & (b) w_b(v_i, v_j) < th_{boundary}; \text{ and} \\ & (c) w_d(v_i, v_j) < th_{dist}; \text{ and} \\ & (d) planar outlier ratio > th_{ratio} \\ false, & \text{otherwise.} \end{cases}$$

Input: $R = \{r_i\}_{i=1,\dots,M}$, $G = (V, E)$, $th_{boundary}$, th_{dist} and th_{ratio}

Output: Final segmentation after region merging.

Compute $cand(v_i)$ for $\{v_i\}_{i=1,\dots,M}$ using Eq. (18);

Set $i = 1$;

foreach i **do**

if $cand(v_i)$ **is true then**

while *no adjacent of v_i is left to check* **do**

 Sort e_{ij} in ascending order according to $w_b(v_i, v_j)$;

 Evaluate each v_j with the *merging predicate* P_{ij} (Eq. (19)) ;

if P_{ij} **is true then**

 Merge two nodes v_i and v_j and update the RAG;

 Start over again from sorting the adjacents.

else

 Check the next node

end

end

end

end

Results based on aggregation of planar regions

Results on NYU Database

	PRI	VOI	BDE	RC
OWT-UCM	0.89	2.60	8.87	0.56
GBS	0.77	2.37	16.04	0.45
JCSA-HRM	0.90	2.32	10.01	0.57

Methods

- ✦ **OWT-UCM**: Oriented Watershed Transform - Ultrametric Contour Map (PAMI 2011, CVPR 2012)
- ✦ **GBS**: Graph-Based Segmentation for Colored 3D Laser Point Clouds (2010).
- ✦ **JCSA-HRM**: Joint Color-Spatial-Axial clustering with Hierarchical Region Merging (proposed method).

Evaluation criteria

- ✦ For PRI, Vol and BDE, see previous slide.
- ✦ **RC**: Region (or segmentation) Covering evaluates the region overlaps between two segmentations (evaluation of the pixel-wise classification task in recognition).

Outline

- 1 Clustering with mixtures and BD
 - Exponential families (EF) and Bregman Divergence (BD)
 - Mixture model
 - Estimation of number of components
- 2 MBC with directional distributions
 - Directional distributions in \mathbb{R}^p
 - Mixture model and normals of surfaces
 - Results on depth images (NYU database)
- 3 MBC and RGB-D data
 - Mixture Model and RGB-D data
 - First results on NYU Database
 - Results based on aggregation of planar regions
- 4 Conclusion

Conclusion and perspectives

Conclusion

- An “unsupervised” clustering procedure based on Bregman divergence
 - ✚ for Normals (MoVMF and MoW)
 - ✚ for Normals+Positions+Colors (Independence assumption)
 - ✚ estimation of the number of component with IC and W-PLR based on BIC curve
 - ✚ accurate results on NYU Database using a RAG based algorithm

Conclusion and perspectives

Conclusion

- An “unsupervised” clustering procedure based on Bregman divergence
 - ✕ for Normals (MoVMF and MoW)
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 - ✕ accurate results on NYU Database using a RAG based algorithm

Perspectives

- Extension to Kent mixtures
- MRF (or CRF, ...) based spatial regularization
- Still improving the management of the hierarchy of models
- Exploring the different possible combinations of N, P, C, ...
- Semantic analysis

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Merci pour votre attention ! Des questions ?

① Clustering with mixtures and BD

Exponential families (EF) and Bregman Divergence (BD)

Mixture model

Estimation of number of components

② MBC with directional distributions

Directional distributions in \mathbb{R}^P

Mixture model and normals of surfaces

Results on depth images (NYU database)

③ MBC and RGB-D data

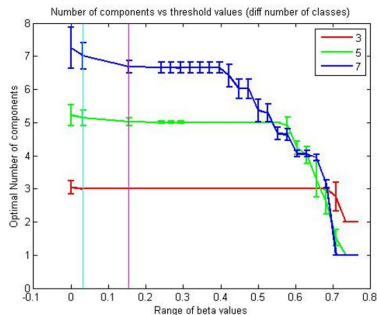
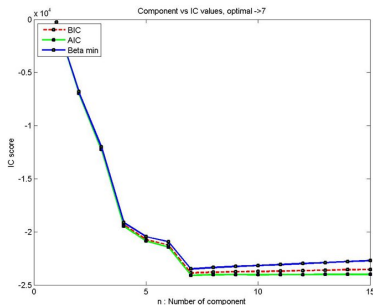
Mixture Model and RGB-D data

First results on NYU Database

Results based on aggregation of planar regions

④ Conclusion

Curves of ϕ_β IC



Data containing 7 classes.

Data containing 3, 5 or 7 classes.

- $K_{\max} = 15$
- IC can be computed using Bregman divergence and a hard clustering of data using the estimated models with decreasing number of components.

Clustering accuracy - K is known - vMF-MM

$N = 10000$

Methods:

- kmeans++ (KMPP)
- Gaussian Mixture Model (GMM)
- Spherical kmeans (SPKM)
- vMF-MM [Banerjee & al. 2005]
- H-vMF-MM (MBC-vMFMM without number of components estimation)

	KMPP	GMM	SPKM	vMF-MM	H-vMF-MM
3 cl, ws	93.41	91.71	98.23	98.92	99.99
5 cl, ws	90.76	83.93	97.07	97.6	99.99
3 cl, nws	89.58	90.5	92.25	93.07	99.05
5 cl, nws	85.76	86.06	93.64	94.96	97.16

Clustering accuracy - K is known - Watson MM

$N = 10000$

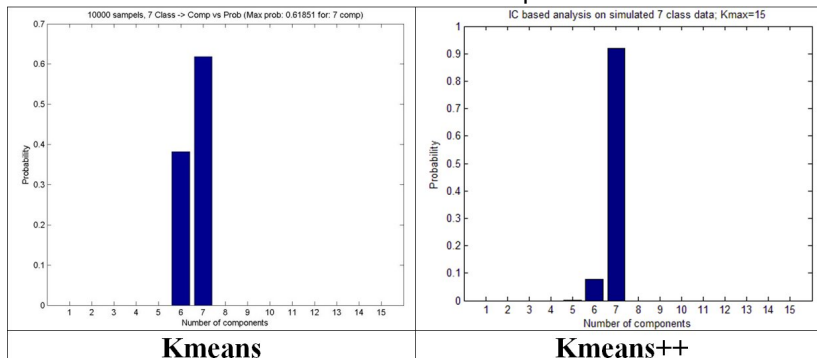
Methods:

- Diametrical clustering (DM) [Dhillon & al. 2003]
- Mixture of Watson Distributions (MWD) [Bijral & al. 2007]
- HWMM (MBC-WMM without number of components estimation)

	DM	MWD	HWMM
2 cl, ws	99.9998	99.9998	100
3 cl, ws	98.9932	98.0559	99.9992
4 cl, ws	90.9388	98.1295	99.9909
2 cl, nws	97.1702	97.2206	97.1998
3 cl, nws	96.7246	96.0239	92.207
4 cl, nws	97.9254	96.7252	98.0496

Importance of the initialisation

Estimation of the number of components with IC



Synthetic data containing 7 classes

Estimation of the number of components (MBC-WMM)

	Cl. Acc	Time	BIC	$\phi_{\beta_{\min}}$	ICL
2, ws	100	12.84	66	66	66
3, ws	99.99	12.30	100	100	100
4, ws	99.99	12.58	90	90	90
5, ws	99.96	12.84	98	98	98
7, ws	99.62	13.37	98	98	98
2, nws	97.23	12.47	98	100	98
3, nws	96.43	12.64	100	100	100
4, nws	98.06	13.11	100	100	100
5, nws	97.22	13.30	100	100	100
7, nws	91.97	14.97	100	100	100